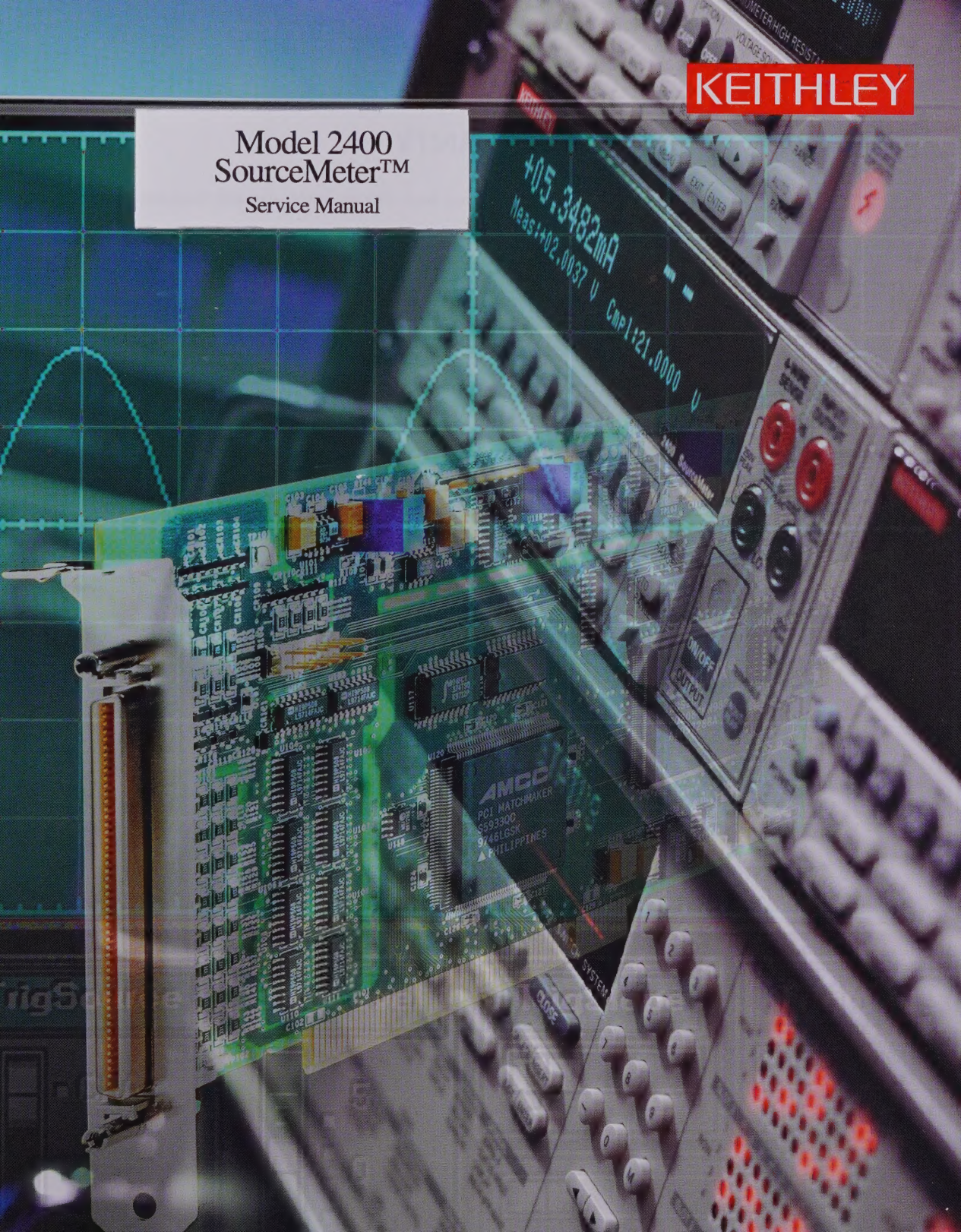
KEITHLEY

Model 2400 SourceMeter™

Service Manual



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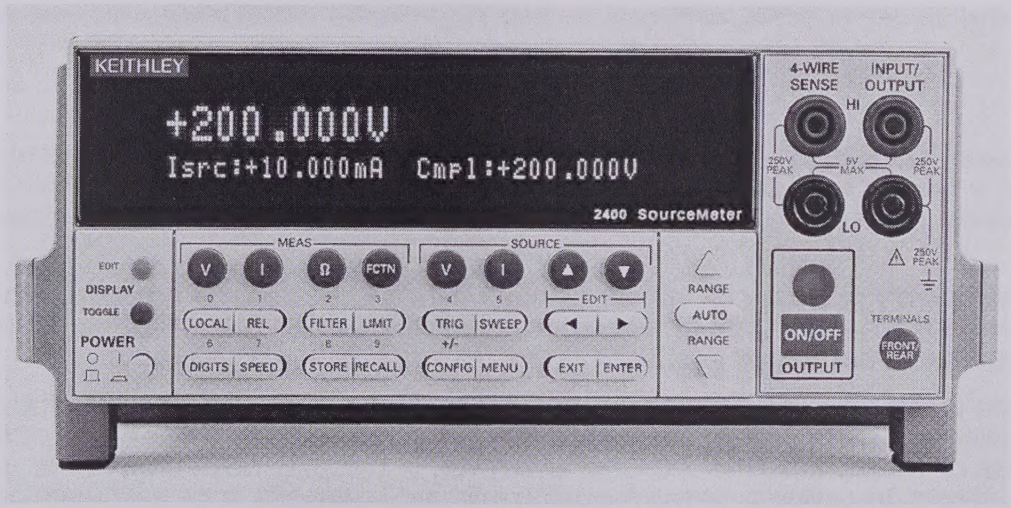

Contains Calibrating and Servicing Information

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WARRANTY

Keithley Instruments, Inc. warrants this product to be free from defects in material and workmanship for a period of 1 year from date of shipment.

Keithley Instruments, Inc. warrants the following items for 90 days from the date of shipment: probes, cables, rechargeable batteries, diskettes, and documentation.

During the warranty period, we will, at our option, either repair or replace any product that proves to be defective.

To exercise this warranty, write or call your local Keithley representative, or contact Keithley headquarters in Cleveland, Ohio. You will be given prompt assistance and return instructions. Send the product, transportation prepaid, to the indicated service facility. Repairs will be made and the product returned, transportation prepaid. Repaired or replaced products are warranted for the balance of the original warranty period, or at least 90 days.

LIMITATION OF WARRANTY

This warranty does not apply to defects resulting from product modification without Keithley's express written consent, or misuse of any product or part. This warranty also does not apply to fuses, software, non-rechargeable batteries, damage from battery leakage, or problems arising from normal wear or failure to follow instructions.

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Model 2400 SourceMeter™ Service Manual

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Manual Print History

The print history shown below lists the printing dates of all Revisions and Addenda created for this manual. The Revision Level letter increases alphabetically as the manual undergoes subsequent updates. Addenda, which are released between Revisions, contain important change information that the user should incorporate immediately into the manual. Addenda are numbered sequentially. When a new Revision is created, all Addenda associated with the previous Revision of the manual are incorporated into the new Revision of the manual. Each new Revision includes a revised copy of this print history page.

Revision A (Document Number 2400-902-01) ..... January 1996
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All Keithley product names are trademarks or registered trademarks of Keithley Instruments, Inc.
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Safety Precautions

The following safety precautions should be observed before using this product and any associated instrumentation. Although some instruments and accessories would normally be used with non-hazardous voltages, there are situations where hazardous conditions may be present.

This product is intended for use by qualified personnel who recognize shock hazards and are familiar with the safety precautions required to avoid possible injury. Read the operating information carefully before using the product.

The types of product users are:

Responsible body is the individual or group responsible for the use and maintenance of equipment, for ensuring that the equipment is operated within its specifications and operating limits, and for ensuring that operators are adequately trained.

Operators use the product for its intended function. They must be trained in electrical safety procedures and proper use of the instrument. They must be protected from electric shock and contact with hazardous live circuits.

Maintenance personnel perform routine procedures on the product to keep it operating, for example, setting the line voltage or replacing consumable materials. Maintenance procedures are described in the manual. The procedures explicitly state if the operator may perform them. Otherwise, they should be performed only by service personnel.

Service personnel are trained to work on live circuits, and perform safe installations and repairs of products. Only properly trained service personnel may perform installation and service procedures.

Exercise extreme caution when a shock hazard is present. Lethal voltage may be present on cable connector jacks or test fixtures. The American National Standards Institute (ANSI) states that a shock hazard exists when voltage levels greater than 30V RMS, 42.4V peak, or 60VDC are present. **A good safety practice is to expect that hazardous voltage is present in any unknown circuit before measuring.**

Users of this product must be protected from electric shock at all times. The responsible body must ensure that users are prevented access and/or insulated from every connection point. In some cases, connections must be exposed to potential human contact. Product users in these circumstances must be trained to protect themselves from the risk of electric shock. If the circuit is capable of operating at or above 1000 volts, **no conductive part of the circuit may be exposed.**

As described in the International Electrotechnical Commission (IEC) Standard IEC 664, digital multimeter measuring circuits (e.g., Keithley Models 175A, 199, 2000, 2001, 2002, and 2010) are Installation Category II. All other instruments' signal terminals are Installation Category I and must not be connected to mains.

Do not connect switching cards directly to unlimited power circuits. They are intended to be used with impedance limited sources. NEVER connect switching cards directly to AC mains. When connecting sources to switching cards, install protective devices to limit fault current and voltage to the card.

Before operating an instrument, make sure the line cord is connected to a properly grounded power receptacle. Inspect the connecting cables, test leads, and jumpers for possible wear, cracks, or breaks before each use.

For maximum safety, do not touch the product, test cables, or any other instruments while power is applied to the circuit under test. ALWAYS remove power from the entire test system and discharge any capacitors before: connecting or disconnecting cables or jumpers, installing or removing switching cards, or making internal changes, such as installing or removing jumpers.

Do not touch any object that could provide a current path to the common side of the circuit under test or power line (earth) ground. Always make measurements with dry hands while standing on a dry, insulated surface capable of withstanding the voltage being measured.

The instrument and accessories must be used in accordance with its specifications and operating instructions or the safety of the equipment may be impaired.

Do not exceed the maximum signal levels of the instruments and accessories, as defined in the specifications and operating information, and as shown on the instrument or test fixture panels, or switching card.

When fuses are used in a product, replace with same type and rating for continued protection against fire hazard.

Chassis connections must only be used as shield connections for measuring circuits, NOT as safety earth ground connections.

If you are using a test fixture, keep the lid closed while power is applied to the device under test. Safe operation requires the use of a lid interlock.

If a screw is present, connect it to safety earth ground using the wire recommended in the user documentation.

The symbol on an instrument indicates that the user should refer to the operating instructions located in the manual.

The symbol on an instrument shows that it can source or measure 1000 volts or more, including the combined effect of normal and common mode voltages. Use standard safety precautions to avoid personal contact with these voltages.

The **WARNING** heading in a manual explains dangers that might result in personal injury or death. Always read the associated information very carefully before performing the indicated procedure.

The **CAUTION** heading in a manual explains hazards that could damage the instrument. Such damage may invalidate the warranty.

Instrumentation and accessories shall not be connected to humans.

Before performing any maintenance, disconnect the line cord and all test cables.

To maintain protection from electric shock and fire, replacement components in mains circuits, including the power transformer, test leads, and input jacks, must be purchased from Keithley Instruments. Standard fuses, with applicable national safety approvals, may be used if the rating and type are the same. Other components that are not safety related may be purchased from other suppliers as long as they are equivalent to the original component. (Note that selected parts should be purchased only through Keithley Instruments to maintain accuracy and functionality of the product.) If you are unsure about the applicability of a replacement component, call a Keithley Instruments office for information.

To clean an instrument, use a damp cloth or mild, water based cleaner. Clean the exterior of the instrument only. Do not apply cleaner directly to the instrument or allow liquids to enter or spill on the instrument. Products that consist of a circuit board with no case or chassis (e.g., data acquisition board for installation into a computer) should never require cleaning if handled according to instructions. If the board becomes contaminated and operation is affected, the board should be returned to the factory for proper cleaning/servicing.

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1
Performance Verification

Introduction

Use the procedures in this section to verify that Model 2400 accuracy is within the limits stated in the instrument's one-year accuracy specifications. You can perform these verification procedures:

- When you first receive the instrument to make sure that it was not damaged during shipment.
- To verify that the unit meets factory specifications.
- To determine if calibration is required.
- Following calibration to make sure it was performed properly.

WARNING ***The information in this section is intended for qualified service personnel only. Do not attempt these procedures unless you are qualified to do so. Some of these procedures may expose you to hazardous voltages, which could cause personal injury or death if contacted. Use standard safety precautions when working with hazardous voltages.***

NOTE *If the instrument is still under warranty and its performance is outside specified limits, contact your Keithley representative or the factory to determine the correct course of action.*

Verification test requirements

Be sure that you perform the verification tests:

- Under the proper environmental conditions.
- After the specified warm-up period.
- Using the correct line voltage.
- Using the proper test equipment.
- Using the specified output signal and reading limits.

Environmental conditions

Conduct your performance verification procedures in a test environment with:

- An ambient temperature of 18-28°C (65-82°F).
- A relative humidity of less than 70% unless otherwise noted.

Warm-up period

Allow the Model 2400 to warm up for at least one hour before conducting the verification procedures. If the instrument has been subjected to temperature extremes (those outside the ranges stated above), allow additional time for the instrument's internal temperature to stabilize. Typically, allow one extra hour to stabilize a unit that is 10°C (18°F) outside the specified temperature range.

Also, allow the test equipment to warm up for the minimum time specified by the manufacturer.

Line power

The Model 2400 requires a line voltage of 88 to 264V and a line frequency of 50 or 60Hz. Verification tests should be performed within this range.

Recommended test equipment

Table 1-1 summarizes recommended verification equipment. You can use alternate equipment as long as that equipment has specifications at least as good as those listed in Table 1-1. Keep in mind, however, that test equipment uncertainty will add to the uncertainty of each measurement. Generally, test equipment uncertainty should be at least four times better than corresponding Model 2400 specifications. Table 1-1 lists the uncertainties of the recommended test equipment.

Table 1-1
Recommended verification equipment

Description	Manufacturer/ Model	Accuracy*		
Digital multimeter	Hewlett Packard HP3458A	DC voltage	200mV:	±15ppm
			2V:	±6ppm
			20V:	±9ppm
			200V:	±7ppm
		DC current	1µA:	±55ppm
			10µA:	±25ppm
			100µA:	±23ppm
			1mA:	±20ppm
			10mA:	±20ppm
			100mA:	±35ppm
			1A:	±110ppm
Resistance calibrator	Fluke 5450A	Resistance**	19Ω:	±23ppm
			190Ω:	±10.5ppm
			1.9kΩ:	±8ppm
			19kΩ:	±7.5ppm
			190kΩ:	±8.5ppm
			1.9MΩ:	±11.5ppm
			19MΩ:	±30ppm
			100MΩ:	±120ppm

* 90-day specifications show accuracy at specified measurement point.
** Nominal resistance values shown.

Verification limits

The verification limits stated in this section have been calculated using only the Model 2400 one-year accuracy specifications, and they do not include test equipment uncertainty. If a particular measurement falls outside the allowable range, recalculate new limits based both on Model 2400 specifications and corresponding test equipment specifications.

Example limits calculation

As an example of how verification limits are calculated, assume you are testing the 20V DC output range using a 20V output value. Using the Model 2400 one-year accuracy specification for 20V DC output of ±(0.02% of output + 2.4mV offset), the calculated output limits are:

Output limits = 20V ± [(20V × 0.02%) + 2.4mV]

Output limits = 20V ± (0.004 + 0.0024)

Output limits = 20V ± 0.0064V

Output limits = 19.9936V to 20.0064V

Resistance limits calculation

When verifying the ohms function, you may find it necessary to recalculate resistance limits based on the actual calibrator resistance values. You can calculate resistance reading limits in the same manner described above; be sure to use the actual calibrator resistance values and the Model 2400 normal accuracy specifications for your calculations.

As an example, assume that you are testing the 20kΩ range, and the actual value of the nominal 19kΩ calibrator resistor is 19.025kΩ. Using the Model 2400 one-year normal accuracy specifications of ±(0.063% of reading + 3Ω), the recalculated reading limits are:

Reading limits = 19.025kΩ ± [(19.025kΩ × 0.063%) + 3Ω]

Reading limits = 19.025kΩ ± 15Ω

Reading limits = 19.0100kΩ to 19.0400kΩ

Restoring factory defaults

Before performing the verification procedures, restore the instrument to its factory front panel (bench) defaults as follows:

1. Press MENU key. The instrument will display the following prompt:

   MAIN MENU
   SAVESETUP COMMUNICATION CAL▶

2. Select SAVESETUP, and then press ENTER. The unit then displays:

   SETUP MENU
   SAVE RESTORE POWERON RESET

3. Select RESET, and then press ENTER. The unit displays:

   RESET ORIGINAL DFLTS
   BENCH GPIB

4. Select BENCH, then press ENTER. The unit then displays:

   RESETTING INSTRUMENT
   ENTER to confirm; EXIT to abort

5. Press ENTER to restore bench defaults, and note the unit displays the following:

   RESET COMPLETE
   BENCH defaults are now restored▶
   ◀ Press ENTER to continue

6. Press ENTER and then EXIT to return to normal display.

Performing the verification test procedures

Test summary

- DC voltage output accuracy
- DC voltage measurement accuracy
- DC current output accuracy
- DC current measurement accuracy
- Resistance measurement accuracy

If the Model 2400 is not within specifications and not under warranty, see the calibration procedures in Section 2 for information on calibrating the unit.

Test considerations

When performing the verification procedures:

- Be sure to restore factory front panel defaults as outlined above.
- Make sure that the test equipment is properly warmed up and connected to the Model 2400 INPUT/OUTPUT jacks. Also be sure that the front panel jacks are selected with the TERMINALS key.
- Make sure the Model 2400 is set to the correct source range.
- Be sure that the Model 2400 output is turned on before making measurements.
- Be sure the test equipment is set up for the proper function and range.
- Allow the Model 2400 output signal to settle before making a measurement.
- Do not connect test equipment to the Model 2400 through a scanner, multiplexer, or other switching equipment.

WARNING ***The maximum common-mode voltage (voltage between LO and chassis ground) is 250V peak. Exceeding this value may cause a breakdown in insulation, creating a shock hazard.***

CAUTION ***The maximum voltage between INPUT/OUTPUT HI and LO or 4-WIRE SENSE HI and LO is 250V peak. The maximum voltage between INPUT/OUTPUT HI and 4-WIRE SENSE HI or between INPUT/OUTPUT LO and 4-WIRE SENSE LO is 5V. Exceeding these voltage values may result in instrument damage.***

Setting the source range and output value

Before testing each verification point, you must properly set the source range and output value as outlined below.

1. Press either the SOURCE V or SOURCE I key to select the appropriate source function.
2. Press the EDIT key as required to select the source display field. Note that the cursor will flash in the source field while its value is being edited.
3. With the cursor in the source display field flashing, set the source range to the lowest possible range for the value to be sourced using the up or down RANGE key. For example, you should use the 20V source range to output a 19V or 20V source value. With a 20V source value and the 20V range selected, the source field display will appear as follows:

   Vsrc:+20.0000 V

4. With the source field cursor flashing, set the source output to the required value using either:

   - The SOURCE adjustment and left and right arrow keys.
   - The numeric keys.

5. Note that the source output value will be updated immediately; you need not press ENTER when setting the source value.

Setting the measurement range

When simultaneously sourcing and measuring either voltage or current, the measure range is coupled to the source range, and you cannot independently control the measure range. Thus, it is not necessary for you to set the range when testing voltage or current measurement accuracy.

Output voltage accuracy

Follow the steps below to verify that Model 2400 output voltage accuracy is within specified limits. This test involves setting the output voltage to each full-range value and measuring the voltages with a precision digital multimeter.

1. With the power off, connect the digital multimeter to the Model 2400 INPUT/OUTPUT jacks as shown in Figure 1-1.
2. Select the multimeter DC volts measuring function.
3. Press the Model 2400 SOURCE V key to source voltage, and make sure the source output is turned on.
4. Verify output voltage accuracy for each of the voltages listed in Table 1-2. For each test point:
   - Select the correct source range.
   - Set the Model 2400 output voltage to the indicated value.
   - Verify that the multimeter reading is within the limits given in the table.
5. Repeat the procedure for negative output voltages with the same magnitudes as those listed in Table 1-2.
6. Repeat the entire procedure using the rear panel INPUT/OUTPUT jacks. Be sure to select the rear panel jacks with the front panel TERMINALS key.

Table 1-2
Output voltage accuracy limits

Model 2400 source range	Model 2400 output voltage setting	Output voltage limits (1 year, 18°C–28°C)
200mV	200.000mV	199.360 to 200.640mV
2V	2.00000V	1.99900 to 2.00100V
20V	20.0000V	19.9936 to 20.0064V
200V	200.000V	199.936 to 200.064V

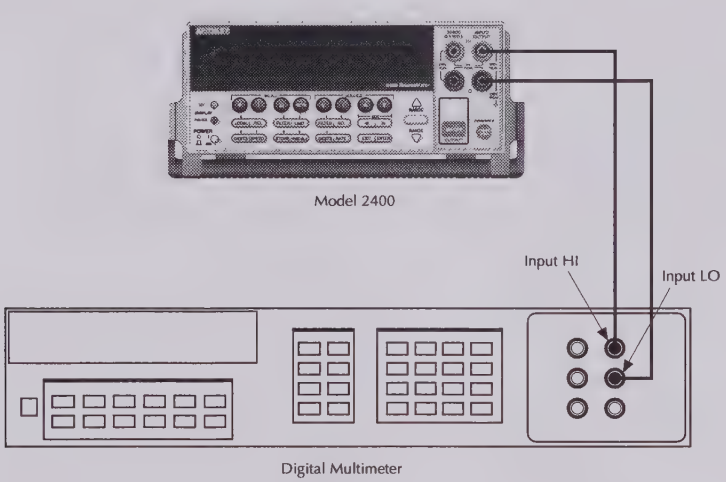


Figure 1-1
Voltage verification front panel connections

Voltage measurement accuracy

Follow the steps below to verify that Model 2400 voltage measurement accuracy is within specified limits. The test involves setting the source voltage to 95% of full-range values, as measured by a precision digital multimeter, and then verifying that the Model 2400 voltage readings are within required limits.

1. With the power off, connect the digital multimeter to the Model 2400 INPUT/OUTPUT jacks as shown in Figure 1-1.
2. Select the multimeter DC volts function.
3. Set the Model 2400 to both source and measure voltage by pressing the SOURCE V and MEAS V keys, and make sure the source output is turned on.
4. Verify output voltage accuracy for each of the voltages listed in Table 1-3. For each test point:
   - Select the correct source range.
   - Set the Model 2400 output voltage to the indicated value as measured by the digital multimeter.
   - Verify that the Model 2400 voltage reading is within the limits given in the table.

NOTE *It may not be possible to set the voltage source to the specified value. Use the closest possible setting, and modify reading limits accordingly.*

5. Repeat the procedure for negative source voltages with the same magnitudes as those listed in Table 1-3.
6. Repeat the entire procedure using the rear panel INPUT/OUTPUT jacks. Be sure to select the rear panel jacks with the front panel TERMINALS key.

Table 1-3

Voltage measurement accuracy limits

Model 2400 source and measure range*	Source voltage**	Model 2400 voltage reading limits (1 year, 18°C–28°C)
200mV	190.000mV	189.677 to 190.323mV
2V	1.90000V	1.89947 to 1.90053V
20V	19.0000V	18.9962 to 19.0038V
200V	190.000V	189.962 to 190.038V

*Measure range coupled to source range when simultaneously sourcing and measuring voltage.

** As measured by precision digital multimeter. Use closest possible value, and modify reading limits accordingly if necessary.

Output current accuracy

Follow the steps below to verify that Model 2400 output current accuracy is within specified limits. The test involves setting the output current to each full-range value and measuring the currents with a precision digital multimeter.

1. With the power off, connect the digital multimeter to the Model 2400 INPUT/OUTPUT jacks as shown in Figure 1-2.
2. Select the multimeter DC current measuring function.
3. Press the Model 2400 SOURCE I key to source current, and make sure the source output is turned on.
4. Verify output current accuracy for each of the currents listed in Table 1-4. For each test point:
   - Select the correct source range.
   - Set the Model 2400 output current to the correct value.
   - Verify that the multimeter reading is within the limits given in the table.
5. Repeat the procedure for negative output currents with the same magnitudes as those listed in Table 1-4.
6. Repeat the entire procedure using the rear panel INPUT/OUTPUT jacks. Be sure to select the rear panel jacks with the front panel TERMINALS key.

Table 1-4

Output current accuracy limits

Model 2400 source range	Model 2400 output current setting	Output current limits (1 year, 18°C–28°C)
1µA	1.00000µA	0.99905 to 1.00095µA
10µA	10.0000µA	9.9947 to 10.0053µA
100µA	100.000µA	99.949 to 100.051µA
1mA	1.00000mA	0.99946 to 1.00054mA
10mA	10.0000mA	9.9935 to 10.0065mA
100mA	100.000mA	99.914 to 100.086mA
1A	1.00000A	0.99640 to 1.00360A

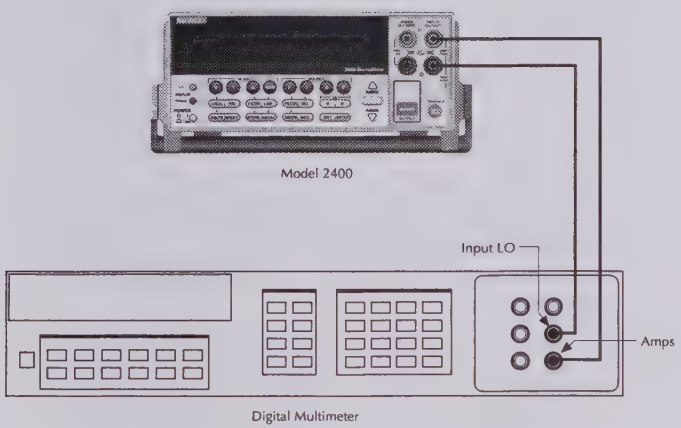


Figure 1-2
Current verification connections

Current measurement accuracy

Follow the steps below to verify that Model 2400 current measurement accuracy is within specified limits. The procedure involves applying accurate currents from the Model 2400 current source and then verifying that Model 2400 current measurements are within required limits.

1. With the power off, connect the digital multimeter to the Model 2400 INPUT/OUTPUT jacks as shown in Figure 1-2.
2. Select the multimeter DC current function.
3. Set the Model 2400 to both source and measure current by pressing the SOURCE I and MEAS I keys, and make sure the source output is turned on.
4. Verify measure current accuracy for each of the currents listed in Table 1-5. For each measurement:
   - Select the correct source range.
   - Set the Model 2400 source output to the correct value as measured by the digital multimeter.
   - Verify that the Model 2400 current reading is within the limits given in the table.

NOTE *It may not be possible to set the current source to the specified value. Use the closest possible setting, and modify reading limits accordingly.*

5. Repeat the procedure for negative calibrator currents with the same magnitudes as those listed in Table 1-5.
6. Repeat the entire procedure using the rear panel INPUT/OUTPUT jacks. Be sure to select the rear panel jacks with the front panel TERMINALS key.

Table 1-5
Current measurement accuracy limits

Model 2400 source and measure range*	Source current**	Model 2400 current reading limits (1 year, 18°C–28°C)
1µA	0.95000µA	0.94942 to 0.95058µA
10µA	9.5000µA	9.4967 to 9.5033µA
100µA	95.000µA	94.970 to 95.030µA
1mA	0.95000mA	0.94968 to 0.95032mA
10mA	9.5000mA	9.4961 to 9.5039mA
100mA	95.000mA	94.942 to 95.058mA
1A	0.95000A	0.94734 to 0.95266A

* Measure range coupled to source range when simultaneously sourcing and measuring current.

** As measured by precision digital multimeter. Use closest possible value, and modify reading limits accordingly if necessary.

Resistance measurement accuracy

Follow the steps below to verify that Model 2400 resistance measurement accuracy is within specified limits. This procedure involves applying accurate resistances from a resistance calibrator and then verifying that Model 2400 resistance measurements are within required limits.

1. With the power off, connect the resistance calibrator to the Model 2400 INPUT/OUTPUT and 4-WIRE SENSE jacks as shown in Figure 1-3. Be sure to use the four-wire connections as shown.
2. Select the resistance calibrator external sense mode.
3. Configure the Model 2400 ohms function for the 4-wire sense mode as follows:
   - Press CONFIG then MEAS Ω. The instrument will display the following:

     CONFIG OHMS
     SOURCE SENSE-MODE GUARD
   - Select SENSE-MODE, and then press ENTER. The following will be displayed:

     SENSE-MODE
     2-WIRE 4-WIRE
   - Select 4-WIRE, and then press ENTER.
   - Press EXIT to return to normal display.
4. Press MEAS Ω to select the ohms measurement function, and make sure the source output is turned on.
5. Verify ohms measurement accuracy for each of the resistance values listed in Table 1-6. For each measurement:
   - Set the resistance calibrator output to the nominal resistance or closest available value.

NOTE *It may not be possible to set the resistance calibrator to the specified value. Use the closest possible setting, and modify reading limits accordingly.*

   - Select the appropriate ohms measurement range with the RANGE keys.
   - Verify that the Model 2400 resistance reading is within the limits given in the table.
6. Repeat the entire procedure using the rear panel INPUT/OUTPUT and 4-WIRE SENSE jacks. Be sure to select the rear panel jacks with the front panel TERMINALS key.

Table 1-6
Ohms measurement accuracy limits

Model 2400 range	Calibrator resistance*	Model 2400 resistance reading limits** (1 year, 18°C–28°C)
20Ω	19Ω	18.9784 to 19.0216Ω
200Ω	190Ω	189.824 to 190.176Ω
2kΩ	1.9kΩ	1.89845 to 1.90155kΩ
20kΩ	19kΩ	18.9850 to 19.0150kΩ
200kΩ	190kΩ	189.847 to 190.153kΩ
2MΩ	1.9MΩ	1.89761 to 1.90239MΩ
20MΩ	19MΩ	18.9781 to 19.0219MΩ
200MΩ	100MΩ	99.020 to 100.980MΩ

* Nominal resistance value.

** Reading limits based on Model 2400 normal accuracy specifications and nominal resistance values. If actual resistance values differ from nominal values shown, recalculate reading limits using actual calibrator resistance values and Model 2400 normal accuracy specifications. See Verification limits earlier in this section for details.

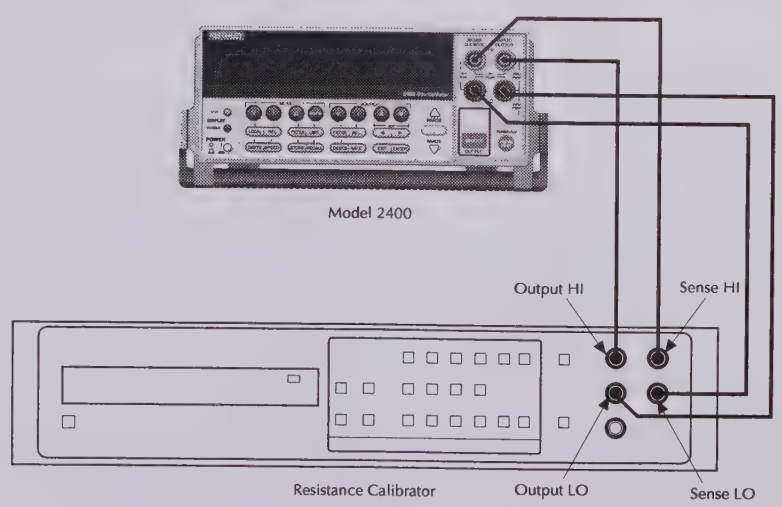


Figure 1-3
Resistance verification connections

2
Calibration

Introduction

Use the procedures in this section to calibrate the Model 2400. These procedures require accurate test equipment to measure precise DC voltages and currents. Calibration can be performed either from the front panel, or by sending SCPI calibration commands over the IEEE-488 bus or RS-232 port with the aid of a computer.

WARNING ***The information in this section is intended for qualified service personnel only. Do not attempt these procedures unless you are qualified to do so. Some of these procedures may expose you to hazardous voltages.***

Environmental conditions

Temperature and relative humidity

Conduct the calibration procedures at an ambient temperature of 18-28°C (65-82°F) with relative humidity of less than 70% unless otherwise noted.

Warm-up period

Allow the Model 2400 to warm up for at least one hour before performing calibration.

If the instrument has been subjected to temperature extremes (those outside the ranges stated above), allow additional time for the instrument's internal temperature to stabilize. Typically, allow one extra hour to stabilize a unit that is 10°C (18°F) outside the specified temperature range.

Also, allow the test equipment to warm up for the minimum time specified by the manufacturer.

Line power

The Model 2400 requires a line voltage of 88 to 264V at line frequency of 50 or 60Hz. The instrument must be calibrated within this range.

Calibration considerations

When performing the calibration procedures:

- Make sure that the test equipment is properly warmed up and connected to the Model 2400 front panel INPUT/OUTPUT jacks. Also be certain that the front panel jacks are selected with the TERMINALS switch.
- Always allow the source signal to settle before calibrating each point.
- Do not connect test equipment to the Model 2400 through a scanner or other switching equipment.
- If an error occurs during calibration, the Model 2400 will generate an appropriate error message. See Appendix B for more information.

WARNING ***The maximum common-mode voltage (voltage between LO and chassis ground) is 250V peak. Exceeding this value may cause a breakdown in insulation, creating a shock hazard.***

CAUTION ***The maximum voltage between INPUT/OUTPUT HI and LO or 4-WIRE SENSE HI and LO is 250V peak. The maximum voltage between INPUT/OUTPUT HI and 4-WIRE SENSE HI or between INPUT/OUTPUT LO and 4-WIRE SENSE LO is 5V. Exceeding these voltage values may result in instrument damage.***

Calibration cycle

Perform calibration at least once a year to ensure the unit meets or exceeds its specifications.

Recommended calibration equipment

Table 2-1 lists the recommended equipment for the calibration procedures. You can use alternate equipment as long as that equipment has specifications at least as good as those listed in the table. Where possible, test equipment specifications should be at least four times better than corresponding Model 2400 specifications.

Table 2-1
Recommended calibration equipment

Description	Manufacturer/ Model	Accuracy*		
Digital Multimeter	Hewlett Packard HP3458A	DC voltage	200mV:	±15ppm
			2V:	±6ppm
			20V:	±9ppm
			200V:	±7ppm
		DC current	1µA:	±55ppm
			10µA:	±25ppm
			100µA:	±23ppm
			1mA:	±20ppm
			10mA:	±20ppm
			100mA:	±35ppm
			1A:	±110ppm

* 90-day specifications show accuracy at specified measurement point.

Unlocking calibration

Before performing calibration, you must first unlock calibration by entering or sending the calibration password as follows:

Front panel calibration password

1. Press the MENU key, then choose CAL, and press ENTER. The instrument will display the following:

   CALIBRATION
   UNLOCK EXECUTE VIEW-DATES ▶
   ◀ SAVE LOCK CHANGE-PASSWORD

2. Select UNLOCK, and then press ENTER. The instrument will display the following:

   PASSWORD:
   Use ◀ , ▶ , ▲, ▼, ENTER, or EXIT.

3. Use the up and down RANGE keys to select the letter or number, and use the left and right arrow keys to choose the position. (Press down RANGE for letters; up RANGE for numbers.) Enter the current password on the display. (Front panel default: 002400.)

4. Once the correct password is displayed, press the ENTER key. If the password was correctly entered, the following message will be displayed:

   CALIBRATION UNLOCKED
   Calibration can now be executed

5. Press EXIT to return to normal display. Calibration will be unlocked and assume the states summarized in Table 2-2. Attempts to change any of the settings listed below with calibration unlocked will result in an error +510, "Not permitted with cal un-locked".

NOTE *With calibration unlocked, the sense function and range track the source function and range. That is, when :SOUR:FUNC is set to VOLT, the :SENS:FUNC setting will be 'VOLT:DC'. When :SOUR:FUNC is set to CURR, the :SENS:FUNC setting will be 'CURR:DC'. A similiar command coupling exists for :SOUR:VOLT:RANG/ :SENS:VOLT:RANG and SOUR:CURR:RANG/:SENS:CURR:RANG.*

Table 2-2
Calibration unlocked states

Mode	State	Equivalent remote command
Concurrent Functions	OFF	:SENS:FUNC:CONC OFF
Sense Function	Source	:SENS:FUNC <source_ function>
Sense Volts NPLC	1.0	:SENS:VOLT:NPLC 1.0
Sense Volts Range	Source V	:SENS:VOLT:RANG <source_V_range>
Sense Current NPLC	1.0	:SENS:CURR:NPLC 1.0
Sense Curent Range	Source I	:SENS:CURR:RANG <source_ I_ range>
Filter Count	10	:SENS:AVER:COUN 10
Filter Control	REPEAT	:SENS:AVER:TCON REPeat
Filter Averaging	ON	:SENS:AVER:STAT ON
Source V Mode	FIXED	:SOUR:VOLT:MODE FIXED
Volts Autorange	OFF:SOUR	:VOLT:RANG:AUTO OFF
Source I Mode	FIXED	:SOUR:CURR:MODE FIXED
Current Autorange	OFF	:SOUR:CURR:RANG:AUTO OFF
Autozero	ON	:SYST:AZERO ON
Trigger Arm Count	1	:ARM:COUNT 1
Trigger Arm Source	Immediate	:ARM:SOUR IMMediate
Trigger Count	1	:TRIG:COUNT 1
Trigger Source	Immediate	:TRIG:SOUR IMMediate

Remote calibration password

To unlock calibration via remote, send the following command:

```
:CAL:PROT:CODE '<password>'
```

For example, the following command uses the default password:

```
:CAL:PROT:CODE 'KI002400'
```

Changing the password

The default password may be changed from the front panel or via remote as discussed in the following paragraphs.

Front panel password

Follow the steps below to change the password from the front panel:

1. Press the MENU key, then choose CAL and press ENTER. The instrument will display the following:

   CALIBRATION
   UNLOCK EXECUTE VIEW-DATES ▶
   ◀ SAVE LOCK CHANGE-PASSWORD

2. Select CHANGE-PASSWORD, and then press ENTER. The instrument will display the following:

   NEW PWD: 002400
   Use ◀ , ▶ , ▲, ▼, ENTER, or EXIT.

3. Using the range keys, and the left and right arrow keys, enter the new password on the display.
4. Once the desired password is displayed, press the ENTER key to store the new password.

Remote password

To change the calibration password via remote, first send the present password, and then send the new password. For example, the following command sequence changes the password from the 'KI002400' remote default to 'KI_CAL':

```
:CAL:PROT:CODE 'KI002400'
:CAL:PROT:CODE 'KI_CAL'
```

You can use any combination of letters and numbers up to a maximum of eight characters.

NOTE *If you change the first two characters of the password to something other than "KI", you will not be able to unlock calibration from the front panel.*

Resetting the calibration password

If you lose the calibration password, you can unlock calibration by shorting together the CAL pads, which are located on the display board. Doing so will also reset the password to the factory default (KI002400).

See Section 5 for details on disassembling the unit to access the CAL pads. Refer to the display board component layout drawing at the end of Section 6 for the location of the CAL pads.

Viewing calibration dates and calibration count

When calibration is locked, only the UNLOCK and VIEW-DATES selections will be accessible in the calibration menu. To view calibration dates and calibration count at any time:

1. From normal display, press MENU, select CAL, and then press ENTER. The unit will display the following:

   CALIBRATION
   UNLOCK EXECUTE VIEW-DATES▶

2. Select VIEW-DATES, and then press ENTER. The Model 2400 will display the next and last calibration dates and the calibration count as in the following example:

   NEXT CAL: 12/15/96
   Last calibration: 12/15/95 Count: 00001

Calibration errors

The Model 2400 checks for errors after each calibration step, minimizing the possibility that improper calibration may occur due to operator error.

Front panel error reporting

If an error is detected during comprehensive calibration, the instrument will display an appropriate error message (see Appendix B). The unit will then prompt you to repeat the calibration step that caused the error.

Remote error reporting

You can detect errors while in remote by testing the state of EAV (Error Available) bit (bit 2) in the status byte. (Use the *STB? query to request the status byte.) Query the instrument for the type of error by using the appropriate :SYST:ERR? query. The Model 2400 will respond with the error number and a text message describing the nature of the error. See Appendix B for details.

Front panel calibration

The front panel calibration procedure described in the following paragraphs calibrates all ranges of both the current and voltage source and measure functions. Note that each range is separately calibrated by repeating the entire procedure for each range.

Step 1: Prepare the Model 2400 for calibration

1. Turn on the Model 2400 and the digital multimeter, and allow them to warm up for at least one hour before performing calibration.
2. Press the MENU key, then choose CAL and press ENTER. Select UNLOCK, and then press ENTER. The instrument will display the following:

   PASSWORD:
   Use ◄ , ► , ▲, ▼, ENTER, or EXIT.
3. Use the up and down range keys to select the letter or number , and use the left and right arrow keys to choose the position. Enter the present password on the display. (Front panel default: 002400.) Press ENTER to complete the process.
4. Press EXIT to return to normal display. Instrument operating states will be set as summarized in Table 2-2.

Step 2: Voltage calibration

Perform the steps below for each voltage range, using Table 2-3 as a guide.

1. Connect the Model 2400 to the digital multimeter, as shown in Figure 2-1. Select the multimeter DC volts measurement function.

NOTE *The 2-wire connections shown assume that remote sensing is not used. Remote sensing may be used, if desired, but it is not essential when using recommended digital multimeter.*

2. From normal display, press the SOURCE V key.
3. Press the EDIT key to select the source field (cursor flashing in source display field), and then use the down RANGE key to select the 200mV source range.
4. From normal display, press MENU.
5. Select CAL, and then press ENTER. The unit will display the following:

   CALIBRATION
   UNLOCK EXECUTE VIEW-DATES ►
   ◄ SAVE LOCK CHANGE-PASSWORD
6. Select EXECUTE, and then press ENTER. The instrument will display the following message:

   V-CAL
   Press ENTER to Output +200.00mV
7. Press ENTER. The Model 2400 will source +200mV and simultaneously display the following:

   DMM RDG: +200.0000mV
   Use ◄ , ► , ▲, ▼, ENTER, or EXIT.

8. Note and record the DMM reading, and then adjust the Model 2400 display to agree exactly with the actual DMM reading. (Use the up and down arrow keys to select the digit value, and use the left and right arrow keys to choose the digit position.) Note that the display adjustment range is within ±10% of the present range.
9. After adjusting the display to agree with the DMM reading, press ENTER. The instrument will then display the following:

   V-CAL
   Press ENTER to Output +000.00mV
10. Press ENTER. The Model 2400 will source 0mV and at the same time display the following:

    DMM RDG: +000.0000mV
    Use ◄ , ► , ▲, ▼, ENTER, or EXIT.
11. Note and record the DMM reading, and then adjust the Model 2400 display to agree with the actual DMM reading. Note that the display value adjustment limits are within ±1% of the present range.
12. After adjusting the display value to agree with the DMM reading, press ENTER. The unit will then display the following:

    V-CAL
    Press ENTER to Output -200.00mV
13. Press ENTER. The Model 2400 will source -200mV and display the following:

    DMM RDG: -200.0000mV
    Use ◄ , ► , ▲, ▼, ENTER, or EXIT.
14. Note and record the DMM reading, and then adjust the Model 2400 display to agree with the DMM reading. Again, the maximum display adjustment is within ± 10% of the present range.
15. After adjusting the display value to agree with the DMM reading, press ENTER, and note that the instrument displays:

    V-CAL
    Press ENTER to Output -000.00mV
16. Press ENTER The Model 2400 will source -0mV and simultaneously display the following:

    DMM RDG: -000.0000mV
    Use ◄ , ► , ▲, ▼, ENTER, or EXIT.
17. Note and record the DMM reading, and then adjust the display to agree with the DMM reading. Once again, the maximum adjustment is within ±1% of the present range.
18. After adjusting the display to agree with the DMM reading, press ENTER to complete calibration of the present range.
19. Press EXIT to return to normal display, and then select the 2V source range. Repeat steps 2 through 18 for the 2V range.
20. After calibrating the 2V range, repeat the entire procedure for the 20V and 200V ranges using Table 2-3 as a guide. Be sure to select the appropriate source range with the EDIT and RANGE keys before calibrating each range.
21. Press EXIT as necessary to return to normal display.

Figure 2-1
Voltage calibration connections

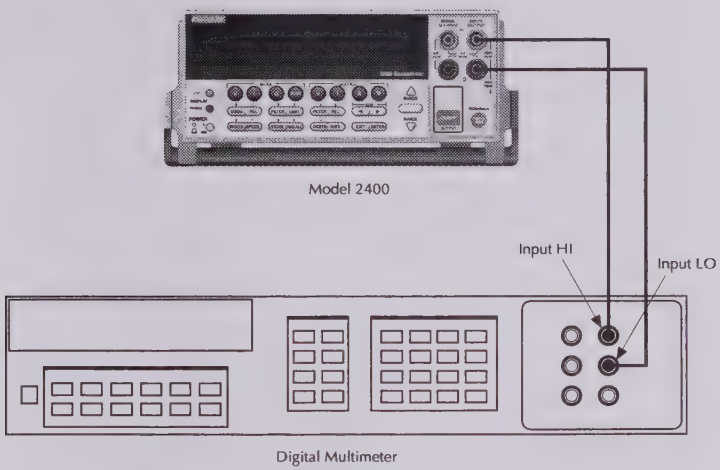


Table 2-3
Front panel voltage calibration

Source range*	Source voltage	Multimeter voltage reading**
0.2V	+200.00mV	_____ mV
	+000.00mV	_____ mV
	-200.00mV	_____ mV
	-000.00mV	_____ mV
2V	+2.0000V	_____ V
	+0.0000V	_____ V
	-2.0000V	_____ V
	-0.0000V	_____ V
20V	+20.000V	_____ V
	+00.000V	_____ V
	-20.000V	_____ V
	-00.000V	_____ V
200V	+200.00V	_____ V
	+000.00V	_____ V
	-200.00V	_____ V
	-000.00V	_____ V

* Use EDIT and RANGE keys to select source range.
** Multimeter reading used in corresponding calibration step. See procedure.

Step 3: Current calibration

Perform the following steps for each current range using Table 2-4 as a guide.

1. Connect the Model 2400 to the digital multimeter as shown in Figure 2-2. Select the multimeter DC current measurement function.
2. From normal display, press the SOURCE I key.
3. Press the EDIT key to select the source display field, and then use the down RANGE key to select the 1μA source range.
4. From normal display, press MENU.
5. Select CAL, and then press ENTER. The unit will display the following:

   CALIBRATION
   UNLOCK EXECUTE VIEW-DATES ▶
   ◀ SAVE LOCK CHANGE-PASSWORD
6. Select EXECUTE, and then press ENTER. The instrument will display the following message:

   I-CAL
   Press ENTER to Output +1.0000μA
7. Press ENTER. The Model 2400 will source +1μA and simultaneously display the following:

   DMM RDG: +1.000000μA
   Use ◀ , ▶ , ▲, ▼, ENTER, or EXIT.
8. Note and record the DMM reading, and then adjust the Model 2400 display to agree exactly with the actual DMM reading. (Use the up and down arrow keys to select the digit value; use the left and right arrow keys to choose the digit position.) Note that the display adjustment range is within ±10% of the present range.
9. After adjusting the display to agree with the DMM reading, press ENTER. The instrument will then display the following:

   I-CAL
   Press ENTER to Output +0.0000μA
10. Press ENTER. The Model 2400 will source 0μA and at the same time display the following:

    DMM RDG: +0.000000μA
    Use ◀ , ▶ , ▲, ▼, ENTER, or EXIT.
11. Note and record the DMM reading, and then adjust the Model 2400 display to agree with the actual DMM reading. Note that the display value adjustment limits are within ±1% of the present range.
12. After adjusting the display value to agree with the DMM reading, press ENTER. The unit will then display the following:

    I-CAL
    Press ENTER to Output -1.0000μA
13. Press ENTER. The Model 2400 will source -1μA and display the following:

    DMM RDG: -1.000000μA
    Use ◀ , ▶ , ▲, ▼, ENTER, or EXIT.

14. Note and record the DMM reading, then adjust the Model 2400 display to agree with the DMM reading. Again, the maximum display adjustment is within ± 10% of the present range.
15. After adjusting the display value to agree with the DMM reading, press ENTER, and note that the instrument displays:

    I-CAL
    Press ENTER to Output -0.0000µA
16. Press ENTER. The Model 2400 will source -0µA and simultaneously display the following:

    DMM RDG: -0.000000µA
    Use ◄ , ► , ▲, ▼, ENTER, or EXIT.
17. Note and record the DMM reading, and then adjust the display to agree with the DMM reading. Once again, the maximum adjustment is within ±1% of the present range.
18. After adjusting the display to agree with the DMM reading, press ENTER to complete calibration of the present range.
19. Press EXIT to return to normal display, then select the 10µA source range using the EDIT and up RANGE keys. Repeat steps 2 through 18 for the 10µA range.
20. After calibrating the 10µA range, repeat the entire procedure for the 100µA through 1A ranges using Table 2-4 as a guide. Be sure to select the appropriate source range with the EDIT and up RANGE keys before calibrating each range.

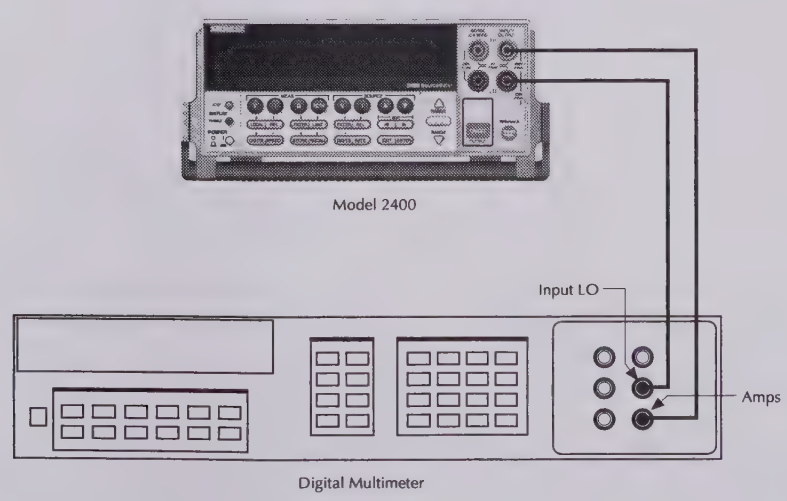


Figure 2-2
Current calibration connections

Table 2-4
Front panel current calibration

Source range*	Source current	Multimeter current reading**
1µA	+1.0000µA	_____µA
	+0.0000µA	_____µA
	-1.0000µA	_____µA
	-0.0000µA	_____µA
10µA	+10.000µA	_____µA
	+00.000µA	_____µA
	-10.000µA	_____µA
	-00.000µA	_____µA
100µA	+100.00µA	_____µA
	+000.00µA	_____µA
	-100.00µA	_____µA
	-000.00µA	_____µA
1mA	+1.0000mA	_____ mA
	+0.0000mA	_____ mA
	-1.0000mA	_____ mA
	-0.0000mA	_____ mA
10mA	+10.000mA	_____ mA
	+00.000mA	_____ mA
	-10.000mA	_____ mA
	-00.000mA	_____ mA
100mA	+100.00mA	_____ mA
	+000.00mA	_____ mA
	-100.00mA	_____ mA
	-000.00mA	_____ mA
1A	+1.0000A	_____ A
	+0.0000A	_____ A
	-1.0000A	_____ A
	-0.0000A	_____ A

* Use EDIT and RANGE keys to select source range.
** Multimeter reading used in corresponding calibration step. See procedure.

Step 4: Enter calibration dates and save calibration.

NOTE *For temporary calibration without saving new calibration constants, proceed to Step 5: Lock out calibration.*

1. From normal display, press MENU.
2. Select CAL, and then press ENTER. The Model 2400 will display the following:

   CALIBRATION
   UNLOCK EXECUTE VIEW-DATES ▶
   ◀ SAVE LOCK CHANGE-PASSWORD
3. Select SAVE, and then press ENTER. The instrument will display the following message:

   SAVE CAL
   Press ENTER to continue; EXIT to abort calibration sequence.
4. Press ENTER. The unit will prompt you for the calibration date:

   CAL DATE: 12/15/95
   Use ◀ , ▶ , ▲, ▼, ENTER, or EXIT.
5. Change the displayed date to today's date, and then press the ENTER key. Press ENTER again to confirm the date.
6. The unit will then prompt for the calibration due date:

   NEXT CAL: 12/15/96
   Use ◀ , ▶ , ▲, ▼, ENTER, or EXIT.
7. Set the calibration due date to the desired value, and then press ENTER. Press ENTER again to confirm the date.
8. Once the calibration dates are entered, calibration is complete. The following message will be displayed:

   CALIBRATION COMPLETE
   Press ENTER to confirm; EXIT to abort
9. Press ENTER to save the calibration data (or press EXIT to abort without saving calibration data). The following message will be displayed:

   CALIBRATION SUCCESS
   Press ENTER or EXIT to continue.
10. Press ENTER or EXIT to complete process.

Step 5: Lock out calibration.

1. From normal display, press MENU.
2. Select CAL, and then press ENTER. The Model 2400 will display the following:

   CALIBRATION
   UNLOCK EXECUTE VIEW-DATES ▶
   ◀ SAVE LOCK CHANGE-PASSWORD
3. Select LOCK, and then press ENTER. The instrument will display the following message:

   CALIBRATION LOCKED.
   Press ENTER or EXIT to continue.
4. Press ENTER or EXIT to return to normal display.

Remote calibration

Use the following procedure to perform remote calibration by sending SCPI commands over the IEEE-488 bus or RS-232 port. The remote commands and appropriate parameters are separately summarized for each step.

Remote calibration commands

Table 2-5 summarizes remote calibration commands, while Table 2-6 and Table 2-7 list command parameter limits. Note that each sense range requires three parameters: zero, negative full scale, and positive full scale. Similarly, each source range requires four parameters: two zero parameters, a positive full-scale parameter, and a negative full-scale parameter.

For a more complete description of these commands, refer to Appendix B.

Table 2-5
Remote calibration command summary

Command	Description
:CALibration	Calibration subsystem.
:PROTected	Cal commands protected by password.
:CODE '<password>'	Unlock cal; changes password if cal is already unlocked. (Default password: KI002400.)
:COUNT?	Query number of times 2400 has been calibrated.
:SAVE	Save calibration data to EEPROM.*
:LOCK	Lock calibration, inhibit SAVE command operation.
:LOCK?	Request cal lock status.
:DATE <y>,<m>,<d>	Program calibration year, month, day.
:DATE?	Query calibration year, month, day.
:NDUE <y>,<m>,<d>	Program calibration due year, month, day.
:NDUE?	Query calibration due year, month, day.
:SENSe <nrf>	Calibrate active measure range. (See Table 2-6 parameters.)
:DATA?	Query measurement cal constants for active range.
:SOURce <nrf>	Calibrate active source range. (See Table 2-7 parameters.)
:DATA?	Query source cal constants for active range.

* Calibration data will not be saved if:

1. Calibration was not unlocked with :CODE command.
2. Invalid data exists. (For example, cal step failed or was aborted.)
3. Incomplete number of cal steps were performed. (For example, omitting a negative full-scale step.)

Table 2-6
:CALibration:PROTected:SENSe parameter ranges

Sense range	First parameter (zero)	Second parameter (negative full scale)	Third parameter (positive full scale)
0.2V	-0.002 to +0.002	-0.18 to -0.22	+0.18 to +0.22
2V	-0.02 to +0.02	-1.8 to -2.2	+1.8 to +2.2
20V	-0.2 to +0.2	-18 to -22	+18 to +22
200V	-2 to +2	-180 to -220	+180 to +220
1µA	-1E-8 to +1E-8	-0.9E-6 to -1.1E-6	+0.9E-6 to +1.1E-6
10µA	-1E-7 to +1E-7	-9E-6 to -11E-6	+9E-6 to +11E-6
100µA	-1E-6 to +1E-6	-90E-6 to -110E-6	+90E-6 to +110E-6
1mA	-1E-5 to +1E-5	-0.9E-3 to -1.1E-3	+0.9E-3 to +1.1E-3
10mA	-1E-4 to +1E-4	-9E-3 to -11E-3	+9E-3 to +11E-3
100mA	-1E-3 to +1E-3	-90E-3 to -110E-3	+90E-3 to +110E-3
1A	-1E-2 to +1E-2	-0.9 to -1.1	+0.9 to +1.1

NOTE: Parameter steps for each range may be performed in any order, but all three parameter steps for each range must be completed.

Table 2-7
:CALibration:PROTected:SOURce parameter ranges

Source range	First parameter (negative full scale)	Second parameter (negative zero)	Third parameter (positive full scale)	Fourth parameter (positive zero)
0.2V	-0.18 to -0.22	-0.002 to +0.002	+0.18 to +0.22	-0.002 to +0.002
2V	-1.8 to -2.2	-0.02 to +0.02	+1.8 to +2.2	-0.02 to +0.02
20V	-18 to -22	-0.2 to +0.2	+18 to +22	-0.2 to +0.2
200V	-180 to -220	-2 to +2	+180 to +220	-2 to +2
1µA	-0.9E-6 to -1.1E-6	-1E-8 to +1E-8	+0.9E-6 to +1.1E-6	-1E-8 to +1E-8
10µA	-9E-6 to -11E-6	-1E-7 to +1E-7	+9E-6 to +11E-6	-1E-7 to +1E-7
100µA	-90E-6 to -110E-6	-1E-6 to +1E-6	+90E-6 to +110E-6	-1E-6 to +1E-6
1mA	-0.9E-3 to -1.1E-3	-1E-5 to +1E-5	+0.9E-3 to +1.1E-3	-1E-5 to +1E-5
10mA	-9E-3 to -11E-3	-1E-4 to +1E-4	+9E-3 to +11E-3	-1E-4 to +1E-4
100mA	-90E-3 to -110E-3	-1E-3 to +1E-3	+90E-3 to +110E-3	-1E-3 to +1E-3
1A	-0.9 to -1.1	-1E-2 to +1E-2	+0.9 to +1.1	-1E-2 to +1E-2

NOTE: Parameter steps for each range may be performed in any order, but all four parameter steps for each range must be completed.

Remote calibration procedure

Step 1: Prepare the Model 2400 for calibration

1. Connect the Model 2400 to the controller IEEE-488 interface or RS-232 port using a shielded interface cable.
2. Turn on the Model 2400 and the test equipment, and allow them to warm up for at least one hour before performing calibration.
3. If you are using the IEEE-488 interface, make sure the primary address of the Model 2400 is the same as the address specified in the program you will be using to send commands. (Use the MENU key and the COMMUNICATION menu to access the IEEE-488 address.)

Step 2: Voltage Calibration

1. Connect the Model 2400 to the digital multimeter (see Figure 2-1), and select the multimeter DC volts function.
2. Send the commands summarized in Table 2-8 in the order listed to initialize voltage calibration. (When the :CAL:PROT:CODE command is sent, the instrument will assume the operating states listed in Table 2-2.)
3. Perform the range calibration steps listed in Table 2-9 for each range. For each range:
   - Send the :SOUR:VOLT:RANG command to select the source and sense range being calibrated.. For example, for the 2V range, the following command would be sent:

     :SOUR:VOLT:RANG 2
   - Program the source to output the negative full-range value using the :SOUR:VOLT command. For example:

     :SOUR:VOLT -2
   - Note and record the multimeter reading.
   - Use the multimeter reading as the parameter for the :CAL:PROT:SOUR and :CAL:PROT:SENS commands. For example, a typical value for the 2V range would be:

     :CAL:PROT:SOUR -1.998
     :CAL:PROT:SENS -1.998
   - Program the voltage source for 0V output using the :SOUR:VOLT 0.0 command.
   - Note the multimeter reading.
   - Send the source and sense calibration commands using the multimeter reading for the parameter. For example:

     :CAL:PROT:SOUR 1E-3
     :CAL:PROT:SENS 1E-3
   - Set the source to the positive full-range value using the :SOUR:VOLT command. For example:

     :SOUR:VOLT 2
   - Note and record the multimeter reading.
   - Send the source and sense commands using the multimeter reading as the parameter. For example:

     :CAL:PROT:SOUR 1.997
     :CAL:PROT:SENS 1.997
   - Send the SOUR:VOLT 0.0 command to set the source voltage to 0V.
   - Note and record the multimeter reading.
   - Send the :CAL:PROT:SOUR command using the multimeter reading as the command parameter. For example:

     :CAL:PROT:SOUR -1.02E-3

Table 2-8
Voltage calibration initialization commands

Command	Description
*RST	Restore GPIB defaults.
:SOUR:FUNC VOLT	Activate voltage source.
:SENS:CURR:PROT 0.1	Current limit when voltage source is active.
:SENS:CURR:RANG 0.1	Make sure 1A range is not active.
:SOUR:VOLT:PROT :LEV MAX	Maximium allowable source voltage.
:SYST:RSEN OFF	Disable remote sensing. *
:CAL:PROT:CODE 'KI002400'	Unlock cal.
:OUTP:STAT ON	Turn source on.

* Remote sensing may be used if desired, but is not essential when using recommended digital multimeter.

Table 2-9
Voltage range calibration commands

Step	Command/procedure*	Description
1	:SOUR:VOLT:RANGE <Range>	Select source range.
2	:SOUR:VOLT -<Range>	Establish negative polarity.
3	Take DMM reading.	Read actual output value.
4	:CAL:PROT:SOUR <DMM_Reading>	Calibrate source function negative full scale.
5	Check 2400 for errors.	
6	:CAL:PROT:SENS <DMM_Reading>	Calibrate sense function negative full scale.
7	Check 2400 for errors.	
8	:SOUR:VOLT 0.0	Set output to 0V.
9	Take DMM reading.	Read actual output value.
10	:CAL:PROT:SOUR <DMM_Reading>	Calibrate sense function negative zero.
11	Check 2400 for errors.	
12	CAL:PROT:SENS <DMM_Reading>	Calibration source function negative zero.
13	Check 2400 for errors.	
14	:SOUR:VOLT +<Range>	Establish positive polarity.
15	Take DMM reading.	Read actual output value.
16	:CAL:PROT:SOUR <DMM_Reading>	Calibrate sense function positive full scale.
17	Check 2400 for errors.	
18	:CAL:PROT:SENS <DMM_Reading>	Calibrate source function positive full scale.
19	Check 2400 for errors.	
20	:SOUR:VOLT 0.0	Set output to 0V.
21	Take DMM reading.	Read actual output value.
22	:CAL:PROT:SOUR <DMM_Reading>	Calibrate source positive zero.

*1. Perform complete procedure for each range, where <Range> = 0.2, 2, 20, and 200.
2. <DMM_Reading> parameter is multimeter reading from previous step.
3. Use :SYST:ERR? query to check for errors.

Step 3: Current Calibration

1. Connect the Model 2400 to the digital multimeter (see Figure 2-2), and select the multimeter DC current function.
2. Send the commands summarized in Table 2-10 in the order listed to initialize current calibration.
3. Calibrate each current range using the procedure summarized in Table 2-11. For each range:
   - Send the :SOUR:CURR:RANG command to select the source and sense range being calibrated. For example, for the 1mA range, the command is:

     :SOUR:CURR:RANG 1E-3
   - Program the source to output the negative full-range value using the :SOUR:CURR command. For example:

     :SOUR:CURR -1E-3
   - Note and record the multimeter reading.
   - Use the multimeter reading as the parameter for the :CAL:PROT:SOUR and :CAL:PROT:SENS commands. For example, a typical value for the 1mA range would be:

     :CAL:PROT:SOUR -1.025E-3
     :CAL:PROT:SENS -1.025E-3
   - Program the current source for 0A output using the :SOUR:CURR 0.0 command.
   - Note the multimeter reading.
   - Send the source and sense calibration commands using the multimeter reading for the parameter. For example:

     :CAL:PROT:SOUR 1E-6
     :CAL:PROT:SENS 1E-6
   - Set the source to the positive full-range value using the :SOUR:CURR command. For example, for the 1mA range:

     :SOUR:CURR 1E3
   - Note and record the multimeter reading.
   - Send the source and sense commands using the multimeter reading as the parameter. For example:

     :CAL:PROT:SOUR 1.03E-3
     :CAL:PROT:SENS 1.03E-3
   - Send the :SOUR:CURR 0.0 command to set the source current to 0A.
   - Note and record the multimeter reading.
   - Send the :CAL:PROT:SOUR command using the multimeter reading as the command parameter. For example:

     :CAL:PROT:SOUR -1.02E-3

Table 2-10
Current calibration initialization commands

Command	Description
:SOUR:FUNC CURR	Select source current mode.
:SENS:VOLT:PROT 20	Voltage limit when current source is active.
:SENS:VOLT:RANG 20	Make sure 200V range is not active.
:OUTP:STAT ON	Turn source on.

Table 2-11
Current range calibration commands

Step	Command/procedure*	Description
1	:SOUR:CURR:RANGE <Range>	Select source range.
2	:SOUR:CURR -<Range>	Establish negative polarity.
3	Take DMM reading.	Read actual output value.
4	:CAL:PROT:SOUR <DMM_Reading>	Calibrate sense function negative full scale.
5	Check 2400 for errors.	
6	:CAL:PROT:SENS <DMM_Reading>	Calibrate source function negative full scale.
7	Check 2400 for errors.	
8	:SOUR:CURR 0.0	Set output to 0A.
9	Take DMM reading.	Read actual output value.
10	:CAL:PROT:SOUR <DMM_Reading>	Calibrate sense function negative zero.
11	Check 2400 for errors.	
12	:CAL:PROT:SENS <DMM_Reading>	Calibration source function negative zero.
13	Check 2400 for errors.	
14	:SOUR:CURR +<Range>	Establish positive polarity.
15	Take DMM reading.	Read actual output value.
16	:CAL:PROT:SOUR <DMM_Reading>	Calibrate sense function positive full scale.
17	Check 2400 for errors.	
18	:CAL:PROT:SENS <DMM_Reading>	Calibrate source function positive full scale.
19	Check 2400 for errors.	
20	:SOUR:CURR 0.0	Set output to 0A.
21	Take DMM reading.	Read actual output value.
22	:CAL:PROT:SOUR <DMM_Reading>	Calibrate source positive zero.

* 1. Perform complete procedure for each range, where <Range> = 1E6, 10E6, 100E6, 1E3, 10E3, 100E3, or 1.
2. <DMM_Reading> parameter is multimeter reading from previous step.
3. Use :SYST:ERR? query to check for errors.

Step 4: Program Calibration Dates

Use following commands to set the calibration date and calibration due date:

:CAL:PROT:DATE <year>, <month>, <day> (Calibration date)
:CAL:PROT:NDUE <year>, <month>, <day> (Next calibration due date)

Note that the year, month, and day must be separated by commas. The allowable range for the year is from 1995 to 2094, the month is from 1 to 12, and the day is from 1 to 31.

Step 5: Save Calibration Constants

Calibration is now complete, so you can store the calibration constants in EEROM by sending the following command:

```
:CAL:PROT:SAVE
```

NOTE *Calibration will be temporary unless you send the SAVE command. Also, calibration data will not be saved if (1) calibration is locked, (2) invalid data exists, or (3) all steps were not completed.*

Step 6: Lock Out Calibration

To lock out further calibration, send the following command after completing the calibration procedure:

```
:CAL:PROT:LOCK
```

Single-range calibration

Normally, the complete calibration procedure should be performed to ensure that the entire instrument is properly calibrated. In some instances, however, you may want to calibrate only certain ranges. To do so, simply complete the entire procedure only for the range(s) to be calibrated. Keep in mind, however, that you must complete all parameter steps for each source or sense range. Also be sure to set calibration dates and save calibration after calibrating the desired range(s).

3
Routine Maintenance

Introduction

The information in this section deals with routine type maintenance that can be performed by the operator.

Line fuse replacement

WARNING ***Disconnect the line cord at the rear panel, and remove all test leads connected to the instrument (front and rear) before replacing the line fuse.***

The power line fuse is accessible from the rear panel, just above the AC power receptacle (see Figure 3-1).

Perform the following steps to replace the line fuse:

1. Carefully grasp and squeeze together the locking tabs that secure the fuse carrier to the fuse holder.
2. Pull out the fuse carrier, and replace the fuse with the type specified in Table 3-1.

CAUTION ***To prevent instrument damage, use only the fuse type specified in Table 3-1.***

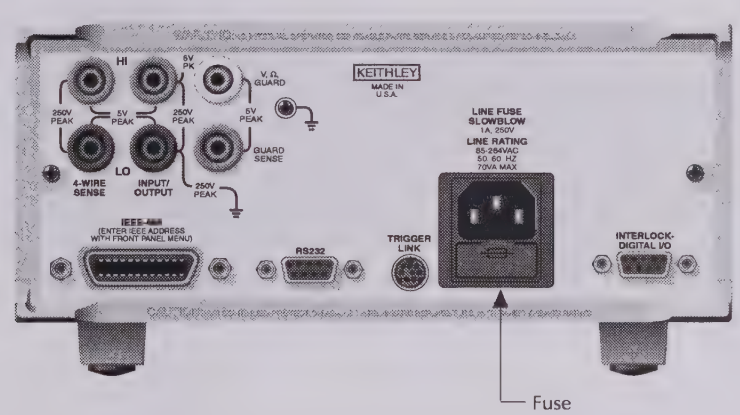
3. Re-install the fuse carrier.

NOTE *If the power line fuse continues to blow, a circuit malfunction exists and must be corrected. Refer to the troubleshooting section of this manual for additional information.*

Table 3-1
Power line fuse

Line voltage	Rating	Keithley part no.
88-264V	250V, 1A, slow blow 5 × 20mm	FU-72

Figure 3-1
Rear panel



4
Troubleshooting

Introduction

This section of the manual will assist you in troubleshooting and repairing the Model 2400. Included are self-tests, test procedures, troubleshooting tables, and circuit descriptions. The repair technician must select the appropriate tests and documentation needed to troubleshoot the instrument. Note that disassembly instructions are located in Section 5, while component layout drawings are at the end of Section 6.

WARNING ***The information in this section is intended for qualified service personnel only. Do not perform these procedures unless you are qualified to do so. Some of these procedures may expose you to hazardous voltages that could cause personal injury or death. Use caution when working with hazardous voltages.***

Repair considerations

Before making any repairs to the Model 2400, be sure to read the following considerations.

CAUTION ***The PC boards are built using surface mount techniques and require specialized equipment and skills for repair. If you are not equipped and/or qualified, it is strongly recommended that you send the unit back to the factory for repairs or limit repairs to the PC board replacement level. Without proper equipment and training, you could damage a PC board beyond repair.***

- Repairs will require various degrees of disassembly. However, it is recommended that the Front Panel Tests be performed prior to any disassembly. The disassembly instructions for the Model 2400 are contained in Section 5 of this manual.
- Do not make repairs to surface mount PC boards unless equipped and qualified to do so (see previous CAUTION).
- When working inside the unit and replacing parts, be sure to adhere to the handling precautions and cleaning procedures explained in Section 5.
- Many CMOS devices are installed in the Model 2400. These static-sensitive devices require special handling as explained in Section 5.
- Whenever a circuit board is removed or a component is replaced, the Model 2400 must be recalibrated. See Section 2 for details on calibrating the unit.

Power-on self-test

During the power-on sequence, the Model 2400 will perform a checksum test on its ROM and test its RAM. If the RAM test fails, the instrument will lock up. If the ROM checksum test fails, the firmware upgrade mode is automatically enabled. See Firmware upgrades at the end of this section.

Front panel tests

There are three front panel tests: one to test the functionality of the front panel keys and two to test the display. In the event of a test failure, refer to Display board checks for details on troubleshooting the display board.

KEYS test

The KEYS test allows you to check the functionality of each front panel key. Perform the following steps to run the KEYS test.

1. Display the MAIN MENU by pressing the MENU key.
2. Select TEST, and press ENTER to display the SELF-TEST MENU.
3. Select DISPLAY-TESTS, and press ENTER to display the following menu:

   FRONT PANEL TESTS
   KEYS DISPLAY-PATTERNS CHAR-SET
4. Select KEYS, and press ENTER to start the test. When a key is pressed, the label name for that key will be displayed to indicate that it is functioning properly. When the key is released, the "No keys pressed" message is displayed.
5. Pressing EXIT tests the EXIT key. However, the second consecutive press of EXIT aborts the test and returns the instrument to the SELF-TEST MENU. Continue pressing EXIT to back out of the menu structure.

DISPLAY PATTERNS test

The display test allows you to verify that each pixel and annunciator in the vacuum fluorescent display is working properly. Perform the following steps to run the display test:

1. Display the MAIN MENU by pressing the MENU key.
2. Select TEST, and press ENTER to display the SELF-TEST MENU.
3. Select DISPLAY-TESTS, and press ENTER to display the following menu:

   FRONT PANEL TESTS
   KEYS DISPLAY-PATTERNS CHAR-SET
4. Select DISPLAY-PATTERNS, and press ENTER to start the display test. There are five parts to the display test. Each time a front panel key (except EXIT) is pressed, the next part of the test sequence is selected. The five parts of the test sequence are:

   - Checkerboard pattern (alternate pixels on) and all annunciators.
   - Checkerboard pattern and the annunciators that are on during normal operation.
   - Horizontal lines (pixels) of the first digit are sequenced.
   - Vertical lines (pixels) of the first digit are sequenced.
   - Each digit (and adjacent annunciator) is sequenced. All the pixels of the selected digit are on.
5. When finished, abort the display test by pressing EXIT. The instrument returns to the SELF-TEST MENU. Continue pressing EXIT to back out of the menu structure.

CHAR SET test

The character set test allows you to display all characters. Perform the following steps to run the character set test:

1. Display the MAIN MENU by pressing the MENU key.
2. Select TEST, and press ENTER to display the SELF-TEST MENU.
3. Select DISPLAY-TESTS, and press ENTER to display the following menu:

   FRONT PANEL TESTS
   KEYS DISPLAY-PATTERNS CHAR-SET
4. Select CHAR-SET, and press ENTER to start the character set test. Press any key except EXIT to cycle through all displayable characters.
5. When finished, abort the character set test by pressing EXIT. The instrument returns to the SELF-TEST MENU. Continue pressing EXIT to back out of the menu structure.

Principles of operation

The following information is provided to support the troubleshooting tests and procedures covered in this section of the manual. Refer to the following drawings:

Figure 4-1 — Analog circuitry overall block diagram
Figure 4-2 — Power supply block diagram
Figure 4-3 — Output stage simplified schematic
Figure 4-4 — Digital circuitry block diagram

Analog circuits

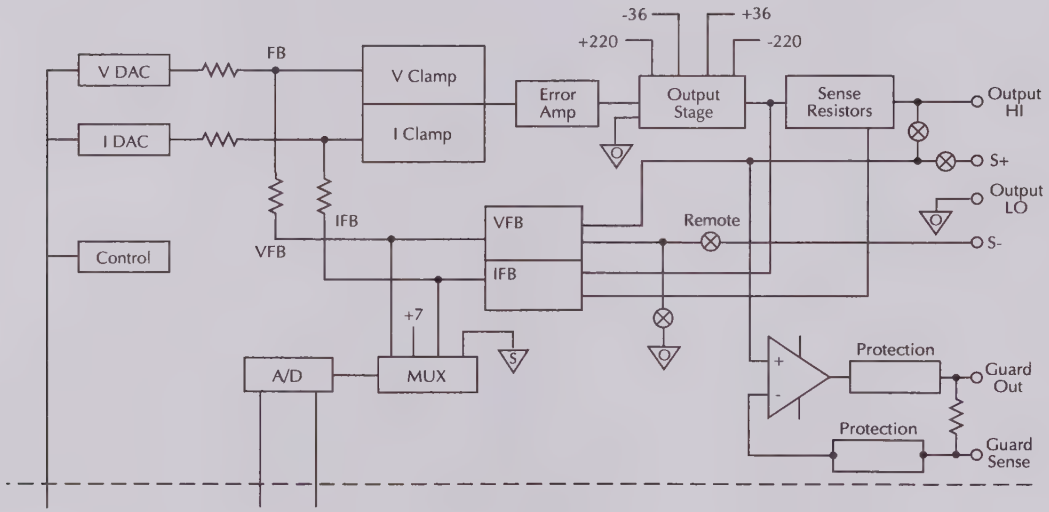
Figure 4-1 shows the overall block diagram for the Model 2400.

D/A converters control the programmed voltage and current, or voltage compliance and current compliance. Each DAC has two ranges, a 10V output or a 1V output. The DAC outputs are fed to the summing node, FB. Either the V DAC or the I DAC has the ability to control the main loop. If the unit is set for SV (source voltage), it will source voltage until the compliance current is reached (as determined by the I DAC setting), and the current loop will override the voltage loop. If, however, the unit is set for SI (source current), it will source current until the compliance voltage is reached (as determined by the V DAC setting), and the voltage loop will override the current loop. A priority bit in the Vclamp/I clamp circuit controls these functions.

The error amplifier adds open-loop gain and slew-rate control to the system to assure accuracy and provide a controllable signal for the output stage, which provides the necessary voltage and current gain to drive the output. Sense resistors in the HI output lead provide output current sensing, and a separate sense resistor is used for each current range. The 1A range uses 0.2V full-scale for a full-range 1A output, while all other ranges use 2V output for full-scale current. Voltage feedback is routed either internally or externally.

There are four voltage ranges: 0.2V, 2V, 20V, and 200V. The feedback gain changes for only the 20V and 200V ranges, resulting in three unique feedback gain values. A multiplexer directs the voltage feedback, current feedback, reference, or ground signal to the A/D converter. An opto-isolated interface provides control signals for both DACs, analog circuit control, and A/D converter communication to the digital section.

Figure 4-1
Analog circuit block diagram



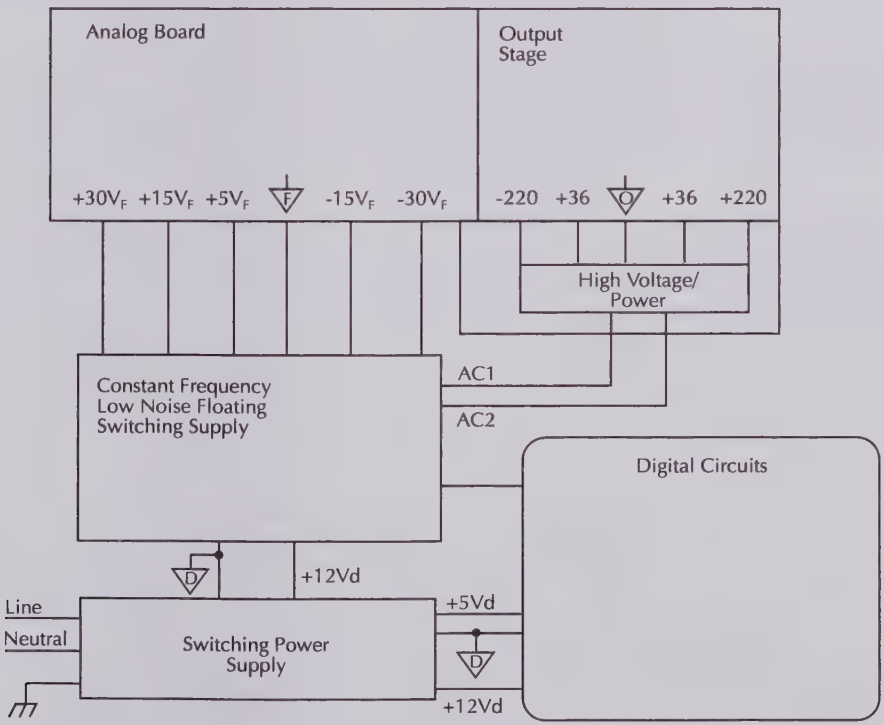
Power supply

Figure 4-2 shows a block diagram of the Model 2400 power delivery system.

The offline flyback switching power supply provides all power for the instrument while providing universal inputs for the 110/120V line. The digital board runs directly from the switcher, including the +12VD supply. (See Digital circuitry.)

A constant-frequency switching supply runs off the +12VD supplies and generates all the floating supply voltages for the analog board: +5VF, ±15VF, and ±30VF. An AC output (low voltage) supplies the analog board with the power it uses to derive the output stage supply voltages, ±36VO and ±220VO.

Figure 4-2
Power supply block diagram



Output stage

Figure 4-3 shows a simplified schematic of the output stage.

The Model 2400 output stage serves two purposes: (1) it converts signals from floating common to output common, and (2) it provides both voltage and current amplification. The output stage drive transistors are biased in class B configuration to prevent the possibility of thermal runaway with high-current output values. High-current taps for the ±20V outputs are provided to reduce power dissipation on the 20V and lower ranges.

Output transistors Q518 and Q521 are cascoded with output MOSFETs Q516 and Q523. All other MOSFETs and transistors are slaves, and the voltages across these devices are determined by the resistor-capacitor ladder circuits shown. Coarse current limits are built into the output stage.

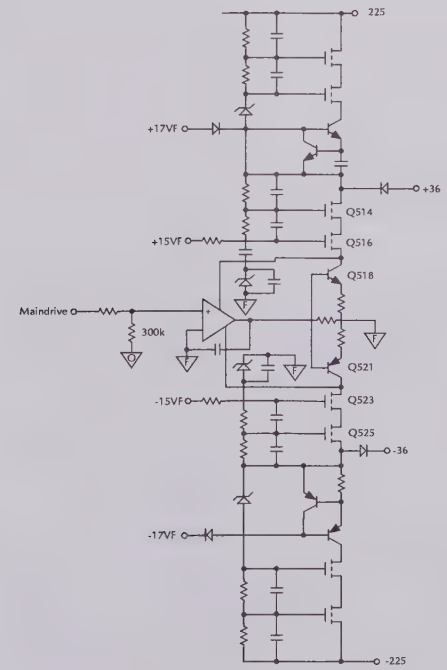


Figure 4-3
Output stage simplified schematic

A/D converter

The SourceMeter unit uses a multi-slope charge balance A/D converter with a single-slope run-down. The converter is controlled by gate array U610. Commands are issued by the MPU on the digital board through communications opto-isolators to U610, and U610 sends A/D reading data back through opto-isolators to the digital board for calibration and processing.

Active guard

The Model 2400 has an active guard or "six-wire ohms" circuit used to measure complex devices. This circuitry provides a low-current (50mA) equivalent of the voltage on output HI. If the unit is in the SV mode, the low-current equivalent of the source voltage will appear on the guard terminal. If the unit is in the SI mode, the voltage on output HI is equal to the source current multiplied by the external resistance value. An equivalent voltage will be generated by the guard circuit, and a guard sense terminal is provided to sense around the voltage drop in the guard leads since significant current can flow (50mA).

Digital circuitry

Refer to Figure 4-4 for the following discussion on digital circuitry.

The core digital circuitry uses a Motorola 68332 microcontroller running at 16.78MHz. The memory configuration includes two 256K X 8-bit EEPROMs and two 128K X 8-bit RAMs used in parallel to utilize the 16-bit data bus of the MPU. The RAM is battery backed-up, providing continued storage of data buffer information during power-down cycles. All calibration constants and system setups are stored in a separate serial EEPROM.

External communication is provided via GPIB and serial interfaces. A 9914 GPIA IEEE-488 standard interface IC is used for the GPIB, and a 68332 Queued Serial Module (QSM) provides the serial UART. For internal communications, the Time Processing Unit (TPU) is used for serial communications with the front panel display module, and both the TPU and QSM handle digital-to-analog interfacing.

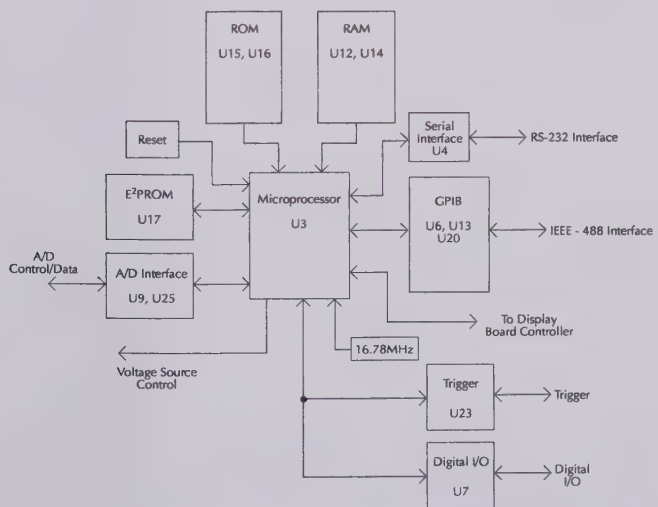


Figure 4-4
Digital board block diagram

Display board

Display board components are shown in the digital circuitry block diagram in Figure 4-4.

U902 is the display microcontroller that controls the VFD (vacuum fluorescent display) and interprets key data. The microcontroller has four peripheral I/O ports that are used for the various control and read functions.

Display data is serially transmitted to the microcontroller from the digital board via the TXB line to the microcontroller PD0 terminal. In a similar manner, key data is serially sent back to the digital board through the RXB line via PD1. The 4MHz clock for the microcontroller is generated on the digital board.

DS901 is the VFD (vacuum fluorescent display) module, which can display up to 49 characters. Each character is organized as a 5×7 matrix of dots or pixels and includes a long underbar segment to act as a cursor.

The display uses a common multiplexing scheme with each character refreshed in sequence. U903 and U904 are the grid drivers, and U901 and U905 are the dot drivers. Note that dot driver and grid driver data is serially transmitted from the microcontroller (PD3 and PC1).

The VFD requires both +60VDC and 5VAC for the filaments. These VFD voltages are supplied by U625, which is located on the digital board.

The front panel keys (S901-S931) are organized into a row-column matrix to minimize the number of microcontroller peripheral lines required to read the keyboard. A key is read by strobing the columns and reading all rows for each strobed column. Key down data is interpreted by the display microcontroller and sent back to the main microprocessor using proprietary encoding schemes.

Troubleshooting

Troubleshooting information for the various circuits is summarized in the following paragraphs.

Display board checks

If the front panel display tests indicate that there is a problem on the display board, use Table 4-1. See Principles of operation for display circuit theory.

Table 4-1
Display board checks

Step	Item/component	Required condition	Remarks
1	Front panel test	Verify that all segments operate.	Use front panel display test.
2	P1005, pin 5	+5V ±5%	Digital +5V supply.
3	P1005, pin 9	+37V ±5%	Display +37V supply.
4	U902, pin 1	Goes low briefly on power up, and then goes high.	Microcontroller RESET.
5	U902, pin 43	4MHz square wave.	Controller 4MHz clock.
6	U902, pin 32	Pulse train every 1ms.	Control from main processor.
7	U902 pin 33	Brief pulse train when front panel key is pressed.	Key down data sent to main processor.

Power supply checks

Power supply problems can be checked using Table 4-2. See Principles of operation for circuit theory on the power supply. Note that the power supply circuits are located on the digital board.

Table 4-2
Power supply checks

Step	Item/component	Required condition	Remarks
1	Line fuse	Check continuity.	Remove to check.
2	Line power	Plugged into live receptacle, power on.	Check for correct power-up sequence.
3	TP5	+5V ±5%	+5VF, referenced to Common F3[1].
4	TP6	+15V ±5%	+15VF, referenced to Common F2[2].
5	TP7	-15V ±5%	-15VF, referenced to Common F2.
6	TP8	~ -35V	-30VF, referenced to Common F2.
7	TP9	~ +35V	+30VF, referenced to Common F2.

[1] U18, pin 2.
[2] U8, pin 1.

Digital circuitry checks

Digital circuit problems can be checked using Table 4-3. See Principles of operation for a digital circuit description.

Table 4-3
Digital circuitry checks

Step	Item/component	Required condition	Remarks
1	Power-on test	RAM OK, ROM OK.	Verify that RAM and ROM are functional.
2	U3 pin 19	Digital common.	All signals referenced to digital common.
3	U3 pin 7	+5V	Digital logic supply.
4	U3 pin 68	Low on power-up, and then goes high.	MPU RESET line.
5	U3, lines A0-A19	Check for stuck bits.	MPU address bus.
6	U3, lines D0-D15	Check for stuck bits.	MPU data bus.
7	U3 pin 66	16.78MHz.	MPU clock.
8	U4 pin 7	Pulse train during RS-232 I/O.	RS-232 RX line.
9	U4 pin 8	Pulse train during RS-232 I/O.	RS-232 TX line.
10	U13 pins 34-42	Pulse train during IEEE-488 I/O.	IEEE-488 data bus.
11	U13 pins 26-31	Pulses during IEEE-488 I/O.	IEEE-488 command lines.
12	U13 pin 24	Low with remote enabled.	IEEE-488 REN line.
13	U13 pin 25	Low during interface clear.	IEEE-488 IFC line.
14	U3 pin 43	Pulse train.	D_ADDATA
15	U3 pin 44	Pulse train.	D_DATA
16	U3 pin 45	Pulse train.	D_CLK
17	U3 pin 47	Pulse train.	D_STB

Analog circuitry checks

Table 4-4 summarizes analog circuitry checks.

Table 4-4
Analog circuitry checks

Step	Item/ component	Required condition (Bench defaults)	Remarks
1	TP200	>200V voltage protection	-13 ±1V
2	TP201	SOURCE +10V	-5V ±.5V
3	TP202	SOURCE +10V (SVMI)	-10V ±1V
4	TP203	SOURCE +10V	-10.5 ±1V
5	TP213	SOURCE +10V	0V ±.1V
6*	TP218	OUTPUT COM	7V ±.7V
7*	TP219	OUTPUT COM	7V ±.7V
8*	TP214	SVMI, OUTPUT ON, 20V, on 20V RANGE	20V ±.5V
9	TP232	Bench defaults	6.4V ±.6V

*Measured with respect to OUTPUT COM (TP501)

Battery replacement

WARNING ***Disconnect the instrument from the power line and all other equipment before changing the battery.***

The volatile memories of the Model 2400 are protected by a replaceable battery when power is off. Typical life for the battery is approximately ten years. The battery should be suspected if the instrument no longer retains buffer data or user-defined operating parameters, such as instrument setups, source memory, and math expressions. If the battery is absent or totally exhausted, the display will show the "Reading buffer data lost" message shortly after the Model 2400 is switched on.

The battery is a 3V wafer-type lithium cell, Duracell type DL2450 or equivalent (Keithley part number BA-44), which is located on the digital board. Replacement of the battery requires removal of the case cover, analog shield, and analog board assembly. (See Section 5.)

WARNING ***The precautions below must be followed to avoid personal injury.***

1. Wear safety glasses or goggles when working with lithium batteries.
2. Do not short the battery terminals together.
3. Keep lithium batteries away from all liquids.
4. Do not attempt to recharge lithium batteries.
5. Observe proper polarity when inserting the battery in its holder.
6. Do not incinerate or otherwise expose the battery to excessive heat (>60°C).
7. Bulk quantities of lithium batteries should be disposed of as a hazardous waste.

To replace the battery, first locate its holder. Use a small, non-metallic tool to lift the battery so that it can be slid out from under the retainer spring clip.

The new battery should be reinstalled with the "+" terminal facing up. Lift up on the retaining clip and place the edge of the battery under the clip. Slide the battery fully into the holder.

Re-assemble the instrument and turn it on. The "Reading buffer data lost" error message will be displayed. Send the :syst:mem:init command to perform the following:

- Clear the reading buffer.
- Initialize instrument setups 1-4 to the present instrument settings.
- Initialize all 100 source memory locations to the present instrument settings.
- Delete user math expressions.

No comm link error

A "No Comm Link" error indicates that the front panel processor has ceased communication with the main processor, which is located on the digital board. This error indicates that one of the main processor ROMs may require re-seating in its socket. ROMs may be reseated as follows:

1. Turn off the power, and disconnect the line cord and all other test leads and cables from the instrument.
2. Remove the case cover as outlined in Section 5.
3. Remove the analog shield and analog board assembly as outlined in Section 5.
4. Locate the two firmware ROMs, U15 and U16, located on the digital board. These are the only ICs installed in sockets. (Refer to the component layout drawing at the end of Section 6 for exact locations.)
5. Carefully push down on each ROM IC to make sure it is properly seated in its socket.

CAUTION ***Be careful not to push down excessively, or you might crack the digital board.***

6. Connect the line cord, and turn on the power. If the problem persists, additional troubleshooting will be required.

5
Disassembly

Introduction

This section explains how to handle, clean, and disassemble the Model 2400. Disassembly drawings are located at the end of this section.

Handling and cleaning

To avoid contaminating PC board traces with body oil or other foreign matter, avoid touching the PC board traces while you are repairing the instrument. Analog circuits have high-impedance devices or sensitive circuitry where contamination could cause degraded performance.

Handling PC boards

Observe the following precautions when handling PC boards:

- Wear cotton gloves.
- Only handle PC boards by the edges and shields.
- Do not touch any board traces or components not associated with repair.
- Do not touch areas adjacent to electrical contacts.
- Use dry nitrogen gas to clean dust off PC boards.

Solder repairs

Observe the following precautions when you must solder a circuit board:

- Use an OA-based (organic activated) flux, and take care not to spread the flux to other areas of the circuit board.
- Remove the flux from the work area when you have finished the repair by using pure water with clean, foam-tipped swabs or a clean, soft brush.
- Once you have removed the flux, swab only the repair area with methanol, then blow-dry the board with dry nitrogen gas.
- After cleaning, allow the board to dry in a 50°C, low-humidity environment for several hours.

Static sensitive devices

CMOS devices operate at very high impedance levels. Therefore, any static that builds up on you or your clothing may be sufficient to destroy these devices if they are not handled properly. Use the following precautions to avoid damaging them:

CAUTION ***Many CMOS devices are installed in the Model 2400. Handle all semiconductor devices as being static sensitive.***

- Transport and handle ICs only in containers specially designed to prevent static build-up. Typically, you will receive these parts in anti-static containers made of plastic or foam. Keep these devices in their original containers until ready for installation.
- Remove the devices from their protective containers only at a properly grounded work station. Also, ground yourself with a suitable wrist strap.
- Handle the devices only by the body; do not touch the pins.
- Ground any printed circuit board into which a semiconductor device is to be inserted to the bench or table.
- Use only anti-static type desoldering tools.
- Use only grounded-tip solder irons.
- Once the device is installed in the PC board, it is normally adequately protected, and you can handle the boards normally.

Assembly drawings

Use the assembly drawings located at the end of this section to assist you as you disassemble and re-assemble the Model 2400. Also, refer to these drawings for information about the Keithley part numbers of most mechanical parts in the unit.

- Front panel assembly — 2400-040
- Analog board/heat sink/shield assembly — 2400-050
- Chassis assembly — 2400-051
- Chassis/analog board assembly — 2400-052
- Final chassis assembly — 2400-053

Case cover removal

Follow the steps below to remove the case cover to gain access to internal parts.

WARNING ***Before removing the case cover, disconnect the line cord and any test leads from the instrument.***

1. Remove Handle — The handle serves as an adjustable tilt-bail. Adjust its position by gently pulling it away from the sides of the instrument case and swinging it up or down. To remove the handle, swing the handle below the bottom surface of the case and back until the orientation arrows on the handles line up with the orientation arrows on the mounting ears. With the arrows lined up, pull the ends of the handle away from the case.
2. Remove Mounting Ears — Remove the screw that secures each mounting ear. Pull down and out on each mounting ear.

NOTE *When re-installing the mounting ears, be sure to mount the right ear to the right side of the chassis and the left ear to the left side of the chassis. Each ear is marked "RIGHT" or "LEFT" on its inside surface.*

3. Remove Rear Bezel — To remove the rear bezel, loosen the two screws that secure the rear bezel to the chassis, and then pull the bezel away from the case.
4. Removing Grounding Screws — Remove the two grounding screws that secure the case to the chassis. They are located on the bottom of the case at the back.
5. Remove Chassis — To remove the case, grasp the front bezel of the instrument, and carefully slide the chassis forward. Slide the chassis out of the metal case.

NOTE *To gain access to the components under the analog board shield, remove the shield, which is secured to the analog board by a single screw.*

Analog board removal

Perform the following steps to remove the analog board. This procedure assumes that the case cover is already removed.

1. Remove analog board shield.
   Remove the screw that secures the shield to the analog board, then remove the shield.
2. Disconnect the front and rear input terminals.
   You must disconnect these input terminal connections for both the front and rear inputs:
   - INPUT/OUTPUT HI and LO
   - 4-WIRE SENSE HI and LO
   - V, Ω, GUARD, and GUARD SENSE (rear panel only)

   Remove all the connections by pulling the wires off the pin connectors. During re-assembly, use the following table to identify input terminals:

	Front wire color	Rear wire color
INPUT/OUTPUT HI	Red	White/Red
INPUT/OUTPUT LO	Black	White/Black
4-WIRE SENSE HI	Yellow	White/Yellow
4-WIRE SENSE LO	Gray	White/Gray
V, Ω, GUARD	—	White
GUARD SENSE	—	Blue/White

3. Unplug cables.
   - Carefully unplug the ribbon cables at J1001, J1002, and J1003.
   - Unplug the ON/OFF cable at J1034.
4. Remove screws.
   - Remove the two fastening screws that secure the analog board assembly to the chassis. These screws are located on the side of the board opposite from the heat sink.
   - Remove the two screws that secure the heat sink to the chassis.
5. Remove analog board assembly.
   - After all screws have been removed, carefully lift the analog board assembly free of the main chassis.
6. Disassemble analog board assembly.
   - Remove the screws that secure the analog board and heat sink to the analog board sub-chassis.
   - Carefully remove the heat sink by sliding the clips off the power transistors.

CAUTION ***Be careful not to damage the heat sink insulation layer.***

- Remove the analog board from the subchassis.
- Remove the four screws that secure the bottom cover, and then remove the cover from the bottom of the PC board.

NOTE *When re-installing the heat sink, make sure that all clips are properly installed and centered on each pair of output transistors.*

Digital board removal

Perform the following steps to remove the digital board. This procedure assumes that the analog board assembly is already removed.

1. Remove the IEEE-488, Digital I/O, and RS-232 fasteners.
   The IEEE-488, Digital I/O, and RS-232 connectors each have two nuts that secure the connectors to the rear panel. Remove these nuts.
2. Remove the POWER switch rod.
   At the switch, place the edge of a flat-blade screw driver in the notch on the pushrod. Gently twist the screw driver while pulling the rod from the shaft.
3. Unplug cables:
   - Unplug the display board ribbon cable.
   - Unplug the cables going to the power supply.
   - Unplug the rear panel power module cable.
4. Remove digital board.
   Slide the digital board forward until it is free of the guide pins, then remove the board.

   During re-assembly, replace the board, and start the IEEE-488, Digital I/O, and RS-232 connector nuts and the mounting screw. Tighten all the fasteners once they are all in place and the board is correctly aligned.

Front panel disassembly

Use the following steps to remove the display board and/or the pushbutton switch pad.

1. Unplug the display board ribbon cable.
2. Remove the front panel assembly.
   This assembly has four retaining clips that snap onto the chassis over four pem nut studs. Two retaining clips are located on each side of the front panel. Pull the retaining clips outward and, at the same time, pull the front panel assembly forward until it separates from the chassis.
3. Using a thin-bladed screw driver, pry the plastic PC board stop (located at the bottom of the display board) until the bar separates from the casing. Pull the display board from the front panel.
4. Remove the switch pad by pulling it from the front panel.

Removing power components

The following procedures for removing the power supply and/or power module require that the case cover and analog board be removed, as previously explained.

Power supply removal

Perform the following steps to remove the power supply:

1. Remove the analog board.
2. Unplug the two cables coming from the digital board.
3. Remove the four screws that secure the power supply to the bottom of the chassis.
4. Remove the power supply from the chassis.

Power module removal

Perform the following steps to remove the rear panel power module:

1. Remove the analog board.
2. Unplug the cable connecting the power module to the digital board.
3. Disconnect the power module's ground wire. This green and yellow wire connects to a threaded stud on the chassis with a kep nut.
4. Squeeze the latches on either side of the power module while pushing the module from the access hole.

WARNING ***To avoid electrical shock, which could result in injury or death, the ground wire of the power module must be connected to chassis ground. When installing the power module, be sure to re-connect the green and yellow ground wire to the threaded stud on the chassis.***

Instrument re-assembly

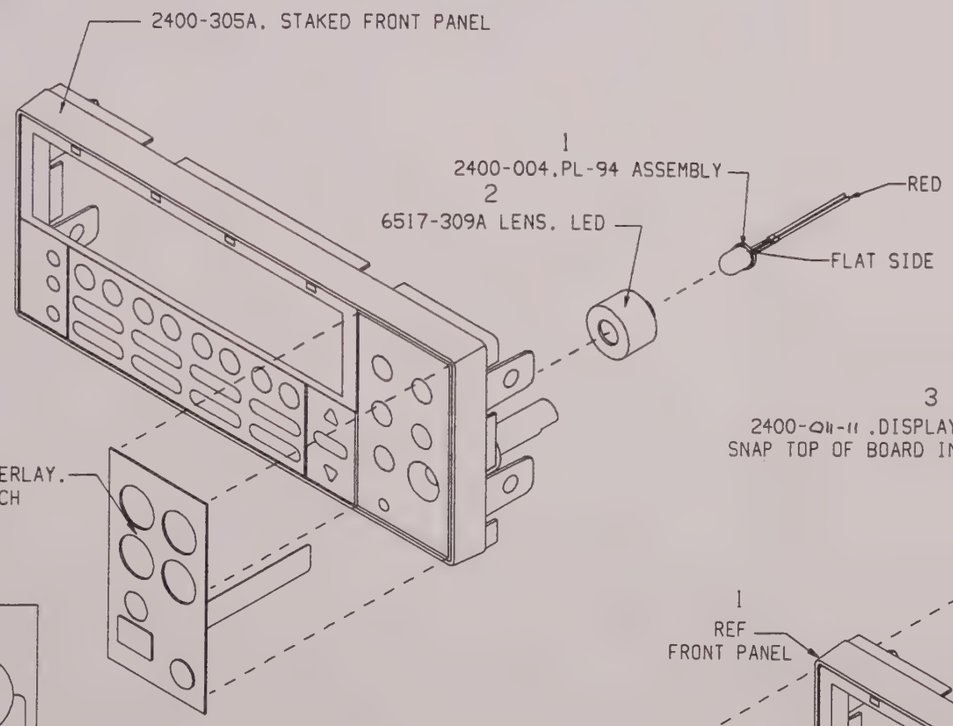
Re-assemble the instrument by reversing the previous disassembly procedures. Make sure that all parts are properly seated and secured and that all connections are properly made. To ensure proper operation, replace and securely fasten the shield.

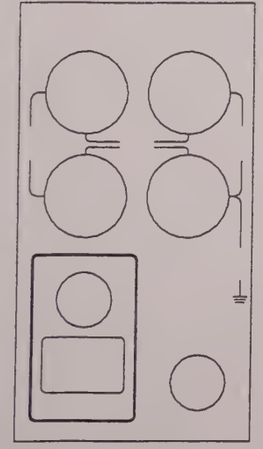
WARNING ***To ensure continued protection against electrical shock, verify that power line ground (green and yellow wire attached to the power module) is connected to the chassis. Also make certain that the two bottom case screws are properly installed to secure and ground the case cover to the chassis.***

NO. 2400-040

LTR	ECA NO.	REVISION	ENG	DATE
A	18139	RELEASED	SF	12/14/95

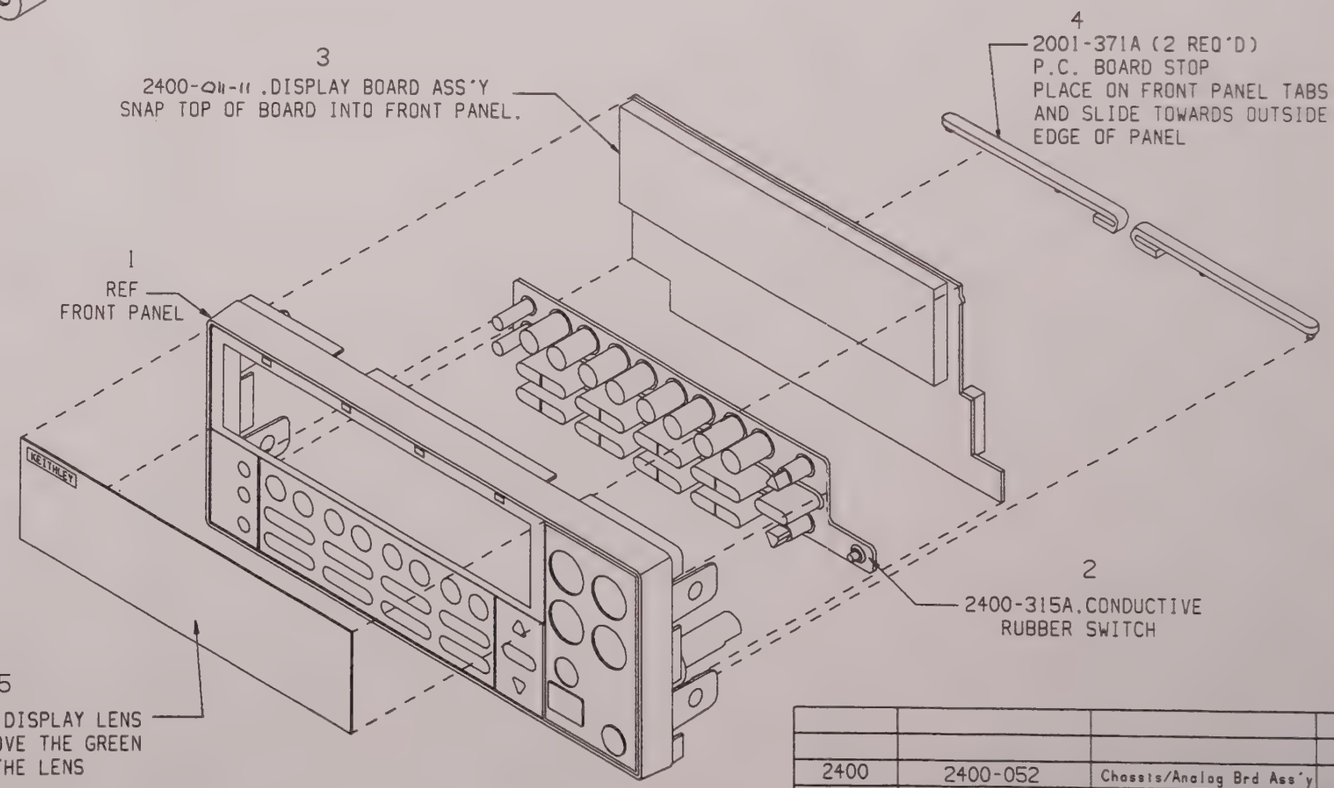
STEP 1





2400-313A. OVERLAY.
MEMBRANE SWITCH
(REF VIEW)

STEP 2



PART NO.	QTY	DESCRIPTION
2400-305A	1	FRONT PANEL
2400-011-11	1	DISPLAY BOARD ASSEMBLY
2400-313A	1	OVERLAY.MEMBRANE SWITCH
2400-311A	1	DISPLAY LENS
2400-315A	1	CONDUCTIVE RUBBER SWITCH
2001-371A	2	P.C. BD STOP
6517-309A	1	LENS. LED
2400-004	1	CRIMP ASSEMBLY

2400	2400-052	Chassis/Analog Brd Ass'y	1
MODEL	NEXT ASSEMBLY	NEXT PROCESS STEP	QTY
USED ON			

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XX = ±.015 ANG = ±1°
XXX = ±.005 FRAC = ±1/64
SURFACE MAX 63

DATE 10/5/95
DRN Mat
ENG APPR JAK
MATERIAL
FINISH

SCALE X

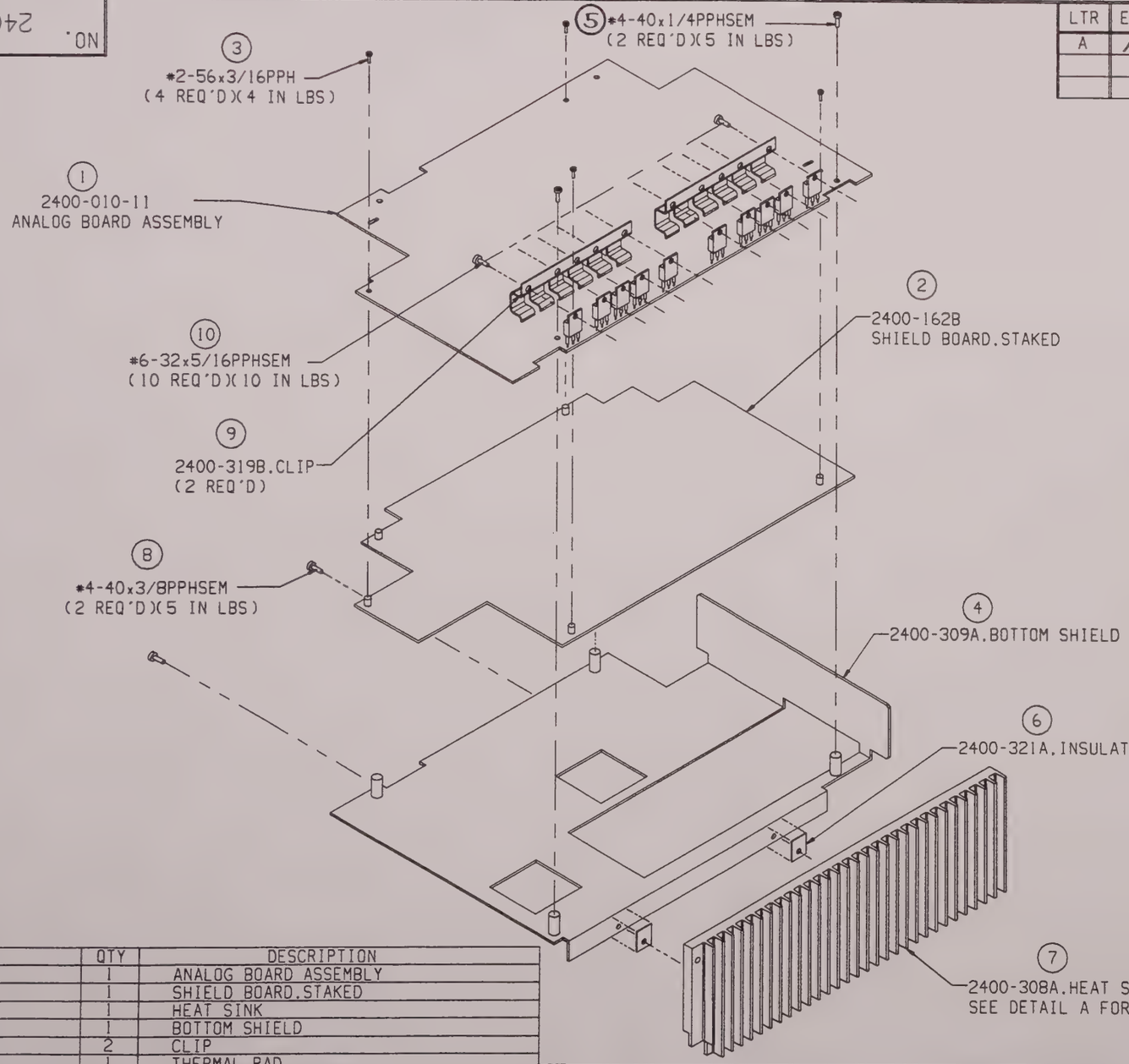
TITLE
FRONT PANEL ASSEMBLY OP6

B

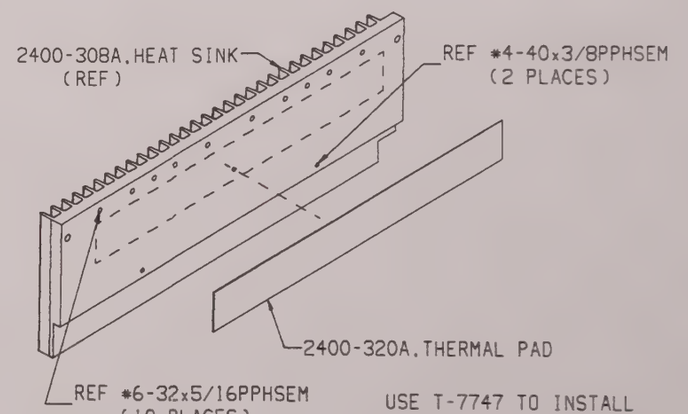
NO.
2400-040

NO. 2400-050

LTR	ECA NO.	REVISION	ENG	DATE
A	18134	Released	ST	12/14/95


③ *2-56x3/16PPH (4 REQ'D)(4 IN LBS)
⑤ *4-40x1/4PPHSEM (2 REQ'D)(5 IN LBS)
① 2400-010-11 ANALOG BOARD ASSEMBLY
② 2400-162B SHIELD BOARD.STAKED
⑩ *6-32x5/16PPHSEM (10 REQ'D)(10 IN LBS)
⑨ 2400-319B.CLIP (2 REQ'D)
⑧ *4-40x3/8PPHSEM (2 REQ'D)(5 IN LBS)
④ 2400-309A.BOTTOM SHIELD
⑥ 2400-321A.INSULATOR (2 REQ'D)
⑦ 2400-308A.HEAT SINK SEE DETAIL A FOR MOUNTING

DETAIL A



USE T-7747 TO INSTALL THERMAL PAD TO HEAT SINK

PART NUMBER	QTY	DESCRIPTION
2400-010-11	1	ANALOG BOARD ASSEMBLY
2400-162B	1	SHIELD BOARD.STAKED
2400-308A	1	HEAT SINK
2400-309A	1	BOTTOM SHIELD
2400-319B	2	CLIP
2400-320A	1	THERMAL PAD
2400-321A	2	INSULATOR
*2-56x3/16PPH	4	PHIL PAN HEAD SCREW
*4-40x1/4PPHSEM	2	PHIL PAN HEAD SEMS SCREW
*4-40x3/8PPHSEM	2	PHIL PAN HEAD SEMS SCREW
*6-32x5/16PPHSEM	10	PHIL PAN HEAD SEMS SCREW

2400	2400-052	Chassis/Analog Board Ass'y	1
MODEL	NEXT ASSEMBLY	NEXT PROCESS STEP	QTY

USED ON

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SURFACE MAX 63

DATE 10/5/95 SCALE .375

DRN mat ENG APPR

MATERIAL

FINISH

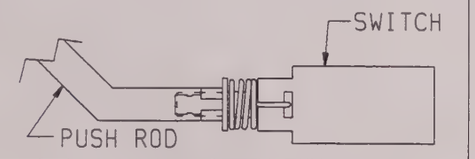
TITLE ANALOG BOARD/HEAT SINK/ SHIELD ASSEMBLY

B NO. 2400-050

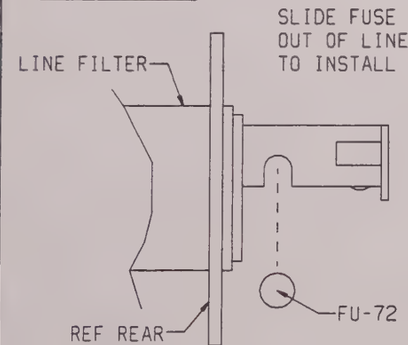
NO. 2400-051

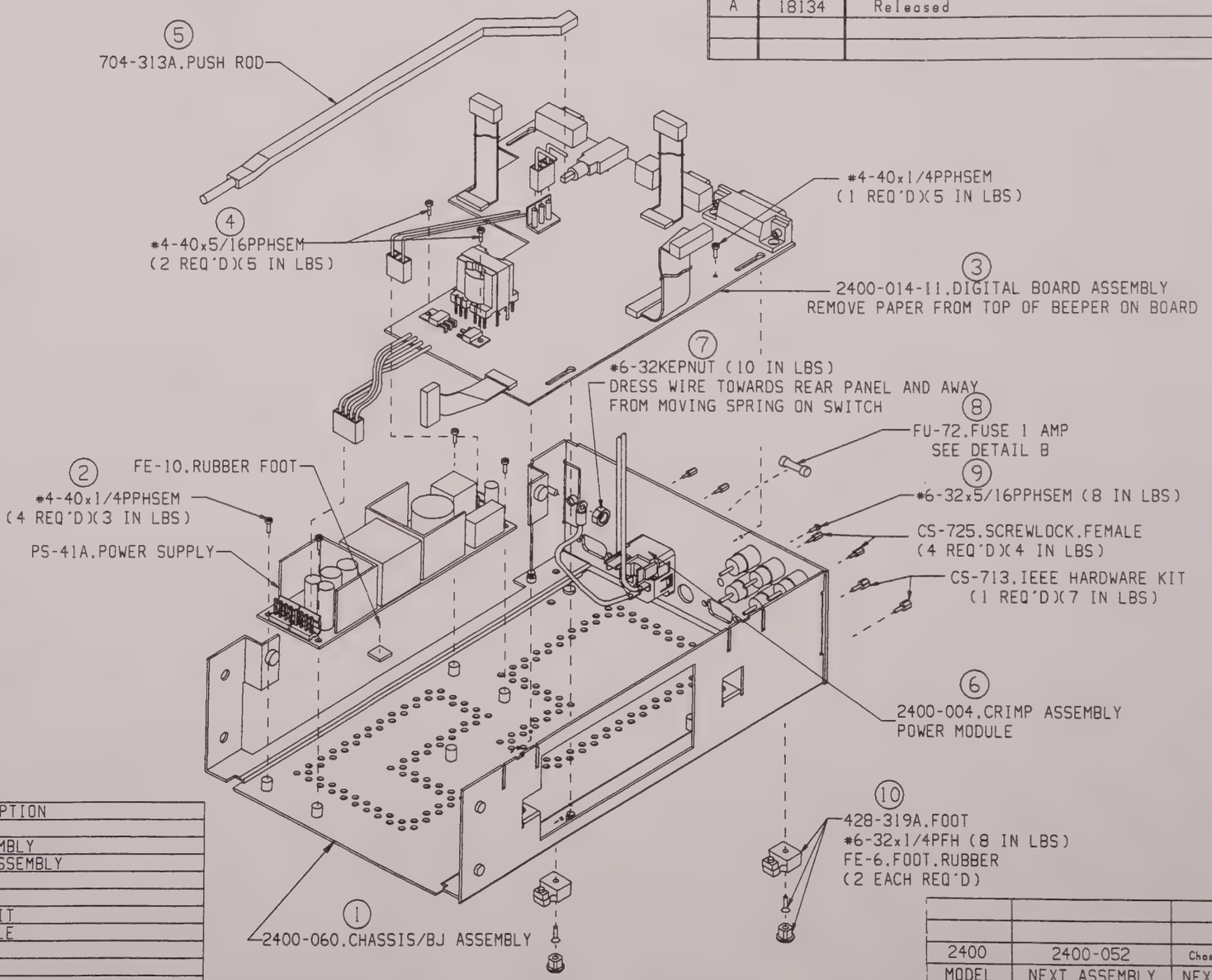
LTR	ECA NO.	REVISION	ENG	DATE
A	18134	Released	JAH	12/15/95

DETAIL A PROPERLY INSTALLED PUSH ROD



DETAIL B





PART NUMBER	QTY	DESCRIPTION
2400-004	1	CRIMP ASSEMBLY
2400-060	1	CHASSIS/BJ ASSEMBLY
2400-014-11	1	DIGITAL BOARD ASSEMBLY
428-319A	2	FOOT
704-313A	1	PUSH ROD
CS-713	1	IEEE HARDWARE KIT
CS-725	4	SCREWLOCK, FEMALE
FE-6	2	FOOT,RUBBER
FE-10	1	FOOT,RUBBER
FU-72	1	FUSE -- 1AMP
PS-41A	1	POWER SUPPLY
#4-40x1/4PPHSEM	5	PHIL PAN HEAD SEMS SCREW
#6-32KEPNUT	1	KEPNUT
#6-32x1/4PFH	2	PHIL FLAT HEAD SCREW
#6-32x5/16PPHSEM	1	PHIL FLAT HEAD SEMS SCREW
#4-40x5/16PPHSEM	2	PHIL PAN HEAD SEMS SCREW

2400	2400-052	Chassis/Analog Board Ass'y	1
MODEL	NEXT ASSEMBLY	NEXT PROCESS STEP	QTY
USED ON			

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SURFACE MAX 63

DATE 10/5/95 SCALE .375
DRN mat ENG APPR JAH
MATERIAL
FINISH

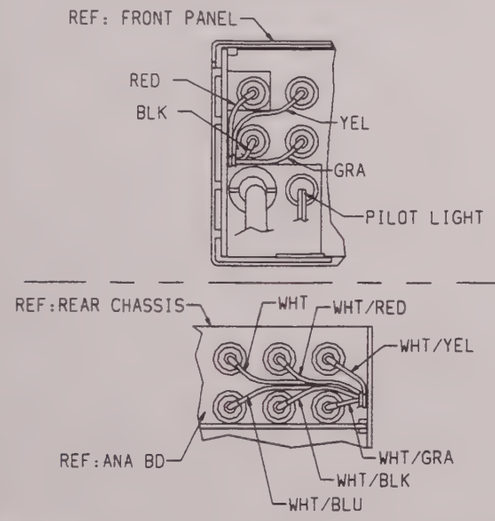
TITLE CHASSIS ASSEMBLY

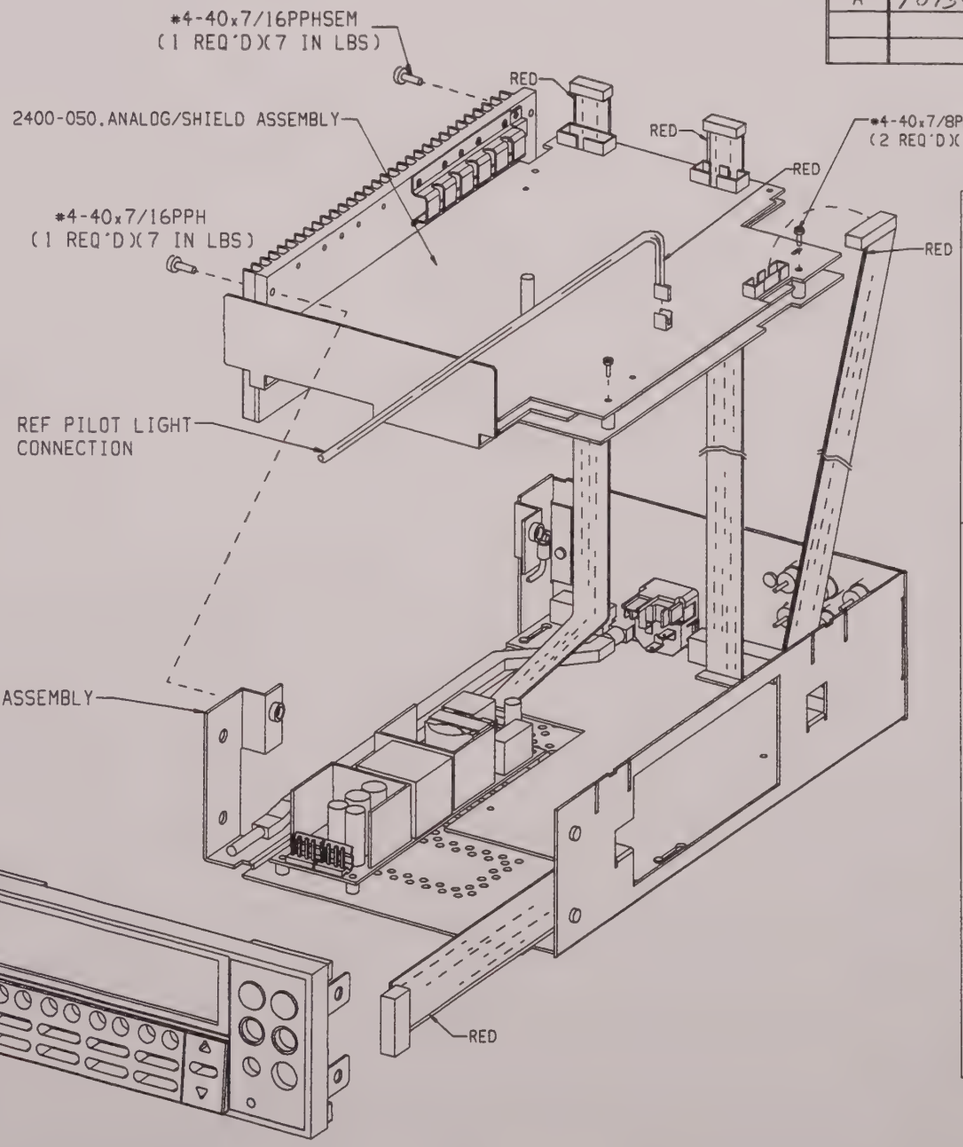
B NO. 2400-051

NO. 2400-052

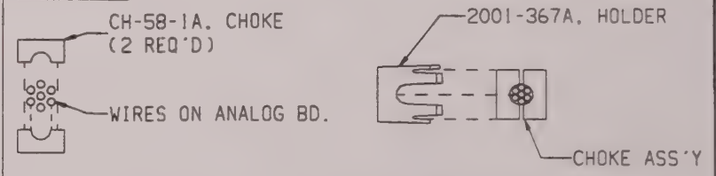
LTR	ECA NO.	REVISION	ENG	DATE
A	10134	Released	JSK	12/15/95

DETAIL A - BJ WIRING
(FRONT PANEL AND REAR CHASSIS)



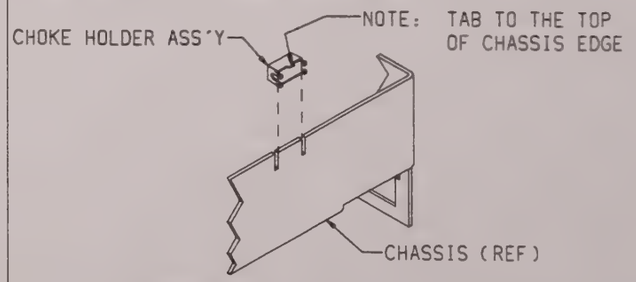


DETAIL "B"



PLACE ALL THE WIRES FOR THE REAR PANEL BETWEEN THE CHOKES.
SLIDE WIRE/CHOKE ASS'Y INTO THE HOLDER AS SHOWN.
DO THE SAME PROCESS FOR ALL THE WIRES TO THE FRONT PANEL.

SEE DETAIL "B" BEFORE INSTALLING



RECOMMENDED PROCESS:
CONNECT THE WHT/YEL AND WHT/GRA WIRES TO REAR PANEL BEFORE INSTALLING THE CHOKE HOLDER.
SLIDE THE BOTTOM LEG ON ONE SIDE OF HOLDER INTO THE CHASSIS. THEN SLIDE THE OTHER LEG INTO SLOT.
THEN SLIDE THE TOP LEGS INTO THE CHASSIS SLOTS BY SLIGHTLY PRESSING INWARD.

PART NUMBER	QTY	DESCRIPTION
2400-040	1	FRONT PANEL ASSEMBLY
2400-050	1	ANALOG BOARD/SHIELD ASSEMBLY
2400-051	1	CHASSIS ASSEMBLY
#4-40x7/8PPH	2	PHIL PAN HEAD SCREW
CH-58-1A	4	CHOKE
2001-367A	2	HOLDER
#4-40x7/16PPHSEM	1	PHIL PAN HEAD SEM SCREW
#4-40x7/16PPH	1	PHIL PAN HEAD SCREW

2400	2400-053	Final Chassis Ass'y	1
MODEL	NEXT ASSEMBLY	NEXT PROCESS STEP	QTY
USED ON			

DO NOT SCALE THIS DRAWING

KEITHLEY Keithley Instruments Inc. Cleveland, Ohio 44139

DIMENSIONAL TOLERANCES UNLESS OTHERWISE SPECIFIED
XX = ±.015 ANG = ±1°
XXX = ±.005 FRAC = ±1/64
SURFACE MAX 63

DATE 10/5/95 SCALE .375
DRN mat ENG APPR JSK
MATERIAL
FINISH

TITLE
CHASSIS/ANALOG BOARD ASSEMBLY

B NO. 2400-052

NO. 2400-053

TEST PROCEDURE:

Press and hold THE SWEEP and SOURCE UP ARROW key on the 2400 Display Board while powering up the instrument. this will allow access to the Secret Menu which contains the BURN-IN mode.

After power sequence is complete. verify that the display shows:

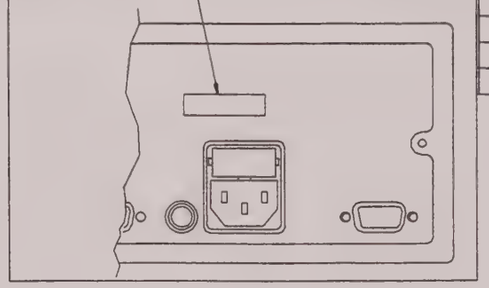
_ _ _ . _ _ _ uA OFF
Vsrc:+00.0000 V Cmpl:100.000 uA

Depress Key	Display
MENU	MAIN MENU "SAVESETUP" flashing
>arrow.4 times	"GENERAL" flashing
ENTER	GENERAL MENU "DIGOUT" flashing
>arrow.6 times	"SECRET" flashing
ENTER	SECRET MENU "INIT_BBRAM" flashing
>arrow.1 time	"DISP-BURN-IN" flashing
ENTER	ALL SEGMENTS ON

Power cycle unit and display will end up with all segments ON>.
The unit is in the BURN-IN mode.

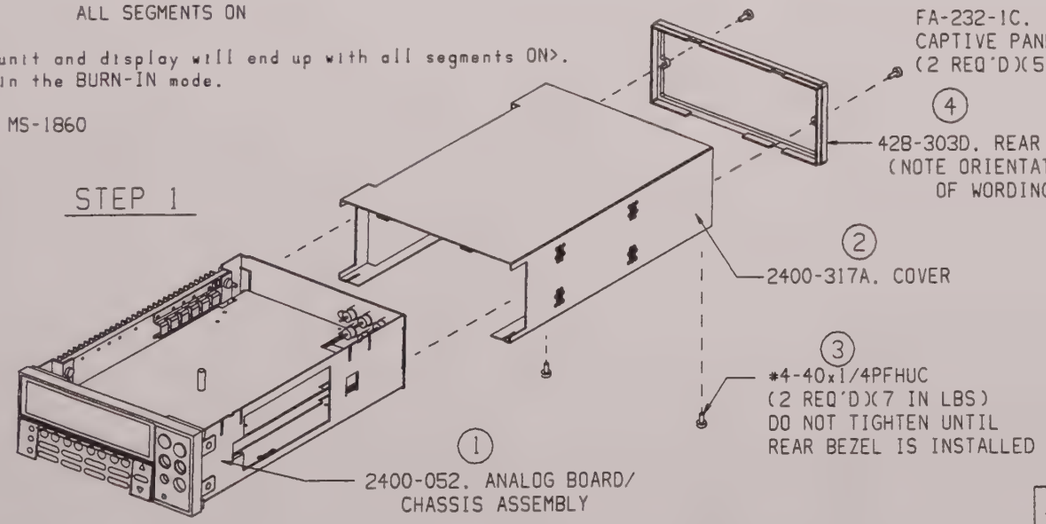
Age unit per MS-1860

DETAIL B

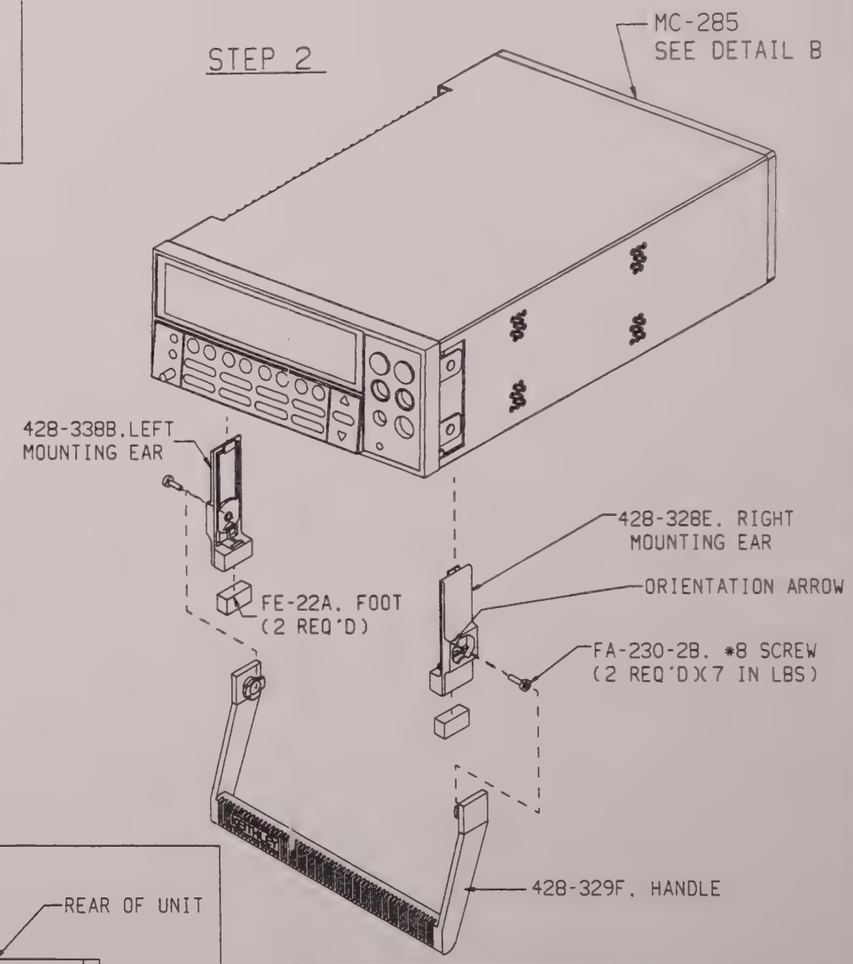


LTR	ECA NO.	REVISION	ENG	DATE
A	18134	Released	St	8/18/94

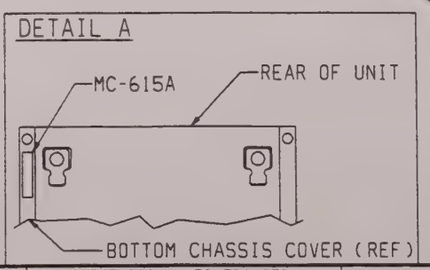
STEP 1



STEP 2



DETAIL A



PART NUMBER	QTY	DESCRIPTION
2400-052	1	ANALOG BOARD/CHASSIS ASSEMBLY
2400-317A	1	COVER
428-328E	1	MOUNTING EAR RIGHT
428-338B	1	MOUNTING EAR LEFT
FA-230-2B	2	FASTENER
FE-22A	2	FOOT
MC-615A	1	WARNING LABEL
#4-40x1/4"PFHUC	2	PHIL FLAT HD UNDERCUT SCREW
MC-285	1	SERIAL NUMBER
428-303D	1	REAR BEZEL
FA-232-1C	2	CAPTIVE PANEL SCREW
428-329F	1	HANDLE

2400	2400-080	FINAL INSPECTION	
2400	TECH	TECH	1
MODEL	NEXT ASSEMBLY	NEXT PROCESS STEP	QTY
USED ON			

DO NOT SCALE THIS DRAWING

DIMENSIONAL TOLERANCES UNLESS OTHERWISE SPECIFIED
XX ± .015 ANG ± 1°
XXX ± .005 FRAC ± 1/64
SURFACE MAX 63

DATE 10/11/95 SCALE X
DRN Mat ENG APPR JAH
MATERIAL X
FINISH X

KEITHLEY Keithley Instruments Inc. Cleveland, Ohio 44139

TITLE
FINAL CHASSIS ASSEMBLY - 0P6

B NO. 2400-053

6
Replaceable Parts

Introduction

This section contains replacement parts information and component layout drawings for the Model 2400.

Parts lists

The electrical parts lists for the Model 2400 are shown in tables at the end of this section. For part numbers to the various mechanical parts and assemblies, use the Miscellaneous parts list and the assembly drawings provided at the end of Section 5.

Ordering information

To place an order or to obtain information concerning replacement parts, contact your Keithley representative or the factory (see inside front cover for addresses). When ordering parts, be sure to include the following information:

- Instrument model number (Model 2400)
- Instrument serial number
- Part description
- Component designation (if applicable)
- Keithley part number

Factory service

If the instrument is to be returned to Keithley Instruments for repair, perform the following:

- Call the Repair Department at 1-800-552-1115 for a Return Material Authorization (RMA) number.
- Complete the service form at the back of this manual, and include it with the instrument.
- Carefully pack the instrument in the original packing carton.
- Write ATTENTION REPAIR DEPARTMENT and the RMA number on the shipping label.

Component layouts

The component layouts for the various circuit boards are provided on the following pages.

- Analog board — 2400-100
- Display board — 2400-110
- Digital board — 2400-140

Table 6-1
Analog board parts list

Circuit desig.	Description	Keithley part no.
C200-203,205-210,225,226,231,232, 237,238,242,243,248-255,258-261, 269-272,273-282,284-291,297-300, 524,525,530,531,542,548,549,554, 605-607,613,614,617-625,650-652, 659-662	CAP, .1UF, 10%, 25V, CERAMIC	C-495-.1
C204,404,550-553,608,609	CAP, .01UF, 10%, 50V CERAMIC	C-491-.01
C211-214	CAP, 1000PF, 10%, 50V, MONO CERAMIC	C-452-1000P
C215-222,611	CAP, 100PF, 5%, 100V, CERAMIC	C-465-100P
C223,224,227-230,233-236,239-240	CAP, 33PF, 5%, 100V, CERAMIC	C-465-33P
C241	CAP, 1000PF, 1%, 50V, CERAMIC	C-347-1000P
C244,245	CAP, .022UF, 10%, 50V CERAMIC	C-491-.022
C246,513	CAP, 560PF, 2.5%, 630V, POLYPROPYLENE	C-405-560P
C247,267,268	CAP, 1000P, 10%, 100V, CERAMIC	C-451-1000P
C256,257	CAP, 22PF, 10%, 100V, CERAMIC	C-451-22P
C283	CAP, .1UF, 20%, 50V, CERAMIC	C-418-.1
C301,302	CAP, 1000PF, 10%, 50V, MONO CERAMIC	C-452-1000P
C311	CAP, 100UF, 20%, 10V, ALUM ELEC	C-483-100
C312-319,329	CAP, 10PF, 5%, 100V, CERAMIC	C-372-10P
C320,323-326,603,604,615	CAP, 47P, 5%, 100V, CERAMIC	C-465-47P
C330	CAP, 100PF, 2.5%, 630V, POLYPROPYLENE	C-405-100P
C331-334	CAP, 100PF, 5%, 100V, CERAMIC	C-465-100P
C296,400,408	CAP, 270PF, 2.5%, 630V, POLYPROPYLENE	C-405-270P
C401,402	CAP, 10PF, .5%, 500V, POLYSTYRENE	C-405-10P
C405,406	CAP, .15UF, 20%, 50V, CERAMIC	C-418-.15
C407	CAP, 1UF, 20%, 35V, TANTALUM	C-494-1
C500-503	CAP, 4.7UF, 20%, 350V, ALUM ELEC	C-393-4.7
C504,505,534,535	CAP, 47UF, 20%, 100V ALUM ELEC	C-521-47
C512,514	CAP, 22PF, 10%, 100V, CERAMIC	C-451-22P
C515,541	CAP, .1UF, 20%, 50V, CERAMIC	C-418-.1
C522,523,526-529,532,533	CAP, 1000P, ±10%, 500V CERAMIC	C-497-1000P
C537,538	CAP, .1UF, 10%, 500V, X7R	C-525-.1
C539,540	CAP, 1UF, 20%, 50V, CERAMIC	C-519-1
C543	CAP, 10PF, 10%, 1000V, CERAMIC	C-64-10P
C544-547	CAP, 2200P, ±10%, 500V, CERAMIC	C-497-2200P
C610,612	CAP, 2200P, 10%, 100V, CERAMIC	C-430-2200P
C616	CAP, 22UF, 20%, 25V, TANTALUM	C-440-22

Table 6-1 (cont.)
Analog board parts list

Circuit desig.	Description	Keithley part no.
CR200-203,205,207,208,210,212,213, 216,221,235,236,602	DIODE, SWITCHING, MMBD914	RF-83
CR204,206,209,211,222-225, 230-233, 400,401,502-504	DIODE, IN3595	RF-43
CR236,602,212,213	ULTRAFAST POWER RECTIFIER	RF-105
CR237	DIODE, DUAL SWITCHING, BAV99L	RF-82
CR500-503	ULTRAFAST POWER RECTIFIER	RF-107
CR508-511,520,521	DIODE, CONTROLLED AVALANCHE, BYD17GSO	RF-91
CR512,513	DIODE ZENER 12V, MMSZ11T1	DZ-112
CR517,519	ULTRAFAST POWER RECTIFIER	RF-106
CR600,238	DIODE, DUAL HSM-2822T31	RF-95
CR601	DIODE, SCHOTTKY, BAT42	RF-78
J1001	CONN, HEADER STRAIGHT SOLDER PIN	CS-368-10
J1002	CONN, HEADER STRAIGHT SOLDER PIN	CS-368-16
J1003	CONNECTOR, HEADER STRAIGHT SOLDER PIN	CS-368-14
J1034	LATCHING HEADER, FRICTON, SGL ROW	CS-724-3
K200-205	N.C RELAY, 1 FORMB, AQV214S	RL-176
K206	RELAY, REED, HI-VOLT/ISOLATION	RL-152
K207,208	RELAY, MINI SIGNAL REL	RL-163
K211	RELAY, SURFACE MOUNT	RL-188
L201	COIL	CH-72-1
L600,601,602	FERRITE CHIP 600 OHM BLM32A07	CH-62
L603	FERRITE CHIP 600 OHM BLM32A07	CH-62
Q200-207,240,241	TRANS, N CHANNEL JFET, SNJ132199	TG-294
Q208,210,212,214,216,218	TRANS, NPN CATV SILICON, MPSH17	TG-221
Q209,211,213,215,217,219	TRANS, CURRENT REGULATOR, CR430	TG-219
Q220,225	TRANS, NPN SILICON, MJE340	TG-209
Q221,226	TRANS, PNP POWER, MJE350	TG-210
Q222,224	TRANS, N-CHAN JFET, SST4393	TG-263
Q234-239,244-246,255,256,400,401, 404	TRANS, N-MOSFET, VN0605T	TG-243
Q242,243	TRANS, N-CHAN MOSFET, TN254ON8	TG-274
Q402,409	TRANS, N-CHAN DMOS FET TN2504N8	TG-261
Q403,406,407,408	TRANS, N-CHAN JFET, SST109	TG-266
Q223,405,410,411,602-607	TRANS, N-MOSFET, VN0605T	TG-243
Q412,414	TRANS, N-MEGAFET, RFD 14N05LSM	TG-267

Table 6-1 (cont.)
Analog board parts list

Circuit desig.	Description	Keithley part no.
Q413	TRANS, P-CHAN, MOSFET, TP0610T	TG-259
Q415	TRANS, P-FET, MTP20P06	TG-229
Q500,502,514,516	TRANS, N-CHANNEL FET, IRF630	TG-214
Q501,503,505,508,510,512,513,528	TRANS, NPN, MMBT3904	TG-238
Q504	TRANS, NPN TIP48	TG-314
Q506,520,601,529	TRANS, PNP, MMBT3906L	TG-244
Q507	TRANS, PMP, MJE5731A	TG-315
Q509,511,523,525	TRANS, P-CHANNEL 200V FET, IRF9630	TG-215
Q515,517,519,522,524,600	TRANS, NPN, MMBT3904	TG-238
Q518	TRANS, NPN DARLINGTON, TIP101	TG-230
Q521	TRANS, PNP DARLINGTON, TIP106	TG-231
Q526,527	N CHANNEL ENHANCED MOSFET	TG-302
R117-128,133-136,137-149	RES, 10K, 5%, 250MW, METAL FILM	R-376-10K
R150-153,336,340,343,353,355,361, 362,365,369,389,390,466,472,478,480, 481,520,552	RES, 1K, 1%, 100MW, THICK FILM	R-418-1K
R200,201,203,232,238	RESISTOR NETWORK	TF-236
R202,204,252,255,256,259,260,263, 264,267,293-296,338,364,402-404, 416,417,459,488	RES, 100K, 1%, 100MW THICK FILM	R-418-100K
R205,210	RES, 768, 1%, 100MW, THICK FILM	R-418-768
R207	RES, 8.87K, 1%, 100MW, THICK FILM	R-418-8.87K
R209,211,268-271	RES, 1M, 1%, 100MW, THICK FILM	R-418-1M
R212	RES, 332, 1%, 100MW, THICK FILM	R-418-332
R213	RES, NET 5K, .1%, 668A	TF-243-5K
R205,214,215,290,485,486	RES, .0499, 1%, 100MW, THICK FILM	R-418-.0499
R216,221,223,274-279,289,303	RES, 20K, 1%, 100MW, THICK FILM	R-418-20K
R217	RES, 121K, 1%,100MW, THICK FILM	R-418-121K
R218	RES, 80.6K, 1%, 100MW, THICK FILM	R-418-80.6K
R219,220,222,230,231,345,373,482, 483	RES, 49.9K, 1%, 100MW, THICK FILM	R-418-49.9K
R224-229,234-237,244-247,281,282, 284-286,288,301,617,622,654,655	RES, 10K, 1%, 100MW, THICK FILM	R-418-10K
R240,243,248,251,253,254,257,258, 261,262,265,266,313,314-317,357, 366,601,608,626	RES, 4.99K, 1%, 100MW THICK FILM	R-418-4.99K
R241,242,249,250,653,664	RES, 140K, 1%, 100MW THICK FILM	R-418-140K
R272,273	RES, 249K, 1%, 100MW, THICK FILM	R-418-249K
R280	RES,4.02K,1%,100MW, THICK FILM	R-418-4.02K
R283,287,297,299,349,350-352,457, 461	RES, 30.1K, 1%, 100MW, THICK FILM	R-418-30.1K

Table 6-1 (cont.)
Analog board parts list

Circuit desig.	Description	Keithley part no.
R291	RES, 45.3K, 1%, 100MW, THICK FILM	R-418-45.3K
R292,544-547	RES, 100K, 1%, 100MW THICK FILM	R-418-100K
R298,300	RES, 150K, 1%, 100MW, THICK FILM	R-418-150K
R302,310,375,376	RES, .0499, 1%, 100MW, THICK FILM	R-418-.0499
R304-306,548	RES, 33, 5%, 250mW, METAL FILM	R-376-33
R307,388,393-399,411,412,413	RES, 357, 1%, 100MW, THICK FILM	R-418-357
R308,379-387,391,392	RES, 475, 1%, 100MW, THICK FILM	R-418-475
R309,504,511	RES, 10K, 1%, 100MW, THICK FILM	R-418-10K
R332,423,604,606	RES, 499, 1%, 100MW, THICK FILM	R-418-499
R346	RES, 357K, 1%, 100MW, THICK FILM	R-418-357K
R347	RES, 332K, 1%, 100MW, THICK FILM	R-418-332K
R348	RES, 255K, 1%, 100MW, THICK FILM	R-418-255K
R354	RES, 1M, 5%, 250MW, METAL FILM	R-376-1M
R356,359,418-421,456,458,460,462, 464,489	RES, 1K, 1%, 100MW, THICK FILM	R-418-1K
R358	RES, 3.01K, 1%, 100MW, THICK FILM	R-418-3.01K
R363	THICK FILM	TF-253
R367,424,425,426,484,487,603,605	RES, 4.99K, 1%, 100MW, THICK FIL	R-418-4.99K
R368	RES, 332, 1%, 100MW, THICK FILM	R-418-332
R374	RES, 49.9K, 1%, 100MW, THICK FILM	R-418-49.9K
R377,378	RES, 6.65K, 1%, 125MW, METAL FILM	R-391-6.65K
R450	RES, 2.0M, .1%, 1/4W, METAL FILM	R-321-2M
R451	RES, 221K, 1%, 1/10W, METAL FILM	R-263-221K
R452	RES, 20K, .5%, 1/8W, METAL FILM	R-351-20K
R453	RES, 2K, 1%, 1/2W, METAL FILM	R-348-2K
R454,455,467-471	RES, 100, .1%, 1/10W, METAL FILM	R-263-100
R463,465,473	RES, 30.1K, 1%, 100MW, THICK FILM	R-418-30.1K
R474-477	RES, .2, 1%, 1W	R-441-.2
R479	RES, 249, 1%, 100MW, THICK FILM	R-418-249
R500,502,513,515,527,528,533,535	RES, 576K, 1%, 100MW, THICK FILM	R-418-576K
R501,503,512,514,529,530,532,534	RES, 249, 1%, 100MW, THICK FILM	R-418-249
R505,510,536,537,550,551	RES, 499, 1%, 100MW THICK FILM	R-418-499
R506-509,521,525,526,549	RES, 10, 10%, 100MW, THICK FILM	R-418-10
R516,523,531	RES, 4.02K, 1%,100MW, THICK FILM	R-418-4.02K
R517,524,538-541	RES, 12.1, 1%, 125MW, METAL FILM	R-391-12.1
R542,543	RES, .5, 5%, 1W, METAL	R-444-.5
R553,554	RES, 2.21K, 1%, 100MW, THICK FILM	R-418-2.21K
R555	RES, 8,98K, .1%, .125W, THIN FILM	R-456-8.98K
R556	RES, 42.7K, .1%, .125W, THIN FILM	R-456-42.7K
R557	RES, 17.2K, .1%, .125W, THIN FILM	R-456-17.2K

Table 6-1 (cont.)
Analog board parts list

Circuit desig.	Description	Keithley part no.
R600,370-372	RES, 100K, 1%, 100MW THICK FILM	R-418-100K
R602,607	RES, 1.5K, 1%, 100MW THICK FILM	R-418-1.5K
R609	RES NET	TF-245
R610	RES, 1.28M, .1%, 1/8W METAL FILM	R-176-1.28M
R611,621	RES, 475, 1%, 100MW, THICK FILM	R-418-475
R612	RES, 5.11K, 1%, 100MW, THICK FILM	R-418-5.11K
R613,624,659,660	RES, 100, 1%, 100MW, THICK FILM	R-418-100
R208,614,615	RES, 2.21K, 1%, 100MW, THICK FILM	R-418-2.21K
R618	RES, 34K, 1%, 100MW, THICK FILM	R-418-34K
R619	RES, 4.75K, 1%, 100MW, THICK FILM	R-418-4.75K
R620	RES, 82.5, 1%, 100MW, THICK FILM	R-418-82.5
R623	RES, 10, 10%, 100MW, THICK FILM	R-418-10
R650,651	RES NET, 9K-1K, MICRO DIVIDER	TF-246-2
R652,665	RES, 357, 1%, 100MW, THICK FILM	R-418-357
R656	RES, 10M, 1%, 125MW, THICK FILM	R-418-10M
R657,658	RES, 1M, 1%, 100MW, THICK FILM	R-418-1M
R666	RES NET, 3K, 12K, 0.1%, 100MW THINFILM	TF-237-2
RT200	POLYSWITCH, PTC RESISTOR	RT-17
T500	TRANSFORMER FOR 0 SUPPLIES	TR-303A
TP200-215,218-225,227,228,230-235, 500-510	CONN,TEST POINT	CS-553
U201,212,214,230,241,400-406,652	IC, CMOS ANAL SWITCH, DG444D	IC-866
U202,203,650	IC, OP AMP LT1112	IC-1048
U204,229	IC, 8-CHAN ANA MULTIPLEXER,DG408D	IC-844
U205,407	IC, HEX INVERTERS, 74HCT04	IC-880
U209,215	IC, QUAD COMPARATOR,LM339D	IC-774
U210,220	IC, DUAL BIPOLAR OP-AMP, LT1124CS8	IC-955
U221,227	IC, DIFF. AMP, AMP03GP	IC-988
U222	IC, OP-AMP, LTC1050CS8	IC-791
U223,409	IC, MOSFET DRIVER, TLP591B	IC-877
U228	IC, OP-AMP, LOW NOISE LT1007CS8	IC-949
U219,231,235	IC, OP AMP, LOW POWER AD795JR	IC-1052
U234	IC, OP-AMP OPA602	IC-1049
U238	IC, CMOS ANA SWITCH SPST MAX326CSE	IC-909
U239	IC, QUAD 2-INPUT NAND, 74HC00M	IC-781
U240	IC,POS NAND GATES/INVERT,74HCT14	IC-656
U242-247	IC,DUAL HIGH CMR/SPEED OPTO,HCPL-26	IC-588

Table 6-1 (cont.)
Analog board parts list

Circuit desig.	Description	Keithley part no.
U252-256	IC, 8 STAGE SHIFT CD74HC4094M	IC-1026
U257	IC, SUPPLY VOLT SUPERVISOR, TL7705A	IC-860
U262,263,226,659	IC, 20V OP-AMP, LT1097S8	IC-767
U211,213,216,218,225,233,408	IC, M DUAL J-FET OP-AMP, OP-282GS	IC-968
U500	IC, OP-AMP, AD847JN	IC-890
U501	IC, VOLT COMPARATOR LM393	IC-775
U502	PROGRAMMABLE TEMP CONTROLLER	IC-1062
U206-208,264,600	IC, DUAL PICOAMP OP-AMP AD706JR	IC-910
U601	IC, QUAD D FLIP FLOP W/CLK, RESET 7474	IC-923
U604	IC, NCHAN LAT DMOS QUADFET,SD5400CY	IC-893
U605	INTEGRATED CIRCUIT, OPA177GS	IC-960
U606,236	IC, HI-SPEED BIFET OP-AMP, AD711JR	IC-894
U607	IC, OP-AMP, NE5534D	IC-802
U608	IC, VOLT. COMPARATOR, LM311M	IC-776
U224,602,603,651	IC, QUAD 2 IN NOR, 74HCT02	IC-809
U660,661	IC, 16 BIT DAC, AD7849BR	IC-1004
VR200,201	DIODE, ZENER 11V, MMSZ11T1	DZ-103
VR214,215	DIODE, ZENER, 8.2V, MMBZ5237	DZ-92
VR216,217	DIODE, ZENER 17V, MMBZ5247BL	DZ-104
VR400,401	DIODE, ZENER 4.7V, IN4732A	DZ-67
VR403,601,604	DIODE, ZENER 3.3V, MMBZ5226BL	DZ-94
VR404-406	DIODE, ZENER 5.1V, BZX84C5V1	DZ-88
VR500,501	DIODE, ZENER 6.0V, BZX84B6V2	DZ-87
VR600	DIODE, ZENER 6.4V, IN4579	DZ-73
VR602,603	DIODE, ZENER, 6.2V MMSZ6V2	DZ-97
W401	JUMPER	J-15
Y600	OSCILLATOR HIGH SPEED CMOS 12MHZ	CR-37

Table 6-2
Digital board parts list

Circuit desig.	Description	Keithley part no.
BH1	BATTERY HOLDER	BH-34
BT1	BATTERY, LITHIUM-MANGANESE CELL 3V	BA-44
C1,3,6-9,11-14,16-20,22,23,25,26,30, 36,37,39,41,44-46,49,59,66-70,73, 76-84,85	CAP, .1UF, 10%, 25V, CERAMIC	C-495-.1
C2,56	CAP, .01UF, 10%, 50V CERAMIC	C-491-.01
C4,10	CAP, 15P, 1%, 100V CERAMIC	C-512-15P
C5	CAP, .1UF, 20%, 100V, CERAMIC	C-436-.1
C15,28,38,47,60,61	CAP, 47P, 5%, 100V, CERAMIC	C-465-47P
C21,27,29,51,72,86	CAP, 1UF, 20%, 50V CERAMIC	C-519-1
C31	CAP, 100PF, 5%, 100V, CERAMIC	C-465-100P
C32,34,63,64	CAP, 47UF, 20%, 100V ALUM ELEC	C-521-47
C33,35,52-55	CAP, 22UF, 20%, 25V, TANTALUM	C-440-22
C48,57,58	CAP, 1000PF, 10%, 50V, MONO CERAMIC	C-452-1000P
C62	CAP, 10UF, 20%, 25V, TANTALUM	C-440-10
C65	CAP, .022UF, 10%, 50V CERAMIC	C-491-.022
C74,75	CAP, 470UF, 20%, 25V ALUM ELEC	C-413-470
CR1-4,7,10,16,18	ULTRAFAST POWER RECTIFIER	RF-107
CR6,9,12,20	ULTRAFAST POWER RECTIFIER	RF-105
CR8,11,17,19,21,25-28,31	DIODE, SWITCHING, 250MA,BAV103	RF-89
CR13	DIODE, DUAL HSM-2822T31	RF-95
CR5,14,15,22-24,32,33	DIODE, DUAL SWITCHING, BAV99L	RF-82
CR29,30	DIODE, SWITCHING, MMBD914	RF-83
F1	POLYSWITCH, SMD030-2	FU-103
HS1,2,3	HEAT SINK	HS-33
IC1	IC, POS VOLTAGE REG +15V, 500MA, 7815	IC-194
J1	CONN, RIGHT ANGLE, 24PIN	CS-507
J3	CONN, RT ANGLE, MALE, 9 PIN	CS-761-9
J5	CONN, CIRCULAR DIN	CS-762
J6	CONN, D-SUB MALE, BOARDLOCK TYPE	CS-848-9
J21	CONN, MOLEX, 3-PIN	CS-772-3
L1	FERRITE CHIP 600 OHM BLM32A07	CH-62

Table 6-2 (cont.)
Digital board parts list

Circuit desig.	Description	Keithley part no.
LS1	BEEPER, 5V, 30MA, QMX-05	EM-6
P1001	CABLE ASSEMBLY	CA-152-1
P1002	CABLE ASSEMBLY	CA-151-1
P1003	CABLE ASSEMBLY	CA-32-9B
P1004	CABLE ASSEMBLY	CA-62-4A
Q1-6	TRANS, N-MOSFET, VN0605T	TG-243
Q7,8	POWER MOSFET IRFZ346	TG-313
Q10	TRANS, NPN, MMBT3904	TG-238
R1,37,43,44,45,65	RES, 2.21K, 1%, 100MW, THICK FILM	R-418-2.21K
R2,4,6,7,13,14,19,34,35,41,47,50,52, 58,60,63,68,69,71,73-81,83,84,85-89	RES, 10K, 1%, 100MW, THICK FILM	R-418-10K
R3	RES, 10, 10%, 100MW, THICK FILM	R-418-10
R5,55	RES, 10M, 1%, 125MW, THICK FILM	R-418-10M
R9,11,12,16,20	RES, 100, 5%, 250MW, METAL FILM	R-376-100
R10	RES, 332K, 1%, 100MW, THICK FILM	R-418-332K
R15,17,18,21,23,31,48,59,61,64,70,72	RES, 1K, 1%, 100MW, THICK FILM	R-418-1K
R25,28,49	RES, 4.75K, 1%, 100MW, THICK FILM	R-418-4.75K
R29,39,46	RES, .0499, 1%, 100MW, THICK FILM	R-418-.0499
R30,26	RES, 100, 1%, 100MW, THICK FILM	R-418-100
R38	RES, 14K, 1%, 125mW, METAL FILM	R-391-14K
R24,27,32,40	RES, 5.1K, 5%, 125MW, METAL FILM	R-375-5.1K
R51	RES, 4.75K, 1%, 125mW, METAL FILM	R-391-4.75K
R53,54,56	RES, 3.01K, 1%, 100MW THICK FILM	R-418-3.01K
R57	RES, 1M, 1%, 100MW, THICK FILM	R-418-1M
R77	RES, 15k, 1%, 100MW, THICK FILM	R-418-15K
R82	RES, 499, 1%, 100MW THICK FILM	R-418-499
R91,92	RES, 200, 1%, 100MW, THICK FILM	R-418-200
S01,2	SOCKET PLCC-032-T-A	SO-143-32
S1	SWITCH, PUSHBUTTON (6 POLE)	SW-466
T1	TRANSFORMER FOR F SUPPLIES	TR-302A
TP1-9	CONN, TEST POINT	CS-553
U1,22	IC, DUAL D-TYPE F/F, 74HC74	IC-773
U2	IC, MICROMANAGER, DS12365-10	IC-884
U3	MICROCONTROLLER, MC68332-FC	LSI-161
U4	IC +5V RS-232 TRANSCEIVER, MAX202	IC-952

Table 6-2 (cont.)
Digital board parts list

Circuit desig.	Description	Keithley part no.
U5	IC, OP-AMP, AD705JR	IC-814
U6	IC,OCTAL INTER BUS TRANS, 75161	IC-647
U7	IC, 4-CHANNEL PWR DRIVER, 2549B	IC-1044
U8	IC, NEG VOLTAGE REG -15V, 500MA, 79M15	IC-195
U9	IC, HEX INVERTERS, 74HCT04	IC-880
U11	IC, VOLT COMPARATOR LM393D	IC-775
U12,14	LARGE SCALE IC	LSI-162-70
U13	IC, GPIB ADAPTER, 9914A	LSI-123
U15	PROGRAMMED ROM	2400-803-*
U16	PROGRAMMED ROM	2400-804-*
U17	IC, SERIAL EPROM 24LC16B	LSI-153
U18	IC, +5V VOLTAGE REGULATOR, LM2940CT	IC-576
U19	IC, SCHMITT-TRIGGER NAND GATE	IC-950
U20	IC, OCTAL INTERFACE BUS, 75160	IC-646
U21	IC, DUAL POWER MOSFET DRIVER, TSC42	IC-437
U23,25	IC, POS NAND GATES/INVERT, 74HCT14	IC-656
U24	IC,TRIPLE 3 IN NAND, 74F10	IC-659
VR1	DIODE, ZENER 33V, IN4752A	DZ-68
Y1	CRYSTAL, FSM327	CR-41

* Order current firmware revision level.

Table 6-3
Display board parts list

Circuit desig.	Description	Keithley part no.
C901	CAP, 22UF, 20%, 6.3,TANTALUM	C-417-22
C902,904,907,908,910	CAP, .1UF, 20%, 100V, CERAMIC	C-436-.1
C903,905,906,909,911	CAP, .1UF, 20%, 50V, CERAMIC	C-418-.1
C912	CAP, 2.2UF, 20%,100V, ALUM ELEC	C-503-2.2
C913,914	CAP, 100UF, 20%, 16V, TANTALUM	C-504-100
C915,916	CAP, 33PF, 10%, 100V, CERAMIC	C-451-33P
CR901-904	DIODE, SWITCHING, 250MA, BAV103	RF-89
CR905,906	DIODE, SWITCHING, MMBD914	RF-83
DS901	VACUUM FLUORESCENT DISPLAY	DD-51C
J1032	CONN, 3 PIN	CS-339-3
J1033	CONN, HEADER STRAIGHT SOLDER PIN	CS-368-16
Q901,902	TRANS, NPN GEN PURPOSE BC868	TG-293
R901	RES NET, 15K, 2%, 1.875W	TF-219-15K
R902	RES, 13K, 5%,125MW, METAL FILM	R-375-13K
R903,904	RES, 4.7K, 5%, 250MW, METAL FILM	R-376-4.7K
R905	RES, 1M, 5%, 125MW, METAL FILM	R-375-1M
R906	RES, 1K, 5% 250MW, METAL FILM	R-376-1K
R907	RES, 240, 5%, 250MW, METAL FILM	R-376-240
R908	RES, 10M, 5%, 125MW, METAL FILM	R-375-10M
T901	TRANSFORMER, TDK, ER14.5 SERIES	TR-300
U901,904,905	IC, LATCHED DRIVERS, UCN-5812EPF-1	IC-732
U902	PROGRAMMED ROM	7001-800-*
U903	IC, 32-BIT, SERIAL UCN5818EPF-1	IC-830
VR901	DIODE, ZENER, 8.2V, MMBZ5237	DZ-92
Y901	CRYSTAL, 4MHZ	CR-36-4M

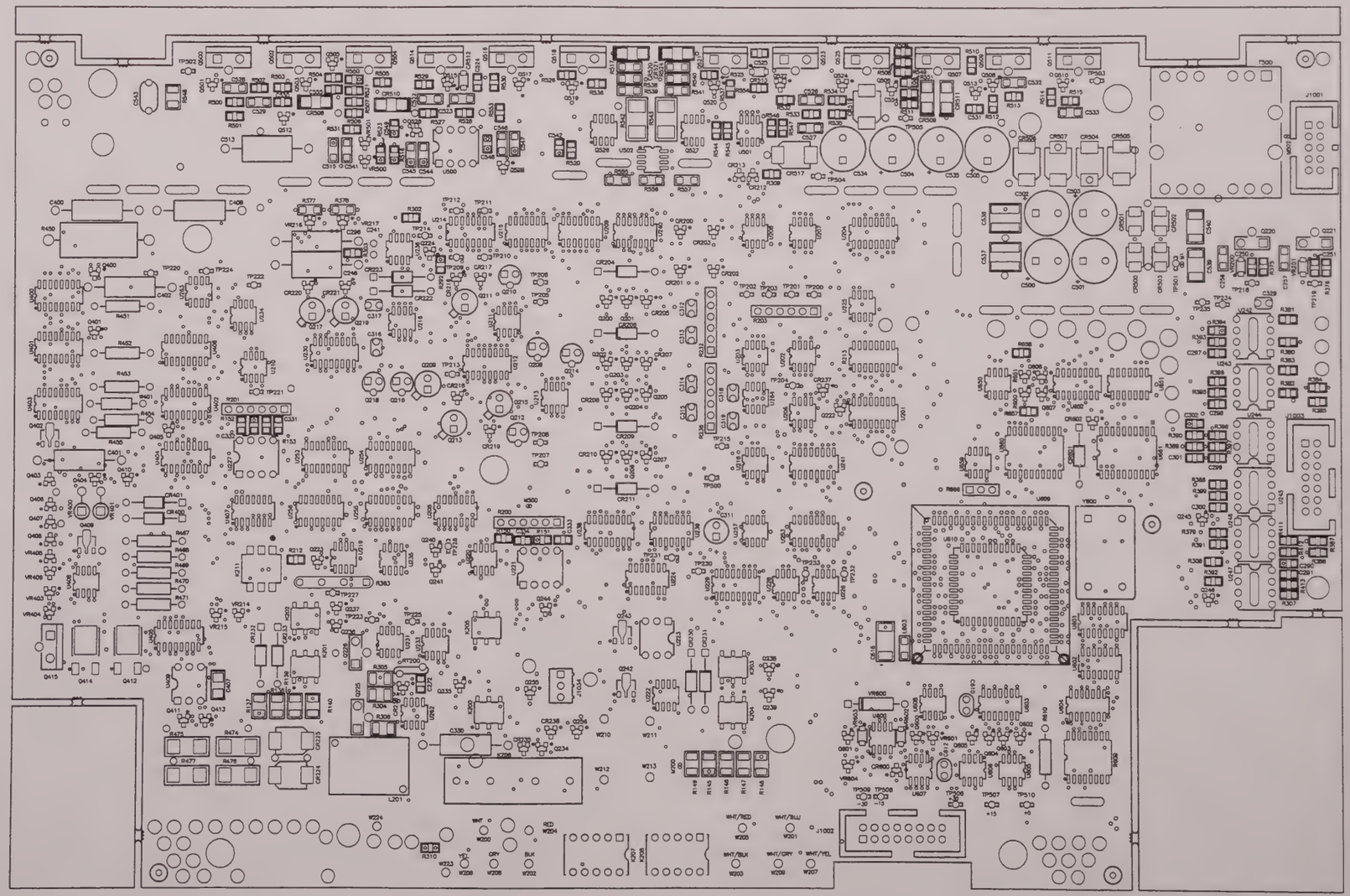
* Order current firmware revision level.

Table 6-4
Mechanical parts list

Quantity	Description	Keithley part no.
4	BLACK BANANA JACK	BJ-13-0
1	BLUE BANANA JACK	BJ-13-6
1	BOTTOM SHIELD	2400-309A
2	FOOT, EXTRUDED	FE-22A
2	FOOT, RUBBER	FE-6
1	FUSE, 1A, SLOW BLOW, 5 X 20MM	FU-72
1	HANDLE	428-329F
1	HEAT SINK	2400-308A
1	LEFT MOUNTING EAR	428-338B
1	LINE CORD	CO-7
1	LINE FILTER	LF-11
1	MEMBRANE SWITCH, FRONT PANEL	2400-313A
1	POWER ROD	704-313A
1	POWER SUPPLY	PS-41A
1	REAR BEZEL	428-303D
4	RED BANANA JACK	BJ-13-2
1	RIGHT MOUNTING EAR	428-328E
1	SWITCHPAD	2400-315A
1	TEST LEADS	CA-22
1	WHITE BANANA JACK	BJ-13-9

NO. 2400-100

LTR.	ECA NO.	REVISION	ENG.	DATE
A		PRELIMINARY		
B		PRELIMINARY		
C	17917	RELEASED		11-27-95



NOTE: FOR COMPONENT INFORMATION SEE PRODUCT STRUCTURE.

MODEL	NEXT ASSEMBLY	QTY.
USED ON		

KEITHLEY

KEITHLEY INSTRUMENTS INC.
CLEVELAND, OHIO 44139

DIM ARE IN IN. UNLESS OTHERWISE NOTED
DIM. TOL. UNLESS OTHERWISE SPECIFIED
XX=+.01 ANG.=+1
XXX=+.005 FRAC.=+1/64
DO NOT SCALE THIS DRAWING

DATE 3/6/95 SCALE 5:4
DRN KEK APPR. JN

TITLE COMPONENT LAYOUT DRAWING
2400 SMU
ANALOG BOARD

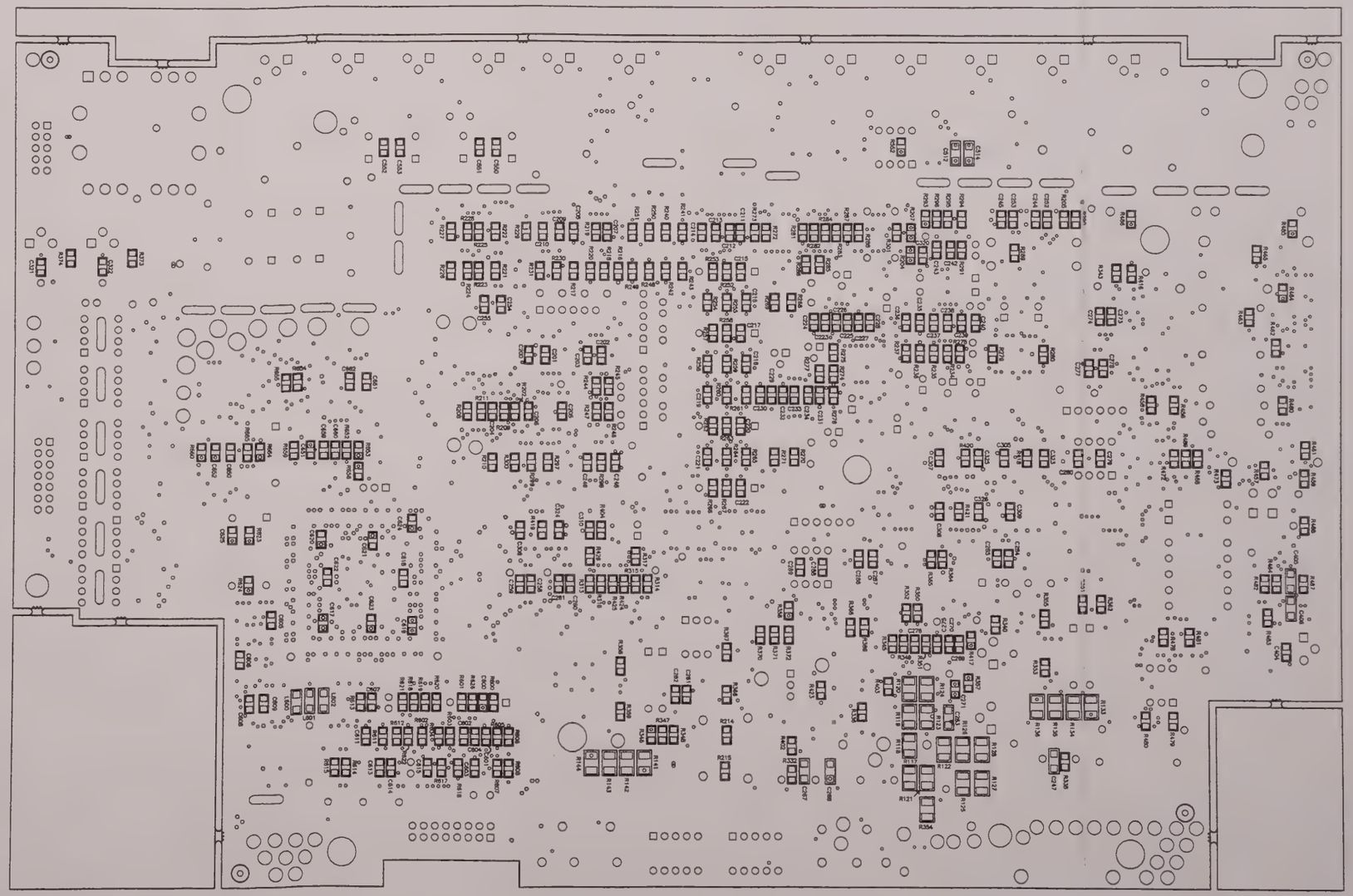
C NO. 2400-100

ORIGINAL IF RED

NO. 2400-100

LTR.	ECA NO.	REVISION	ENG	DATE
A		PRELIMINARY		
B		PRELIMINARY		
C	17917	RELEASED		

SOLDER SIDE COMPONENTS (SIDE -01)



NOTE: FOR COMPONENT INFORMATION SEE PRODUCT STRUCTURE

MODEL	NEXT ASSEMBLY	QTY.
USED ON		

KEITHLEY
KEITHLEY INSTRUMENTS INC.
CLEVELAND, OHIO 44139

DIM ARE IN IN. UNLESS OTHERWISE NOTED
DIM. TOL. UNLESS OTHERWISE SPECIFIED
XX=+.01 ANG.=+1
XXX=+.005 FRAC.=+1/64
DO NOT SCALE THIS DRAWING

DATE 3/6/95 | SCALE 5:4
DRN KEK | APPR. JN

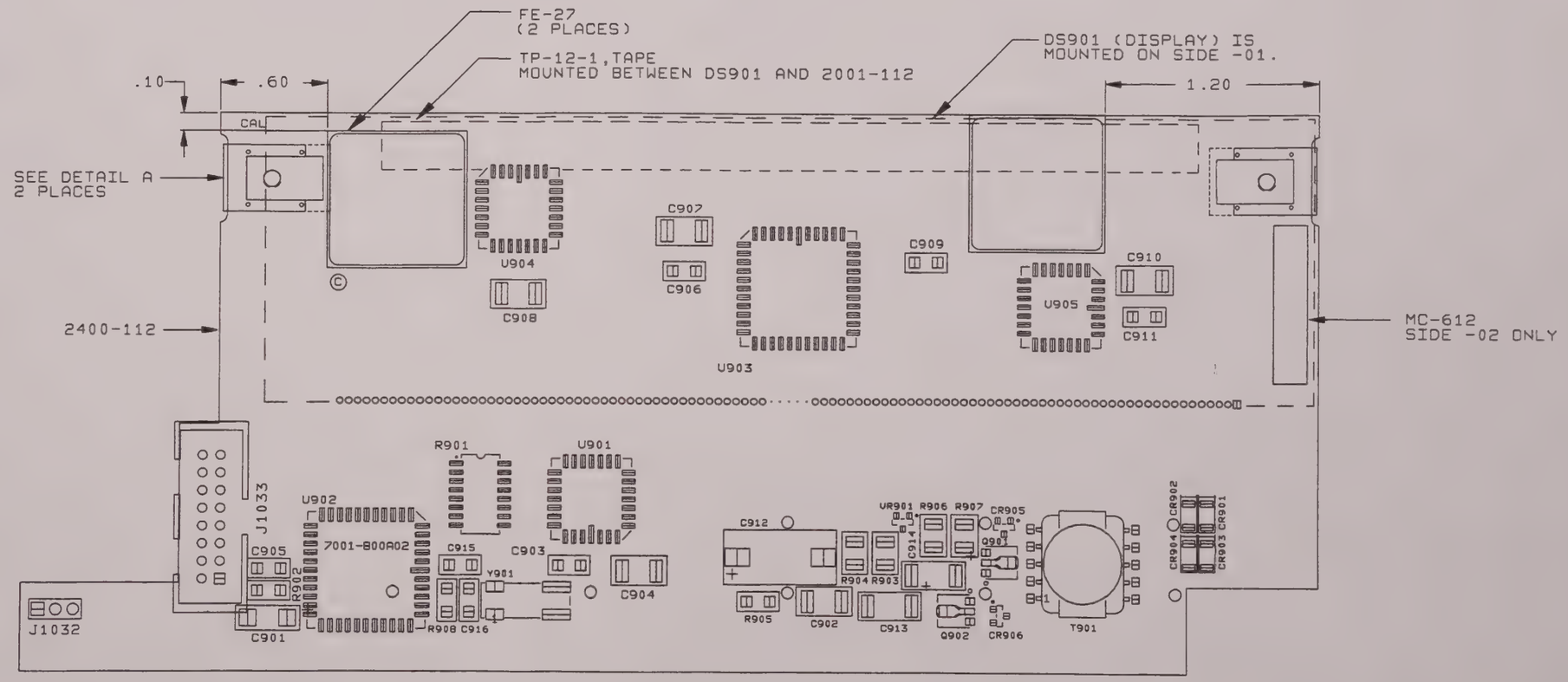
TITLE COMPONENT LAYOUT DRAWING
2400 SMU
ANALOG BOARD

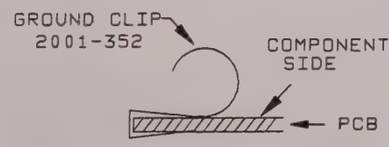
C | NO. 2400-100

ORIGINAL IF RED

NO. 2400-110

LTR.	ECO NO.	REVISION	ENG.	DATE
A	17508	RELEASED		10-25-95





DETAIL A

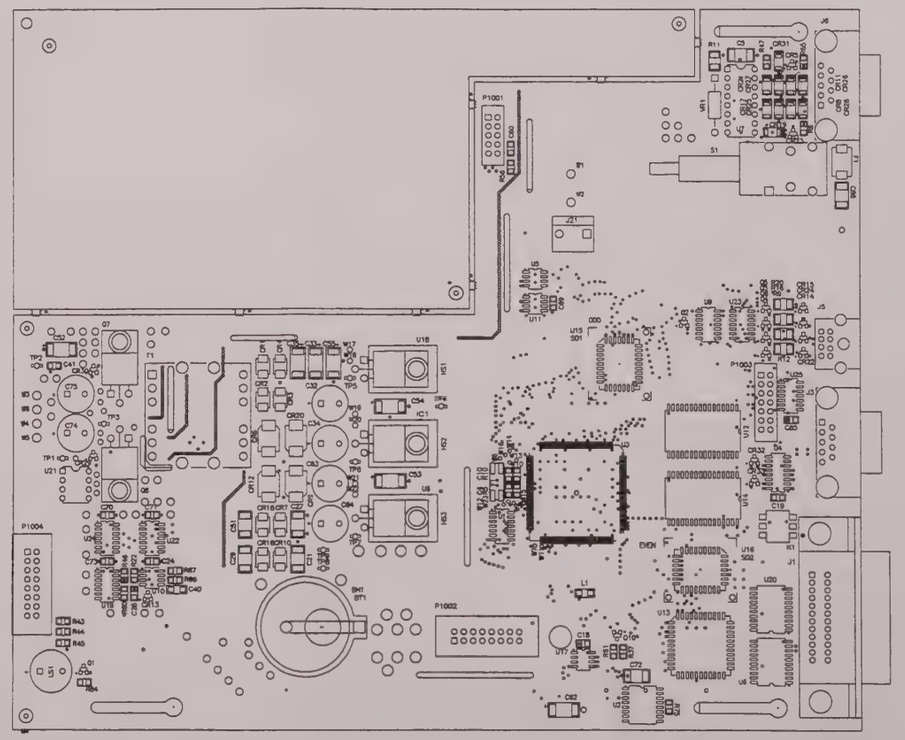
NOTES:
1. FOR MORE COMPONENT INFORMATION REFER TO 2400 PRODUCT STRUCTURE.
2. REQUIRES NO BOTTOM SIDE GLUE STENCIL.
3. REQUIRES TOP SIDE SOLDER PASTE STENCIL *2400-118-02A.

2400		1
MODEL	NEXT ASSEMBLY	QTY.
USED ON		

DO NOT SCALE THIS DRAWING	DIMENSIONAL TOLERANCES UNLESS OTHERWISE SPECIFIED	DATE 6/22/95	SCALE	TITLE COMPONENT LAYOUT, DISPLAY BOARD
KEITHLEY KEITHLEY INSTRUMENTS INC. CLEVELAND, OHIO 44139	XX=±.010 ANG.=±1°	DRN. AJS	ENG. APPR.	
	XXX=±.005 FRAC.=±1/64	MATERIAL	B	NO. 2400-110
	SURFACE MAX. 63	FINISH		

LTR	ECA NO.	REVISION	ENG	DATE
C	17921	RELEASED		11-1-95

NO. 2400-140



LTR.	ECA NO.	REVISION	ENG.	DATE
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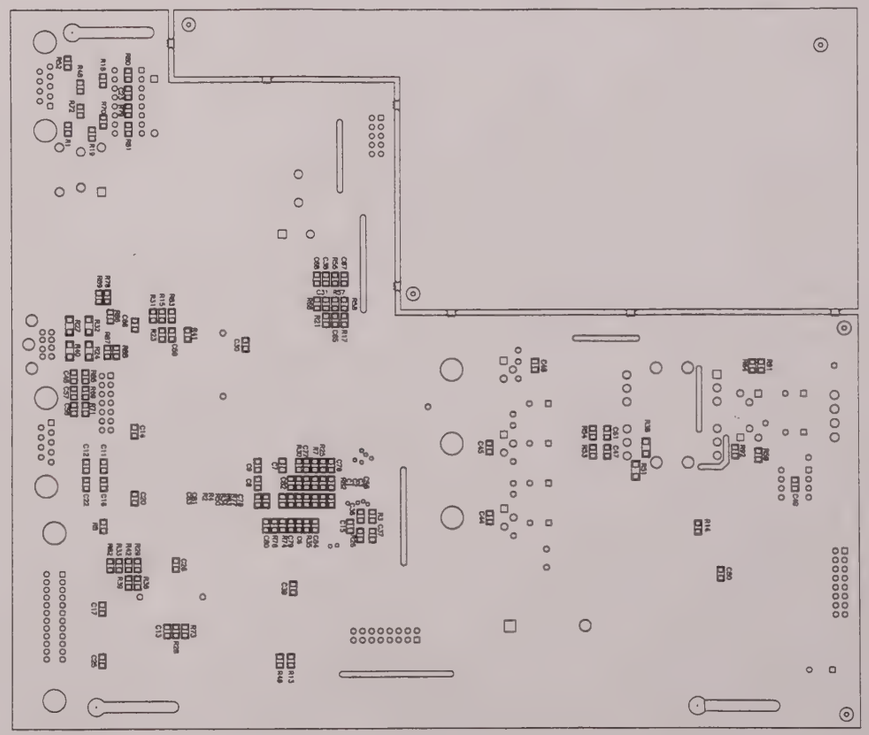
NO. 2400-140



BOTTOM SIDE COMPONENTS (bottom view)

NOTE: FOR COMPONENT INFORMATION, SEE PRODUCT STRUCTURE.

MODEL	NEXT ASSEMBLY	QTY
USED ON		

KEITHLEY KEITHLEY INSTRUMENTS INC. CLEVELAND, OHIO 44139	DIM ARE IN IN. UNLESS OTHERWISE NOTED DIM. TOL. UNLESS OTHERWISE SPECIFIED XX=+.01 ANG.=+1 XXX=+.005 FRAC.=+1/64	DATE 10/11/95 DRN MRS APPR. [illegible] DO NOT SCALE THIS DRAWING	SCALE 1:1 TITLE COMPONENT LAYOUT 2400 SMU (DAUGHTER) DIGITAL BOARD C NO. 2400-140

A
Specifications

SOURCE SPECIFICATIONS[1]

Voltage Programming Accuracy (local or remote sense)

Range	Programming Resolution	Accuracy (1 Year) 23°C ±5°C ±% rdg. + volts	Noise (peak-peak) 0.1Hz – 10Hz
200.000 mV	5 µV	0.02% + 600 µV	5 µV
2.00000 V	50 µV	0.02% + 600 µV	50 µV
20.0000 V	500 µV	0.02% + 2.4 mV	500 µV
200.000 V	5 mV	0.02% + 24 mV	5mV

TEMPERATURE COEFFICIENT (0°–18°C & 28°–50°C): +(0.15 × accuracy specification)/°C.

MAX. OUTPUT POWER: 22W (four quadrant source or sink operation).

SOURCE/SINK LIMITS: ± 21V @ ± 1.05A, ±210V @ ± 105mA.

VOLTAGE REGULATION: Line: 0.01% of range. **Load:** 0.01% of range + 100µV.

NOISE 10Hz–1MHz (p-p): 10mV.

OVER VOLTAGE PROTECTION: User selectable values, 5% tolerance. Factory default = 40 volts.

CURRENT LIMIT: Bipolar current limit (compliance) set with single value. Min. 0.1% of range.

OVERSHOOT: <0.1% (full scale step, resistive load, 10mA range).

Current Programming Accuracy (local or remote sense)

Range	Programming Resolution	Accuracy (1 Year)[3] 23°C ±5°C ±% rdg. +amps	Noise (peak-peak) 0.1Hz – 10Hz
1.00000 µA	50 pA	0.035% + 600pA	5 pA
10.0000 µA	500 pA	0.033% + 2nA	50 pA
100.000 µA	5 nA	0.031% + 20nA	500 pA
1.00000 mA	50 nA	0.034% + 200nA	5 nA
10.0000 mA	500 nA	0.045% + 2µA	
100.000 mA	5 µA	0.066% + 20µA	
1.00000 A[2]	50 µA	0.27 % + 900µA	

TEMPERATURE COEFFICIENT (0°–18°C & 28°–50°C): ±(0.15 × accuracy specification)/°C.

MAX. OUTPUT POWER: 22W (four quadrant source or sink operation).

SOURCE/SINK LIMITS: ±105mA @ 210V, ±1.05A @ 21V.

CURRENT REGULATION: Line: 0.01% of range.
Load: 0.01% of range + 100pA.

VOLTAGE LIMIT: Bipolar voltage limit (compliance) set with single value. Min. 0.1% of range.

OVERSHOOT: <0.1% typical (1mA step, R_L = 10kΩ, 20V range).

[1] Specifications valid for continuous output currents below 105mA. For operating above 105mA continuous for >1 minute, derate accuracy 10%/35mA above 105mA.

[2] Full operation (1A) regardless of load to 30°C. Above 30°C ambient, derate 35mA/°C and prorate 35mA/Ω load. For current sinking, up to 10W (external power) at 23°C. Above 23°C, derate 1W/°C.

[3] For sink mode, 1µA to 100mA range, accuracy is ±(0.1% + offset). For 1A range, accuracy is ±(1% + offset).

ADDITIONAL SOURCE SPECIFICATIONS

TRANSIENT RESPONSE TIME: 30µs minimum for the output to recover to its spec. following a step change in load.

COMMAND PROCESSING TIME: Maximum time required for the output to begin to change following the receipt of :SOURce:VOLTage|CURRent <nrf> command.

Autorange On: 10ms. **Autorange Off:** 7ms.

OUTPUT SETTLING TIME: Maximum settle time required to reach 0.1% of final value after command is processed. 30µs minimum.

OUTPUT SLEW RATE: 0.5V/µs, 200V range, 100mA compliance. 0.08V/µs, 0.2V, 2V, and 20V ranges, 100mA compliance.

DC FLOATING VOLTAGE: Output can be floated up to ±250VDC from chassis ground.

REMOTE SENSE: Up to 1V drop per load lead.

COMPLIANCE ACCURACY: Add 0.1% of range to base specification.

OVER TEMPERATURE PROTECTION: Internally sensed temperature overload puts unit in standby mode.

RANGE CHANGE OVERSHOOT: Overshoot into a fully resistive 100kΩ load, 10Hz to 1MHz BW, adjacent ranges, Smooth Mode: (100mV) typical, except 20V/200V range boundary.

MINIMUM COMPLIANCE VALUE: 0.1% of range.

MEASURE SPECIFICATIONS [1, 2]

Voltage Measurement Accuracy (local or remote sense)

Range	Max. Resolution	Input Resistance	Accuracy (23°C ± 5°C) 1 Year, ±(%rdg + volts)
200.000 mV	1 µV	>10GΩ	0.012% + 300 µV
2.00000 V	10 µV	>10GΩ	0.012% + 300 µV
20.0000 V	100 µV	>10GΩ	0.015% + 1 mV
200.000 V	1 mV	>10GΩ	0.015% + 10 mV

TEMPERATURE COEFFICIENT (0°–18°C & 28°–50°C):
±(0.15 × accuracy specification)/°C.

Current Measurement Accuracy (local or remote sense)

Range	Max. Resolution	Voltage Burden[3]	Accuracy (23°C ± 5°C) 1 Year, ±(%rdg + amps)
1.00000 µA	10 pA	< 1mV	0.029% + 300 pA
10.0000 µA	100 pA	< 1mV	0.027% + 700 pA
100.000 µA	1 nA	< 1mV	0.025% + 6 nA
1.00000 mA	10 nA	< 1mV	0.027% + 60 nA
10.0000 mA	100 nA	< 1mV	0.035% + 600 nA
100.000 mA	1 µA	< 1mV	0.055% + 6 µA
1.00000 A	10 µA	< 1mV	0.22 % + 570 µA

TEMPERATURE COEFFICIENT (0°–18°C & 28°–50°C):
±(0.1 × accuracy specification)/°C.

Resistance Measurement Accuracy (4 wire remote sense)

Source I Mode, Auto Ohms

Range	Max. Resolution	Default Test Current	Normal Accuracy (23°C ± 5°C) 1 Year, ±(%rdg + ohms)	Enhanced Accuracy (23°C ± 5°C) [5] 1 Year, ±(%rdg + ohms)
<2.00000 Ω [4]	1 µΩ	—	Source I_{ACC} + Measure V_{ACC}	Measure I_{ACC} + Measure V_{ACC}
20.0000 Ω	100 µΩ	100 mA	0.098% + 0.003 Ω	0.073% + 0.003 Ω
200.000 Ω	1 mΩ	10 mA	0.077% + 0.03 Ω	0.053% + 0.03 Ω
2.00000 kΩ	10 mΩ	1 mA	0.066% + 0.3 Ω	0.045% + 0.3 Ω
20.0000 kΩ	100 mΩ	100 µA	0.063% + 3 Ω	0.043% + 3 Ω
200.000 kΩ	1 Ω	10 µA	0.065% + 30 Ω	0.046% + 30 Ω
2.00000 MΩ	10 Ω	1 µA	0.11% + 300 Ω	0.049% + 300 Ω
20.0000 MΩ	100 Ω	1 µA	0.11% + 1 kΩ	0.052% + 1 kΩ
200.000 MΩ	1 kΩ	100 nA	0.97% + 10 kΩ	0.3 % + 10 kΩ
>200.000 MΩ [4]	1 MΩ	—	Source I_{ACC} + Measure V_{ACC}	Measure I_{ACC} + Measure V_{ACC}

TEMPERATURE COEFFICIENT (0°–18°C & 28°–50°C):
±(0.15 × accuracy specification)/°C.

SOURCE I MODE, MANUAL OHMS: Total uncertainty = I source accuracy + V measure accuracy (4-wire remote sense).

SOURCE V MODE: Total uncertainty = V source accuracy + I measure accuracy (4-wire remote sense).

6-WIRE OHMS MODE: Available using active ohms guard and guard sense. **Max. Guard Output Current:** 50 mA (except 1A range). Accuracy is load dependent. Refer to manual for calculation formula.

GUARD OUTPUT IMPEDANCE: 0.1Ω in ohms mode.

[1] Speed = Normal (1 PLC).
[2] Accuracies apply to 2- or 4-wire mode when properly zeroed.
[3] 4-wire mode.
[4] Manual ohms mode only.
[5] Source readback enabled.

SYSTEM SPEEDS

MEASUREMENT[1]

MAXIMUM RANGE CHANGE RATE: 75/second.

MAXIMUM MEASURE AUTORANGE TIME: 40ms (fixed source)[2].

SWEEP OPERATION[3] READING RATES (rdg/second) FOR 60Hz (50Hz):

Speed	NPLC/Trigger Origin	Measure To Mem.	Measure To GPIB	Source-Measure To Mem.	Source-Measure To GPIB
Fast	0.01 / internal	2125 (2010)	1000 (1000)	1825 (1735)	900 (900)
	0.01 / external	1275 (1225)	910 (920)	1150 (1115)	830 (835)
Medium	0.10 / internal	510 (435)	510 (435)	480 (420)	480 (420)
	0.10 / external	440 (385)	440 (385)	425 (370)	425 (370)
Normal	1.00 / internal	59 (49)	59 (49)	58 (48)	58 (48)
	1.00 / external	57 (48)	57 (48)	57 (47)	57 (47)

Speed	NPLC/Trigger Origin	Source-Measure Pass/Fail Test[4] To Mem.	Source-Measure Pass/Fail Test[4] To GPIB	Source-Memory[4] To Mem.	Source-Memory[4] To GPIB
Fast	0.01 / internal	1000 (990)	760 (760)	260 (260)	260 (260)
	0.01 / external	940 (910)	710 (710)	255 (250)	255 (250)
Medium	0.10 / internal	400 (355)	400 (355)	200 (200)	200 (200)
	0.10 / external	390 (345)	390 (345)	200 (185)	200 (185)
Normal	1.00 / internal	57 (48)	57 (48)	50 (50)	50 (50)
	1.00 / external	56 (47)	56 (47)	50 (40)	50 (40)

SINGLE READING OPERATION READING RATES (rdg/second) FOR 60Hz (50Hz): [5]

Speed	NPLC/Trigger Origin	Measure To GPIB	Source-Measure[6] To GPIB	Source-Measure Pass/Fail Test[4,6] To GPIB
Fast	0.01 / internal	200 (200)	72 (70)	70 (70)
Medium	0.10 / internal	160 (150)	65 (60)	60 (59)
Normal	1.00 / internal	46 (40)	32 (30)	30 (29)

COMPONENT HANDLER INTERFACE TIME: [4,7]

Speed	NPLC/Trigger Origin	Measure Pass/Fail Test	Source Pass/Fail Test	Source-Measure Pass/Fail Test[8]
Fast	0.01 / external	0.9 ms (0.95 ms)	0.5 ms (0.5 ms)	3.9 ms (4.0 ms)
Medium	0.10 / external	2.5 ms (2.75 ms)	0.5 ms (0.5 ms)	5.3 ms (5.75 ms)
Normal	1.00 / external	17.5 ms (20.75 ms)	0.5 ms (0.5 ms)	20.5 ms (24 ms)

1 Reading rates applicable for voltage or current measurements. Auto zero off, autorange off, filter off, display off, trigger delay = 0, and binary reading format.

2 Purely resistive load. 1µA and 10µA ranges <65ms.

3 1000 point sweep was characterized with the source on a fixed range.

4 Pass/Fail test performed using one high limit and one low math limit.

5 Trigger mode idle, display off.

6 Includes time to re-program source to a new level before making measurement.

7 Time from falling edge of START OF TEST signal to falling edge of END OF TEST signal.

8 Command processing time of :SOURce:VOLTage|CURRent:TRIGgered <nrf> command not included.

GENERAL

NOISE REJECTION:

	NPLC	NMRR	CMRR
Fast	0.01	—	80 dB
Medium	0.1	—	80 dB
Normal	1	60 dB	120 dB [1]

LOAD IMPEDANCE: Stable into 20,000pF typical.

COMMON MODE VOLTAGE: 250VDC.

COMMON MODE ISOLATION: $>10^9\Omega$, <1000pF.

OVERRANGE: 105% of range source + measure.

MAX. VOLTAGE DROP BETWEEN INPUT/OUTPUT AND SENSE TERMINALS: 5 volts.

MAX. SENSE LEAD RESISTANCE: 1kΩ for rated accuracy.

SENSE INPUT IMPEDANCE: $>10^{10}\Omega$.

SOURCE OUTPUT MODES:
Fixed DC level
Memory List (mixed function)
Stair (linear and log)

SOURCE MEMORY LIST: 100 points maximum.

MEMORY BUFFER: 5,000 readings @ 5½ digits (two 2,500 point buffers). Includes selected measured value(s) and time stamp. Lithium battery backup.

PROGRAMMABILITY: IEEE-488 (SCPI-1995.0), RS-232, 5 user-definable power-up states plus factory default and *RST.

DIGITAL INTERFACE:

Safety Interlock: Active low input.

Handler Interface: Start of test, end of test, 3 category bits. +5V @ 300mA supply.

Digital I/O: 1 trigger input, 4 TTL/Relay Drive outputs (33V @ 500mA sink, diode clamped).

POWER SUPPLY: 88V to 264V rms, 50–60Hz (automatically detected at power up).

WARRANTY: 1 year.

EMC: Complies with European Union Directive 89/336/EEC (CE marking requirements), FCC part 15 class B, CTSPR 11, IEC 801-2, IEC 801-3, IEC 801-4.

VIBRATION: MIL-T-28800E Type III, Class 5.

WARM-UP: 1 hour to rated accuracies.

DIMENSIONS: 89mm high × 213mm wide × 370mm deep (3½ in × 8⅜ in × 14⁹/₁₆ in). Bench Configuration (with handle & feet): 104mm high × 238mm wide × 370mm deep (4⅛ in × 9⅜ in × 14⁹/₁₆ in).

WEIGHT: 3.21kg (7.08 lbs).

ENVIRONMENT:

Operating: 0°–50°C, 70% R.H. up to 35°C. Derate 3% R.H./°C, 35°–50°C.

Storage: –25°C to 65°C.

[1] Except lowest 2 current ranges = 90dB.

Specifications are subject to change without notice.

Accuracy calculations

The information below discusses how to calculate accuracy for both sense and source functions.

Measure accuracy

Measurement accuracy is calculated as follows:

Accuracy = ±(% of reading + offset)

As an example of how to calculate the actual reading limits, assume that you are measuring 10V on the 20V range. You can compute the reading limit range from one-year measure voltage accuracy specifications as follows:

$$\begin{aligned} \text{Accuracy} &= \pm(\%\text{ of reading} + \text{offset}) \\ &= \pm[(0.015\% \times 10\text{V}) + 1\text{mV}] \\ &= \pm(1.5\text{mV} + 1\text{mV}) \\ &= \pm 2.5\text{mV} \end{aligned}$$

Thus, the actual reading range is 10V± 2.5mV or from 9.9975 to 10.0025V

DC current measurement calculations are performed in exactly the same manner using the pertinent specifications, ranges, and input signal values.

Source accuracy

Source accuracy is calculated similarly, except source specifications are used. As an example of how to calculate the actual source output limits, assume that you are sourcing 0.7mA on the 1mA source range. You can compute the reading limit range from source current one-year accuracy specifications as follows:

$$\begin{aligned} \text{Accuracy} &= \pm(0.034\%\text{ of output} + 200\text{nA offset}) \\ &= \pm[(0.034\% \times 0.7\text{mA}) + 200\text{nA})] \\ &= \pm(238\text{nA} + 200\text{nA}) \\ &= \pm 438\text{nA} \end{aligned}$$

In this case, the actual current output range is 0.7mA ±438nA or from 0.69956mA to 0.70044mA

B
Command Reference

Introduction

This appendix contains detailed information on the various Model 2400 remote calibration commands, calibration error messages, and methods to detect the end of each calibration step.

Section 2 of this manual covers detailed calibration procedures.

Command summary

Table B-1 summarizes Model 2400 calibration commands. These commands are covered in detail in the following paragraphs.

Table B-1
Remote calibration command summary

Command	Description
CALibration	Calibration subsystem.
:PROTected	Cal commands protected by password.
:CODE '<password>'	Unlock cal. If cal is unlocked, changes password. (Default password: KI002400.)
:COUNT?	Query number of times 2400 has been calibrated.
:SAVE	Save calibration data to EEPROM.*
:LOCK	Lock calibration, inhibit SAVE command operation.
:LOCK?	Request cal lock status. (0 = unlocked; 1= locked.)
:DATE <y>,<m>,<d>	Program calibration year, month, day.
:DATE?	Query calibration year, month, day.
:NDUE <y>,<m>,<d>	Program calibration due year, month, day.
:NDUE?	Query calibration due year, month, day.
:SENSe <nrf>	Calibrate active measure range.
:DATA?	Query measurement cal constants for active range.
:SOURce <nrf>	Calibrate active source range.
:DATA?	Query source cal constants for active range.

* Calibration data will not be saved if:

1. Calibration was not unlocked with :CODE command.
2. Invalid data exists. (For example, cal step failed or was aborted.)
3. Incomplete number of cal steps was performed. (For example, omitting a negative full-scale step.)

Miscellaneous commands

Miscellaneous commands are those commands that perform such functions as saving calibration constants, locking out calibration, and programming date parameters.

:CODE

(:CALibration:PROTected:CODE)

Purpose To unlock calibration so that you can perform the calibration procedures.

Format
```
:cal:prot:code '<password>'
```

Parameter Up to a 8-character string including letters and numbers.

Description The :CODE command sends the password and enables calibration when performing these procedures via remote. The correct password must be sent to the unit before sending any other calibration command. The default remote password is KI002400.

Note
- The :CODE command should only be sent once before performing calibration. Do not send :CODE before each calibration step.
- To change the code, first send the present code, and then send the new code.
- The password parameter must be enclosed in single quotes.
- If you change the first two characters of the password to something other than "KI", you will not be able to unlock calibration from the front panel.

Example
```
:CAL:PROT:CODE 'KI002400'
```
Send default code of KI002400.

:COUNT?

(:CALibration:PROTected:COUNT?)

Purpose To request the number of times the Model 2400 has been calibrated.

Format
```
:cal:prot:count?
```

Response Number of times calibrated.

Description The :COUNT? query may be used to determine the total number of times the Model 2400 has been calibrated.

Example
```
:CAL:PROT:COUNT?
```
Request calibration count.

:LOCK

(:CALibration:PROTected:LOCK)

Purpose To lock out calibration.

Format `:cal:prot:lock`

Query `:cal:prot:lock?`

Response
0 Calibration unlocked
1 Calibration locked

Description The :LOCK command lets you lock out comprehensive calibration after completing those procedures. Thus, :LOCK performs the opposite of sending the password with the :CODE command. The :LOCK? query returns calibration lock status.

Note To unlock calibration, send the :CODE command with the appropriate password.

Example
```
:CAL:PROT:LOCK          Lock out calibration
```

:SAVE

(:CALibration:PROTected:SAVE)

Purpose To save calibration constants in EEROM after the calibration procedure.

Format `:cal:prot:save`

Description The :SAVE command stores internally calculated calibration constants derived during comprehensive in EEROM. EEROM is non-volatile memory, and calibration constants will be retained indefinitely once saved. Generally, :SAVE is sent after all other calibration steps (except for :LOCK).

Note Calibration will be only temporary unless the :SAVE command is sent to permanently store calibration constants. Calibration data will not be saved if: (1) calibration was not unlocked by sending the :CODE command, (2) invalid data exists (for example, cal step failed or was aborted.), or (3) an incomplete number of cal steps were performed (for example, omitting a negative full-scale step).

Example
```
:CAL:PROT:SAVE          Save calibration constants
```

:DATE

(:CALibration:PROTected:DATE)

Purpose To program the calibration date.

Format
```
:cal:prot:date <year>, <month>, <day>
```

Parameter
<year> = 1995 to 2094
<month> = 1 to 12
<day> = 1 to 31

Query
```
:cal:prot:date?
```

Response <year> , <month> , <day>

Description The :DATE command allows you to store the calibration date in instrument EEROM for future reference. You can read back the date from the instrument by using the :DATE? query or by using the front panel CAL menu.

Note The year, month, and day parameters must be delimited by commas.

Example
```
:CAL:PROT:DATE 1995,11,20
```
Send cal date (11/20/95).

:NDUE

(:CALibration:PROTected:NDUE)

Purpose To send the next calibration due date to the instrument.

Format
```
:cal:prot:ndue <year>, <month>, <day>
```

Parameter
<year> = 1995 to 2094
<month> = 1 to 12
<day> = 1 to 31

Query
```
:cal:prot:ndue?
```

Response <year>, <month>, <day>

Description The :NDUE command allows you to store the date when calibration is next due in instrument memory. You can read back the next due date by using the :NDUE? query or by using the front panel CAL menu.

Note The next due date parameters must be delimited by commas.

Example
```
:CAL:PROT:NDUE 1996,11,20
```
Send due date (11/20/96).

:SENSE

(:CALibration:PROTected:SENSe)

Purpose To calibrate the sense function.

Format

```
:cal:prot:sens <nrf>
```

Parameter See Table B-2.

Description The :CAL:PROT:SENS command calibrates the Model 2400 sense function. To use this command, you must (1) program the source to the correct value, (2) select the range being calibrated, and (3) send the :CAL:PROT:SENS command for each parameter listed in Table B-2.

Note When the Model 2400 receives this command, it will attempt to place the parameter into one of the three parameter ranges summarized in Table B-2, depending on the active :SENS:FUNC and range. If the parameter does not fit into any of the three allowed ranges, an error number -222, "Parameter data out of range", will be generated. Once the unit has successfully selected the appropriate parameter range, it will then check to see if autorange for the active :SENS:FUNC is enabled. If so, an error number -221, "Settings conflict", will be generated. If no error occurs, the active sense function/range point will be calibrated using the corresponding parameter.

Note that parameters for a given sense function and range may be sent in any order. However, once one :CAL:PROT:SENS command executes, the other two must also be executed, or an error number -200, "Execution error", will occur when the :CAL:PROT:SAVE command is processed at the end of the calibration procedure.

Example

```
:CAL:PROT:SENS 2
```

Calibrate 2V sense range.

Table B-2
:CALibration:PROTected:SENSe parameter ranges

Sense range	First parameter (zero)	Second parameter (negative full scale)	Third parameter (positive full scale)
0.2V	-0.002 to +0.002	-0.18 to -0.22	+0.18 to +0.22
2V	-0.02 to +0.02	-1.8 to -2.2	+1.8 to +2.2
20V	-0.2 to +0.2	-18 to -22	+18 to +22
200V	-2 to +2	-180 to -220	+180 to +220
1µA	-1E-8 to +1E-8	-0.9E-6 to -1.1E-6	+0.9E-6 to +1.1E-6
10µA	-1E-7 to +1E-7	-9E-6 to -11E-6	+9E-6 to +11E-6
100µA	-1E-6 to +1E-6	-90E-6 to -110E-6	+90E-6 to +110E-6
1mA	-1E-5 to +1E-5	-0.9E-3 to -1.1E-3	+0.9E-3 to +1.1E-3
10mA	-1E-4 to +1E-4	-9E-3 to -11E-3	+9E-3 to +11E-3
100mA	-1E-3 to +1E-3	-90E-3 to -110E-3	+90E-3 to +110E-3
1A	-1E-2 to +1E-2	-0.9 to -1.1	+0.9 to +1.1

:SOURCE

(:CALibration:PROTected:SOURce)

Purpose To calibrate the source function.

Format

```
:cal:prot:sour <nrf>
```

Parameter See Table B-3.

Description The :CAL:PROT:SOUR command calibrates the Model 2400 source function. To use this command, you must (1) program the source to the correct value, (2) select the range being calibrated, and (3) send the :CAL:PROT:SOUR command for each parameter listed in Table B-3.

Note When the Model 2400 receives this command, it will attempt to place the parameter into one of the four parameter ranges summarized in Table B-3, depending on the active :SOUR:FUNC and range. If the parameter does not fit into any of the four allowed ranges, an error number -222, "Parameter data out of range", will be generated. Once the unit has successfully selected the appropriate parameter range, it will then check to see if the active source is programmed to a value within the selected parameter range and that :OUTP:STAT is ON. If the active source is not programmed to a value within the parameter range (or if the source is in autorange or in standby), an error number -221, "Settings conflict", will be generated. If no error occurs, the active source function/range point will be calibrated using the corresponding parameter.

Note that parameters for a given source function and range may be sent in any order. However, once one :CAL:PROT:SOUR command executes, the other three must also be executed, or an error number -200, "Execution error", will occur when the :CAL:PROT:SAVE command is processed at the end of the calibration procedure.

Because the source is calibrated for both positive and negative values, two zero calibration points are required. The Model 2400 automatically uses the appropriate zero parameter based on whether the source polarity is positive or negative.

Example

```
:CAL:PROT:SOUR 2
```

Calibrate 2V source range.

Table B-3
:CALibration:PROTected:SOURce parameter ranges

Source range	First parameter (negative full scale)	Second parameter (negative zero)	Third parameter (positive full scale)	Fourth parameter (positive zero)
0.2V	-0.18 to -0.22	-0.002 to +0.002	+0.18 to +0.22	-0.002 to +0.002
2V	-1.8 to -2.2	-0.02 to +0.02	+1.8 to +2.2	-0.02 to +0.02
20V	-18 to -22	-0.2 to +0.2	+18 to +22	-0.2 to +0.2
200V	-180 to -220	-2 to +2	+180 to +220	-2 to +2
1µA	-0.9E-6 to -1.1E-6	-1E-8 to +1E-8	+0.9E-6 to +1.1E-6	-1E-8 to +1E-8
10µA	-9E-6 to -11E-6	-1E-7 to +1E-7	+9E-6 to +11E-6	-1E-7 to +1E-7
100µA	-90E-6 to -110E-6	-1E-6 to +1E-6	+90E-6 to +110E-6	-1E-6 to +1E-6
1mA	-0.9E-3 to -1.1E-3	-1E-5 to +1E-5	+0.9E-3 to +1.1E-3	-1E-5 to +1E-5
10mA	-9E-3 to -11E-3	-1E-4 to +1E-4	+9E-3 to +11E-3	-1E-4 to +1E-4
100mA	-90E-3 to -110E-3	-1E-3 to +1E-3	+90E-3 to +110E-3	-1E-3 to +1E-3
1A	-0.9 to -1.1	-1E-2 to +1E-2	+0.9 to +1.1	-1E-2 to +1E-2

:DATA?

(:CALibration:PROTected:SENSe:DATA?)
(:CALibration:PROTected:SOURce:DATA?)

Purpose To request the calibration constants for the active range.

Format
```
:cal:prot:sens:data?
:cal:prot:sour:data?
```

Response Four comma-separated ASCII floating-point constants

Description The :CAL:PROT:SENS:DATA? and :CAL:PROT:SOUR:DATA? queries request the calibration constants for the active range of the sense and source functions respectively. The four returned constants are in ASCII floating-point format delimited by commas.

Note To request the appropriate constants, (1) select the source or sense function, (2) choose the desired range, and (3) send the desired :DATA? query.

Example
```
:SENS:FUNC 'VOLT:DC'        Select DC sense function.
:SENS:VOLT:DC:RANGE 0.2     Choose 200mV range.
:CAL:PROT:SENS:DATA?        Request cal constants.
```

Detecting calibration errors

If an error occurs during any calibration step, the Model 2400 will generate an appropriate error message. Several methods to detect calibration errors are discussed in the following paragraphs.

Reading the error queue

As with other Model 2400 errors, any calibration errors will be reported in the error queue. (You can read the error queue by using the :SYST:ERR? query.)

Error summary

Table B-4 summarizes calibration errors. These errors will occur under the following conditions.

Error 500/501	Will occur if you do not set the calibration date or calibration due date.
Error 502	Will occur when the :CAL:PROT:SENS or :CAL:PROT:SOUR command is sent with a parameter that cannot be placed into any of the defined numeric ranges.
Error 503/504	Will occur when the source/compliance DAC calibration constants generate an invalid DAC setting. All of the source/compliance DAC calibration constants are verified each time a :CAL:PROT:SOUR command is processed and when the Model 2400 is first turned on. This error generally occurs when the Model 2400 source circuitry is defective.
Error 505	Will occur when a :CAL:PROT:SOUR command generates an invalid source offset calibration constant.
Error 506	Will occur when a :CAL:PROT:SOUR command generates an invalid source gain calibration constant.
Error 507	Will occur when a :CAL:PROT:SENS command generates an invalid measurement offset calibration constant.
Error 508	Will occur when a :CAL:PROT:SENS command generates an invalid measurement gain calibration constant.

Table B-4
Calibration errors

Error number	Error message
+500	"Date of calibration not set"
+501	"Next date of calibration not set"
+502	"Calibration data invalid"
+503	"DAC calibration overflow"
+504	"DAC calibration underflow"
+505	"Source offset data invalid"
+506	"Source gain data invalid"
+507	"Measurement offset data invalid"
+508	"Measurement gain data invalid"

Status byte EAV (Error Available) bit

Whenever an error is available in the error queue, the EAV (Error Available) bit (bit 2) of the status byte will be set. Use the *STB? query to obtain the status byte, and then test bit 2 to see if it is set. If the EAV bit is set, an error has occurred, and you can use the appropriate error query to read the error and at the same time clear the EAV bit in the status byte.

Generating an SRQ on error

To program the instrument to generate an IEEE-488 bus SRQ (Service Request) when an error occurs, send the *SRE 4 command. This command will enable SRQ when the EAV bit is set. You can then read the status byte and error queue as outlined above to check for errors and to determine the exact nature of the error.

Detecting calibration step completion

When sending remote calibration commands, you must wait until the instrument completes the present operation before sending another command. You can use either *OPC? or *OPC to help determine when each calibration step is completed.

Using the *OPC? query

With the *OPC? (operation complete) query, the instrument will place an ASCII 1 in the output queue when it has completed each step. To determine when the OPC response is ready, perform the following:

1. Repeatedly test the MAV (Message Available) bit (bit 4) in the status byte and wait until it is set. (You can request the status byte by using the *STB? query.)
2. When MAV is set, a message is available in the output queue, and you can read the output queue and test for an ASCII 1.
3. After reading the output queue, repeatedly test MAV again until it clears. At this point, the calibration step is completed.

Using the *OPC command

The *OPC (operation complete) command can also be used to detect the completion of each calibration step. In order to use *OPC to detect the end of each calibration step, perform the following:

1. Enable operation complete by sending *ESE 1. This command sets the OPC (operation complete bit) in the standard event enable register, allowing operation complete status from the standard event status register to set the ESB (event summary bit) in the status byte when operation complete is detected.
2. Send the *OPC command immediately following each calibration command. For example:

   ```
   :CAL:PROT:SENS 2;*OPC
   ```

   Note that you must include the semicolon (;) to separate the two commands and that the *OPC command must appear on the same line as the command.
3. After sending a calibration command, repeatedly test the ESB (Event Summary) bit (bit 5) in the status byte until it is set. (Use *STB? to request the status byte.)
4. Once operation complete has been detected, clear OPC status using one of two methods: (1) use the *ESR? query, and then read the response to clear the standard event status register, or (2) send the *CLS command to clear the status registers. Note that sending *CLS will also clear the error queue and operation complete status.

Generating an SRQ on calibration complete

An IEEE-488 bus SRQ (service request) can be used to detect operation complete instead of repeatedly polling the Model 2400. To use this method, send both *ESE 1 and *SRE 32 to the instrument, and then include the *OPC command at the end of each calibration command line, as previously discussed. Clear the SRQ by querying the ESR (using the *ESR? query) to clear OPC status, and then request the status byte with the *STB? query.

Refer to your controller's documentation for information on detecting and servicing SRQs.

C
Calibration Programs

Introduction

This appendix includes a calibration program written in BASIC to help you calibrate the Model 2400, as well as an example program that demonstrates how to request calibration constants. Refer to Section 2 for more details on calibration procedures, equipment, and connections.

Computer hardware requirements

The following computer hardware is required to run the calibration programs:

- IBM PC, AT, or compatible computer.
- Keithley KPC-488.2, KPS-488.2, or KPC-488.2AT, or CEC PC-488 IEEE-488 interface for the computer.
- Two shielded IEEE-488 connecting cables (Keithley Model 7007)

Software requirements

In order to use the calibration programs, you will need the following computer software:

- Microsoft QBasic (supplied with MS-DOS 5.0 or later).
- MS-DOS version 5.0 or later.
- HP-style Universal Language Driver, CECHP.EXE (supplied with Keithley and CEC interface cards listed above).

Calibration equipment

The following calibration equipment is required:

- Hewlett-Packard HP3458A Digital Multimeter

See Section 2 for detailed equipment specifications.

General program instructions

1. With the power off, connect the Model 2400 and the digital multimeter to the IEEE-488 interface of the computer. Be sure to use shielded IEEE-488 cables for bus connections. Also, connect the digital multimeter to the Model 2400 as discussed in Section 2.
2. Turn on the computer, the Model 2400, and the digital multimeter. Allow the Model 2400 and the multimeter to warm up for at least one hour before performing calibration.
3. Make sure the Model 2400 is set for a primary address of 24. (Use the front panel MENU/GPIB selection to check or change the address.)
4. Make sure the digital multimeter primary address is set to its factory default setting (22).
5. Make sure that the computer bus driver software (CECHP.EXE) is properly initialized.
6. Enter the QBasic editor, and enter in the following program. Check thoroughly for errors, and then save it using a convenient filename.
7. Run the program, and follow the prompts on the screen to perform calibration.

Program C-1. Model 2400 calibration program

```
' Model 2400 calibration program for use with the HP3458A Digital Multimeter.
' Rev. 1.0, 12/28/95
' 2400 primary address = 24. HP3458A primary address = 22.
OPEN "IEEE" FOR OUTPUT AS #1            ' Open IEEE-488 output path.
OPEN "IEEE" FOR INPUT AS #2             ' Open IEEE-488 input path.
PRINT #1, "INTERM CRLF"                 ' Set input terminator.
PRINT #1, "OUTTERM LF"                  ' Set output terminator.
PRINT #1, "REMOTE 22 24"                ' Put 2400, 3458A in remote.
PRINT #1, "CLEAR"                       ' Send DCL.
PRINT #1, "OUTPUT 24;*CLS"              ' Initialize 2400.
PRINT #1, "OUTPUT 24;*ESE 1;*SRE 32"    ' Enable OPC and SRQ.
PRINT #1, "OUTPUT 22;PRESET NORM"       ' Initialize 3458A.
PRINT #1, "OUTPUT 22;NPLC 10;NDIG 7;TRIG LINE;FUNC DCV,AUTO"
'
CLS                                     ' Clear CRT.
PRINT "Model 2400 Calibration Program"
PRINT "Connect DMM volts input to Model 2400 INPUT/OUTPUT jacks."
GOSUB KeyCheck
FOR J = 1 TO 2                          ' Select volts/current cal.
IF J = 1 THEN
        RESTORE VoltsInit
        Max = 8
        Range = .2
        Limit = 200
ELSE
        RESTORE CurrentInit
        Max = 4
        Range = .000001
        Limit = 1
        PRINT #1, "OUTPUT 22;FUNC DCI,AUTO"
        PRINT "Connect DMM current input to 2400 INPUT/OUTPUT jacks."
        GOSUB KeyCheck
END IF
FOR I = 1 TO Max: READ Cmd$: PRINT #1, "OUTPUT 24;"; Cmd$: NEXT I
WHILE Range <= Limit                            ' Cal all ranges.
IF J = 1 THEN RESTORE VoltsCal ELSE RESTORE CurrentCal
IF J = 1 THEN PRINT "Calibrating volts." ELSE PRINT "Calibrating current."
FOR I = 1 TO 12
        READ Cmd$
        SELECT CASE I
                CASE 1
                        PRINT #1, "OUTPUT 24;"; Cmd$; Range
                CASE 2
                        PRINT #1, "OUTPUT 24;"; Cmd$; -Range
                        GOSUB ReadDMM
                CASE 3, 4, 6, 7, 9, 10, 12
                        PRINT #1, "OUTPUT 24;"; Cmd$; Reading; ";*OPC"
                        GOSUB CalEnd
                        GOSUB ErrCheck
```

```
                CASE 5, 11
                        PRINT #1, "OUTPUT 24;"; Cmd$
                        GOSUB ReadDMM
                CASE 8
                        PRINT #1, "OUTPUT 24;"; Cmd$; Range
                        GOSUB ReadDMM
        END SELECT
NEXT I
Range = Range * 10
WEND
NEXT J
LINE INPUT "Enter calibration date (yyyy,mm,dd): "; D$
PRINT #1, "OUTPUT 24;:CAL:PROT:DATE "; D$
LINE INPUT "Enter calibration due date (yyyy,mm,dd): "; D$
PRINT #1, "OUTPUT 24;:CAL:PROT:NDUE "; D$
PRINT #1, "OUTPUT 24;:CAL:PROT:SAVE"     ' Save calibration constants.
GOSUB ErrCheck
PRINT #1, "OUTPUT 24;:CAL:PROT:LOCK"     ' Lock out calibration.
PRINT "Calibration completed."
PRINT #1, "OUTPUT 24;*RST"
PRINT #1, "LOCAL 22 24"
CLOSE
END
'
KeyCheck:                                ' Check for key press routine.
WHILE INKEY$ <> "": WEND                 ' Flush keyboard buffer.
PRINT : PRINT "Press any key to continue (ESC to abort program)."
DO: I$ = INKEY$: LOOP WHILE I$ = ""
IF I$ = CHR$(27) THEN GOTO EndProg       ' Abort if ESC is pressed.
RETURN
'
CalEnd:                                  ' Check for cal step completion.
DO: PRINT #1, "SRQ?"                     ' Request SRQ status.
        INPUT #2, S                      ' Input SRQ status byte.
LOOP UNTIL S                             ' Wait for operation complete.
PRINT #1, "OUTPUT 24;*ESR?"              ' Clear OPC.
PRINT #1, "ENTER 24"
INPUT #2, S
PRINT #1, "SPOLL 24"                     ' Clear SRQ.
INPUT #2, S
RETURN
'
ErrCheck:                                ' Error check routine.
PRINT #1, "OUTPUT 24;:SYST:ERR?"         ' Query error queue.
PRINT #1, "ENTER 24"
INPUT #2, E, Err$
IF E <> 0 THEN PRINT Err$: GOTO EndProg  ' Display error.
RETURN
'
```

```
ReadDMM:                                ' Get reading from DMM.
SLEEP 5
PRINT #1, "ENTER 22"
INPUT #2, Reading
RETURN
'
EndProg:                                ' Close files, end program.
BEEP: PRINT "Calibration aborted."
PRINT #1, "OUTPUT 24;:CAL:PROT:LOCK"
PRINT #1, "OUTPUT 24;*RST"
PRINT #1, "LOCAL 22 24"
CLOSE
END
'
VoltsInit:                              ' Calibration command lists.
DATA "*RST",":SOUR:FUNC VOLT",":SENS:CURR:PROT 0.1"
DATA ":SENS:CURR:RANG 0.1",":SOUR:VOLT:PROT:LEV MAX",":SYST:RSEN OFF"
DATA ":CAL:PROT:CODE 'KI002400'",":OUTP:STAT ON"
VoltsCal:
DATA ":SOUR:VOLT:RANG ",":SOUR:VOLT"
DATA ":CAL:PROT:SOUR ",":CAL:PROT:SENS ",":SOUR:VOLT 0.0"
DATA ":CAL:PROT:SOUR ",":CAL:PROT:SENS ",":SOUR:VOLT ",":CAL:PROT:SOUR"
DATA ":CAL:PROT:SENS ",":SOUR:VOLT 0.0",":CAL:PROT:SOUR"
CurrentInit:
DATA ":SOUR:FUNC CURR",":SENS:VOLT:PROT 20",":SENS:VOLT:RANG 20"
DATA ":OUTP:STAT ON"
CurrentCal:
DATA ":SOUR:CURR:RANG ",":SOUR:CURR ",":CAL:PROT:SOUR"
DATA ":CAL:PROT:SENS ",":SOUR:CURR 0.0",":CAL:PROT:SOUR ",":CAL:PROT:SENS"
DATA ":SOUR:CURR ",":CAL:PROT:SOUR ",":CAL:PROT:SENS"
DATA ":SOUR:CURR 0.0",":CAL:PROT:SOUR"
```

Requesting calibration constants

Program C-2 listed below demonstrates how to request the calibration constants from the Model 2400. The program requests and displays the calibration constants for all ranges of both the volts and current measurement functions.

Program C-2. Requesting calibration constants

```
' Example program to request calibration constants.
' Model 2400 primary address = 24
OPEN "IEEE" FOR OUTPUT AS #1            ' Open IEEE-488 output path.
OPEN "IEEE" FOR INPUT AS #2             ' Open IEEE-488 input path.
PRINT #1, "INTERM CRLF"                 ' Set input terminator.
PRINT #1, "OUTTERM LF"                  ' Set output terminator.
PRINT #1, "REMOTE 24"                   ' Put 2400 in remote.
PRINT #1, "OUTPUT 24;*RST"              ' Restore defaults.
CLS
PRINT #1, "OUTPUT 24;:SENS:FUNC:CONC OFF"
PRINT #1, "OUTPUT 24;:SENS:FUNC 'VOLT:DC'"
PRINT #1, "OUTPUT 24;:SOUR:FUNC VOLT"
PRINT #1, "OUTPUT 24;:CAL:PROT:CODE 'KI002400'"   ' Unlock calibration.
Range = .2                              ' Initial range = 200mV.
PRINT "Model 2400 Voltage Calibration Constants:": PRINT
DO                                      ' Loop for all volts ranges.
        PRINT #1, "OUTPUT 24;:SOUR:VOLT:RANGE "; Range
        PRINT #1, "OUTPUT 24;:CAL:PROT:SENS:DATA?"
        PRINT #1, "ENTER 24"
        LINE INPUT #2, Data$
        PRINT Data$
        PRINT #1, "OUTPUT 24;:CAL:PROT:SOUR:DATA?"
        PRINT #1, "ENTER 24"
        LINE INPUT #2, Data$
        PRINT Data$
        Range = Range * 10
LOOP WHILE Range! <= 200
PRINT #1, "OUTPUT 24;:CAL:PROT:LOCK"
PRINT #1, "OUTPUT 24;:SENS:FUNC 'CURR:DC'"
PRINT #1, "OUTPUT 24;:SOUR:FUNC CURR"
PRINT #1, "OUTPUT 24;:CAL:PROT:CODE 'KI002400'"
Range = .000001                         ' Initial range = 1µA.
PRINT : PRINT "Model 2400 Current Calibration Constants:": PRINT
DO                                      ' Loop for all current ranges.
        PRINT #1, "OUTPUT 24;:SOUR:CURR:RANGE "; Range
        PRINT #1, "OUTPUT 24;:CAL:PROT:SENS:DATA?"
        PRINT #1, "ENTER 24"
        LINE INPUT #2, Data$
```

```
        PRINT Data$
        PRINT #1, "OUTPUT 24;:CAL:PROT:SOUR:DATA?"
        PRINT #1, "ENTER 24"
        LINE INPUT #2, Data$
        PRINT Data$
        Range = Range * 10
LOOP WHILE Range <= 1
PRINT #1, "OUTPUT 24;:CAL:PROT:LOCK"     ' Lock out calibration.
PRINT #1, "OUTPUT 24;*RST"
PRINT #1, "LOCAL 24"
CLOSE
END
```

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Service Form

Model No. _____ **Serial No.** _____ **Date** _____

Name and Telephone No. _____

Company _____

List all control settings, describe problem and check boxes that apply to problem. _____

_____

_____

❑ Intermittent ❑ Analog output follows display ❑ Particular range or function bad; specify

_____

❑ IEEE failure ❑ Obvious problem on power-up ❑ Batteries and fuses are OK

❑ Front panel operational ❑ All ranges or functions are bad ❑ Checked all cables

Display or output (check one)

❑ Drifts ❑ Unable to zero ❑ Unstable

❑ Overload ❑ Will not read applied input

❑ Calibration only ❑ Certificate of calibration required ❑ Data required

(attach any additional sheets as necessary)

Show a block diagram of your measurement including all instruments connected (whether power is turned on or not). Also, describe signal source.

Where is the measurement being performed? (factory, controlled laboratory, out-of-doors, etc.)_____

_____

What power line voltage is used?_____ Ambient temperature? _____ °F

Relative humidity? _____ Other? _____

Any additional information. (If special modifications have been made by the user, please describe.)

_____

_____

Be sure to include your name and phone number on this service form.

1. What other Keithley products do you currently use?

2. What effects, devices or phenomena do you measure with this instrument?

3. What was the main reason a *Keithley* unit was purchased?

4. Do you have any design suggestions concerning this unit?

PLEASE REFOLD SO YOUR NAME IS INSIDE, TAPE AND MAIL.

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